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DEVELOPMENT OF A NEW OPERATIONAL URBAN LAGRANGIAN DISPERSION MODEL FOR EMERGENCY RESPONSE

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1.Introduction



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1.1 Context

Type of context

- Release of CBRN agents in the atmosphere
- Industrial accidents, malicious or terrorist activities
- Help public authorities and industrialists



Figure: Exemple of release in case of an accident



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1.1 Context

Type of context

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Figure: Exemple of release in case of an accident

The answer

- Need software tools gathering the following features
 - 🗕 Easy use
 - Fast answer
 - 🗕 Reliable estimate
 - Realistic simulation



Figure: SIRANERISK, air.ec-lyon.fr/SIRANERISK/



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1.2 State of the art

Gaussian model



[+] Very fast answer
 [-]Doesn't take obstacles info account

 $\label{eq:Figure:Illustrative simulation exercise with ARIA IMPACT, \\ http://www.aria.fr/aria_impact.php$



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1.2 State of the art

Gaussian model



Figure: Illustrative simulation exercise with ARIA IMPACT, http://www.aria.fr/aria_impact.php







Figure: Time averaged 3D streamlines for tall buildings by LES. (Nozu et al., 2012)

- [+]Very reliable estimate
- [-]Very long computational time



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1.2 State of the art

Gaussian model



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- [+]Very reliable estimate
- [-]Very long computational time

Figure: Time averaged 3D streamlines for tall buildings by LES. (Nozu et al., 2012)

Street network model

Figure:

SIRANERISK, air.ec-lyon.fr/Introduction/SIRANERISK/

- [+]Operational model
 [+]Used by public authorities
 - [-]Show some limitations

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1.2 State of the art

The limitation of existing approaches lead to the development of a new operational modelling software: BUILD



In this presentation, we will present:

- The main features of the BUILD model
- The first results of the validation work

2.BUILD model overview



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2.1 Presentation of BUILD





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2.2.1 Street network model

How is a street network model built ?

- Simplified description of the geometry
- Streets = segments, intersections = nodes
- Streets represented by a boxes







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2.2.1 Street network model

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Real geometry Street volumes





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2.2.2 Lagrangian stochastic model

- This approach allows to improve some limitations of the SIRANERISK approach
- Based on the Lagrangian tracking of individual particles trajectories
- The temporal evolution of the Lagrangian position of each particle is described by:

$$dX_i = \left(ar{u}_i + U_i'
ight)dt$$

Langevin stochastic equation

$$dU'_{i} = a_{i}dt + b_{ij}d\xi_{j} \quad \text{with} \quad \begin{cases} a_{i} = -\frac{U'_{i}}{T_{Li}} + \frac{1}{2}\frac{\partial\sigma_{ui}^{2}}{\partialx_{i}} + \frac{U'_{i}}{2\sigma_{ui}^{2}}\left(U_{j}\frac{\partial\sigma_{ui}^{2}}{\partialx_{j}}\right) \\ b_{ij} = \delta_{ij}\sqrt{C_{0}\varepsilon} \\ T_{Li} = \frac{2\sigma_{ui}^{2}}{C_{0}\varepsilon} \end{cases}$$

 $\mathsf{Where}:$

 $d\xi_j$ is Wiener incremental process whose mean is zero and variance is dt a_i is the deterministic acceleration term (Thomson,1987) b_{ii} is the stochastic diffusion term (Pope,1987)

 T_{Li} is the Lagrangian time scale (Tennekes, 1982)



Determination of recirculation zone lenght

Two equations from advection-diffusion equation :

$$\frac{\Delta U}{U_0}|_{critical} = erf\left(\frac{W/H}{2\sqrt{2}0.253x_r/H}
ight)erf\left(\frac{1}{\sqrt{2}0.173x_r/H}
ight)$$

$$x_r/H = 0.15 + \frac{7-0.15}{2} \left(1 + erf \left[\ln(W/H) - 0.6\right]\right)$$



Figure: Characteristic dimension and recirculation zone length



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2.2.3 Flow around isolated obstacle



Figure: In white : boundary of the theoretical speed deficit. In grey : speed recirculation zone obtain with the algorithm based on an image processing approach

Figure: Recirculation zone of buildings for a real neighbourhood



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2.2.4 Wind velocity within the streets

Longitudinal component

Longitudinal velocity in each street is modelled analytically

Balance between :

- Entrainment by the external flow
- The friction on the street walls

Longitudinal component equation



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2.2.4 Wind velocity within the streets

Cross-sectional components

- The street cross-sectional components of the velocity are modelled
- Assuming a separation of variables:

 $\bar{v}(y,z) = V_{street}f(\eta)g(\varsigma) \qquad \bar{w}(y,z) = W_{street}g(\eta)f(\varsigma)$

with η and ς are dimensionless coordinates : $\eta = y/W$ and $\varsigma = z/H - 1/2$

The linear model is defined by:

$$f(x) = 1 - 4x^2$$

 $g(x) = 2x$



Figure: Example of a cross-sectional velocity field



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2.2.5 Wind velocity in the intersections

Air flow field

- The air flow in each street i is given by: $P_{street,i} = \xi HWU_{street,i}$
- The vertical air flow is deduced applying the continuity equation $\Rightarrow P_{vert} = \sum_{i \in intersection} P_{street,i}$
- Assuming that the upwind streets flows behave in such a way they are bidimensional ⇒ So they are not crossing each other



Figure: Air flow horizontal movement in an intersection, (Soulhac, 2009)

Velocity distribution

To compute the velocity distribution we use a potential model: Panel method





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2.2.6 Wind velocity above the roof level

- Modelled using the Monin-Obukhov similarity theory (described by Soulhac,2011)
- Coupling these different models we obtain the following profil



Figure: Vertical profile of the horizontal transverse component of the velocity inside and above a square street-canyon. Comparison between the analytical model and a wind tunnel experiment (Soulhac,2000)

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2.3 Validation process

Complete and progressive approach

- Our approach covers a wide range of validation configurations
 - From isolated built to neighborhood
 - From wind tunnel tests to real dimension
 - From idealized configurations to real configuration
 - First with extended releases then releases in the form of puff
- Intercomparisons between CFD models, experimental measurements and BUILD model

Some examples



Figure: Example of isolated obstacle from Hervé GAMEL Thesis in wind tunnel



Figure: Example of idealized neighborhood in wind tunnel from (Garbero et al.,2010)



Figure: Example of idealized neighborhood from MOCK URBAN SETTING TEST in real situation

3.Preliminary results

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3.1 Test configuration

Test configuration	Geometry and mesh on BUILD
 Idealized neighborhood Identical block Width = 250mm, Lenght = 250mm, Height = 50mm Spaced between buildings S = 50mm Several wind directions Source at H/2 in an intersection 	Geometry and mesh on BUILD
Figure: Geometrical layout of the obstacle array, W = L =	BUILD

Figure: Mesh of the study case

5H et S = Sx = Sy = H



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3.2 Exemples of results

Result

- Preliminary result of the dispersion
- Wind direction = 30°
- CPU time on a laptop = 30s
- The behaviour of the plume is qualitatively realistic



Figure: Tracer behaviour in an idealized neighborhood with BUILD (Wind direction : 30° , source : H/2)

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3.3 Comparisons



Figure: Numerical simulation with the BUILD model

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Figure: Wind tunnel measurements from (Garbero et al.,2010). Concentration field in a network of streets for a wind direction $=27.5^\circ$

Comparisons results

- Provide very encouraging results
- CPU time on a laptop = 30s

4.Conclusion and perspectives

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Conclusion

Summary

- Presentation of the BUILD model with its main features
- The first version has been developed
- Some preliminary results have been given

Perspectives

- To continue the validation process
 - To improve the BUILD model with more physical parametrization