



# **VALIDATION OF GAUSSIAN MODELS USING WIND TUNNEL EXPERIMENTS AND NUMERICAL SIMULATION**

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Espírito Santo**



# Introduction

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## Atmospheric dispersion of odorous compounds





# Odour Dispersion Modelling

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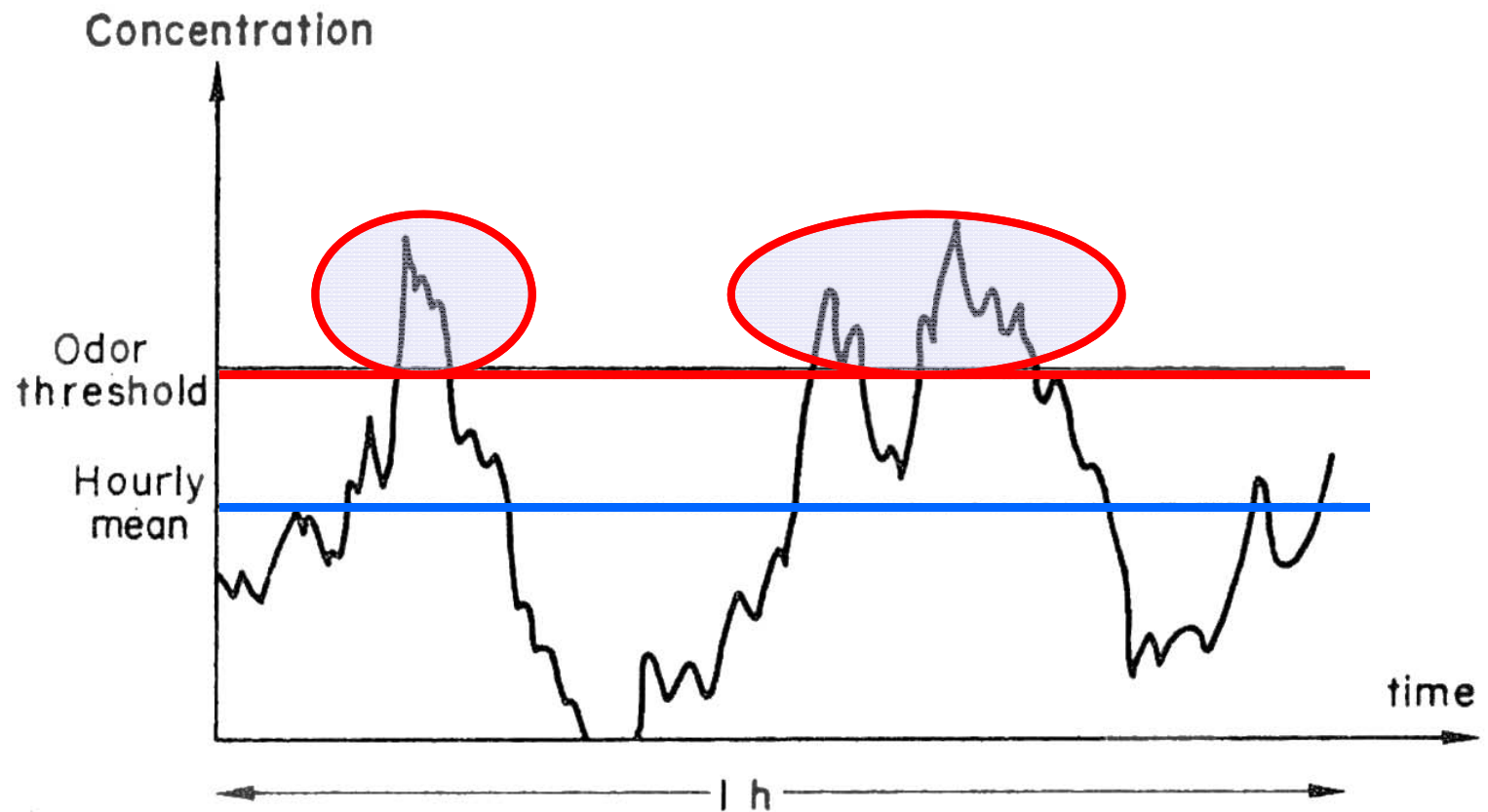
## Important aspects:

- Low average concentration levels (below detection threshold)
- Impact due to short concentration peaks (few seconds)
- Averaging time
- Peak-to-Mean ratio (P/M)
- Intermittency

**Pollutant dispersion studies usually employ long averaging times (1 hour and up)**



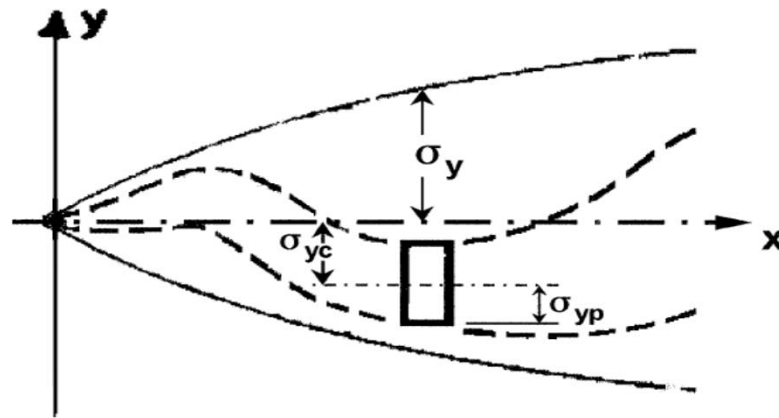
# Odour Dispersion Modelling





# The Fluctuating Gaussian Plume Model

- Plume spreading is the result of meandering and dispersion and both processes are described through Gaussian distributions (Gifford, 1959)



(Mussio *et. al*, 2001)

$$\sigma_y^2 = \sigma_{yp}^2 + \sigma_{yc}^2$$

$$\sigma_z^2 = \sigma_{zp}^2 + \sigma_{zc}^2$$



# The Fluctuating Gaussian Plume Model

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$$\sigma_y^2 = \sigma_{yp}^2 + \sigma_{yc}^2$$

$$\sigma_z^2 = \sigma_{zp}^2 + \sigma_{zc}^2$$

- $\sigma_y$  and  $\sigma_z$  are the usual gaussian dispersion parameters, called **long term parameters**;
- $\sigma_{yp}$  and  $\sigma_{zp}$  are the plume segment dispersion parameters, calculated by Högstrom (1972) expressions;
- $\sigma_{yc}$  and  $\sigma_{zc}$  are the standard deviation of each plume element centroid position and are obtained from the above equations;
- $\sigma_{yp}$ ,  $\sigma_{zp}$ ,  $\sigma_{yc}$ ,  $\sigma_{zc}$  are called the **short-term parameters**.



# The Fluctuating Gaussian Plume Model

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The FPM model can be an useful tool for odour dispersion modelling:

- Estimation of the Peak-to-mean concentration ratio;
- Intermittency factor;
- Frequency of occurrence of odour events;

$$P / M = \frac{C_p}{C_M}$$



# The Fluctuating Gaussian Plume Model

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- Frequency of occurrence of odour events;

Percentage of time during which the concentration stays above a defined threshold (Aubrun & Leitl, 2004)





# The Fluctuating Gaussian Plume Model

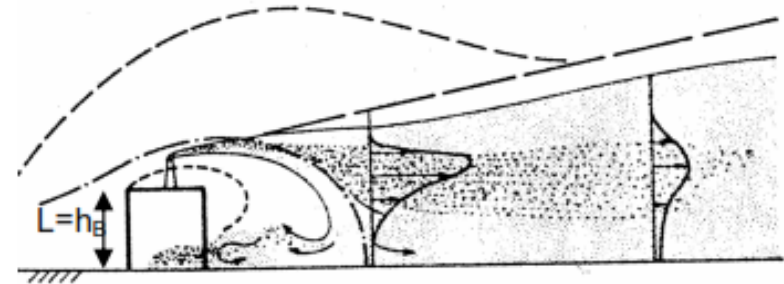
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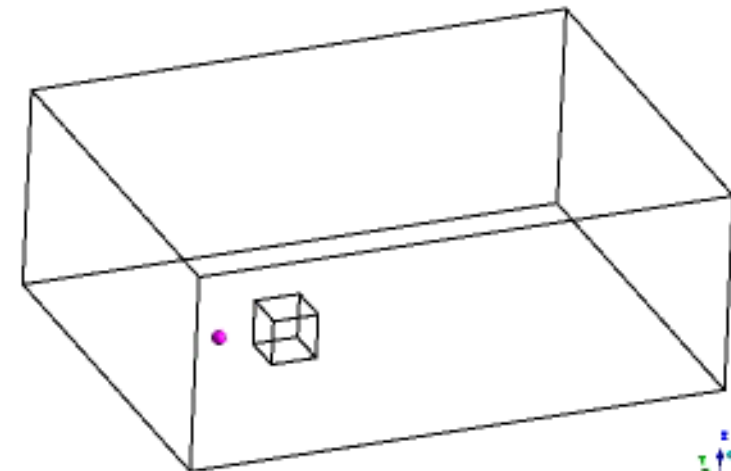
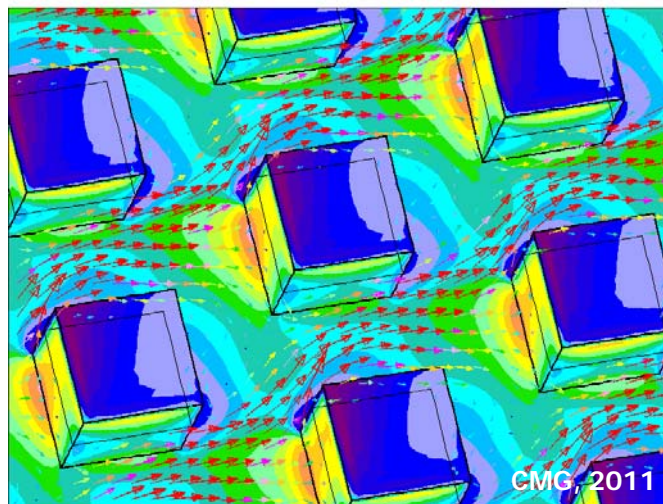
Probability of exceeding a defined odour intensity (Yu et al., 2011) or histogram of the distribution of odour events of different intensities at a recptor (Murray et al., 1978; De Melo Lisboa et al., 2006)

# Urban area dispersion



Meroney, 1982

AVSYS



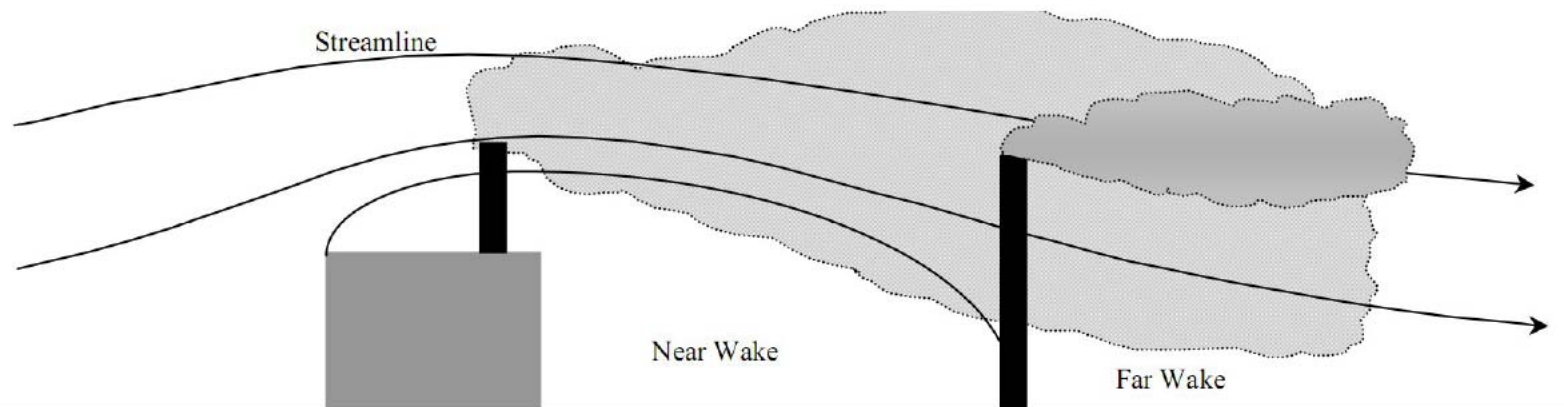
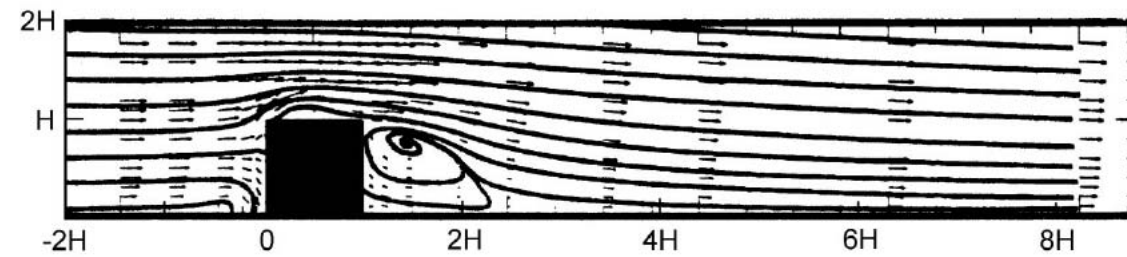
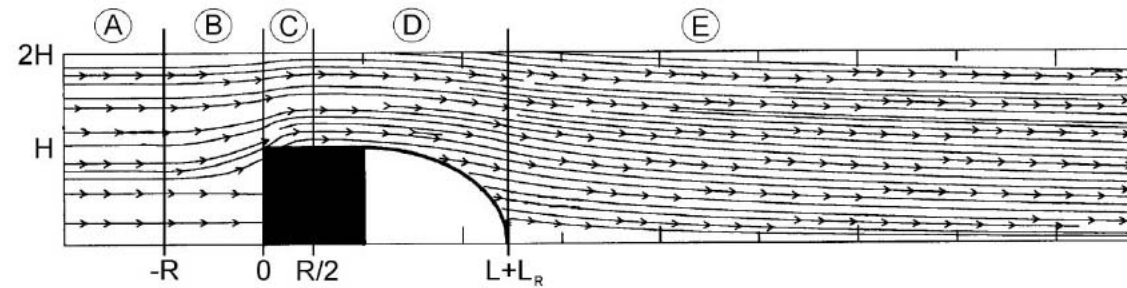


# The PRIME Model

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- The PRIME model (Plume Rise Model Enhancements), incorporates the effect of plume elevation and downwash due to buoyancy and the presence of obstacles (Schulman et al., 2000);
- Developed based on experimental observations of field and wind tunnel experiments;
- Currently used both in AERMOD and CALPUFF regulatory models (Cimorelli et al., 2004; Scire et al., 2000).

# The PRIME Model





# The FPM-PRIME Model

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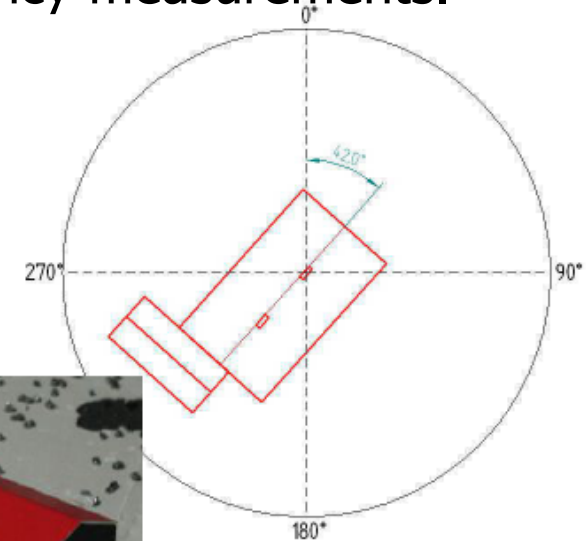
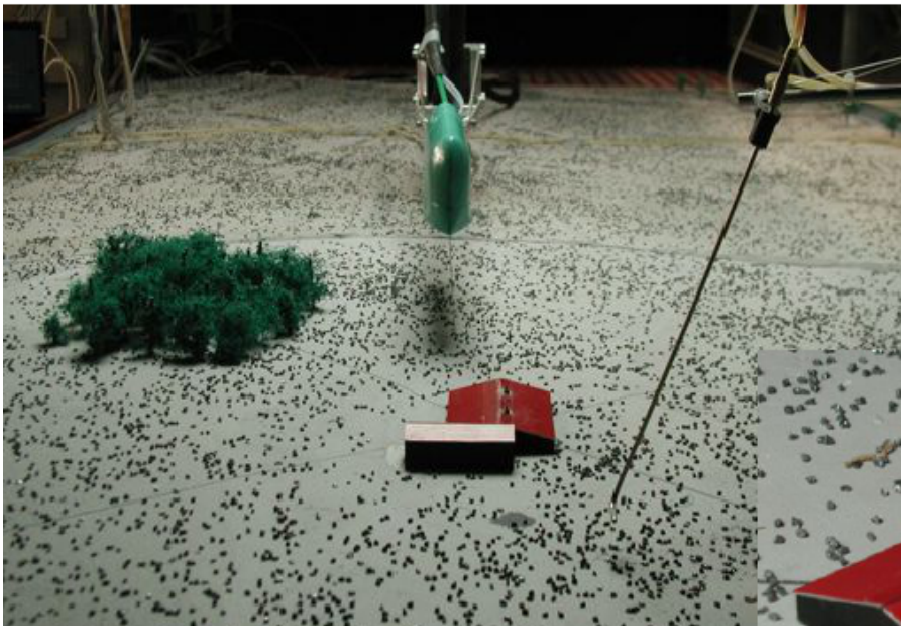
- Incorporates the concept of the fluctuating plume and the effect of streamlines deflection due to the presence of an obstacle in the plume trajectory;
- The growth rate of the long-term dispersion parameters is determined using the PRIME method and the short term parameters ( $\sigma_c$  and  $\sigma_p$ ) are calculated based on Gifford (1959) proposition and on Högstrom (1972) methods;



# Wind tunnel experiment

(Aubrun and Leitl, 2004)

- Wind tunnel experiments, 1:400 scale;
- Tracer gas emitted from a stack at the top of a pig barn model;
- Average concentration and intermittency measurements.



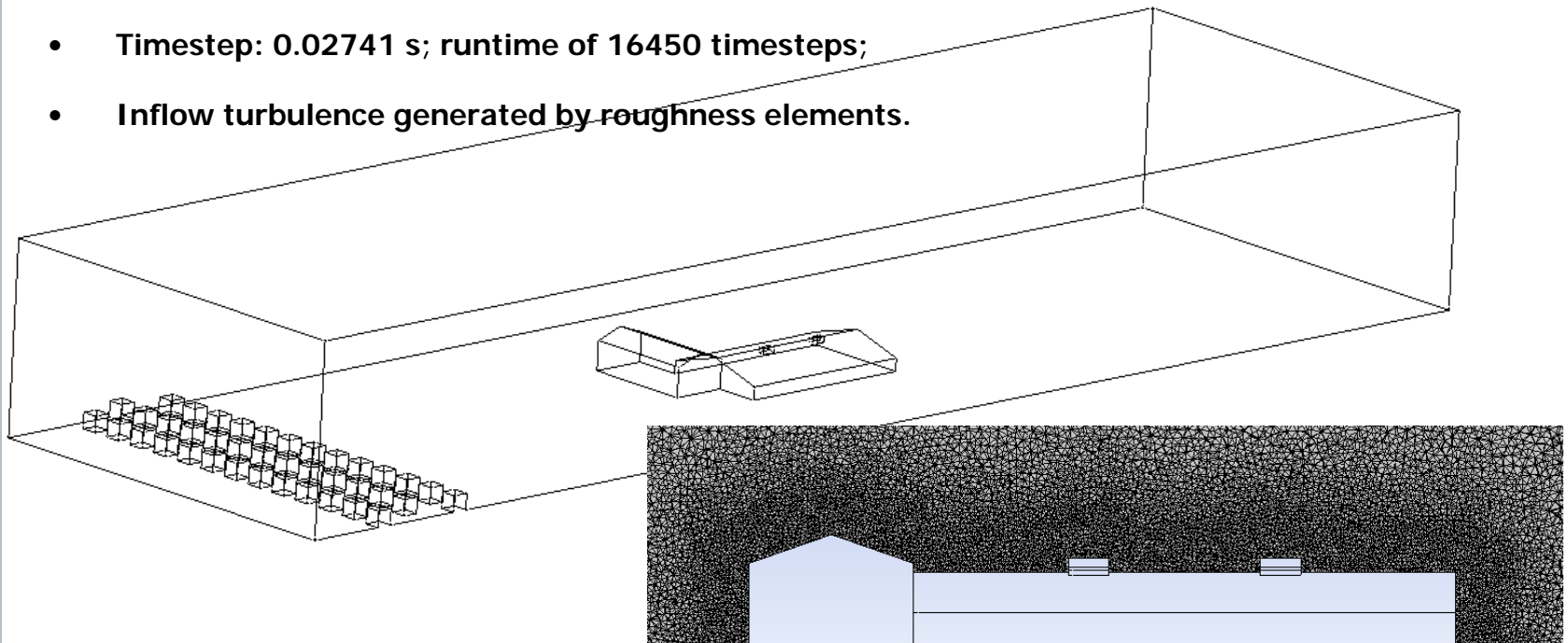
(CEDVAL, 2006)



# LES simulation

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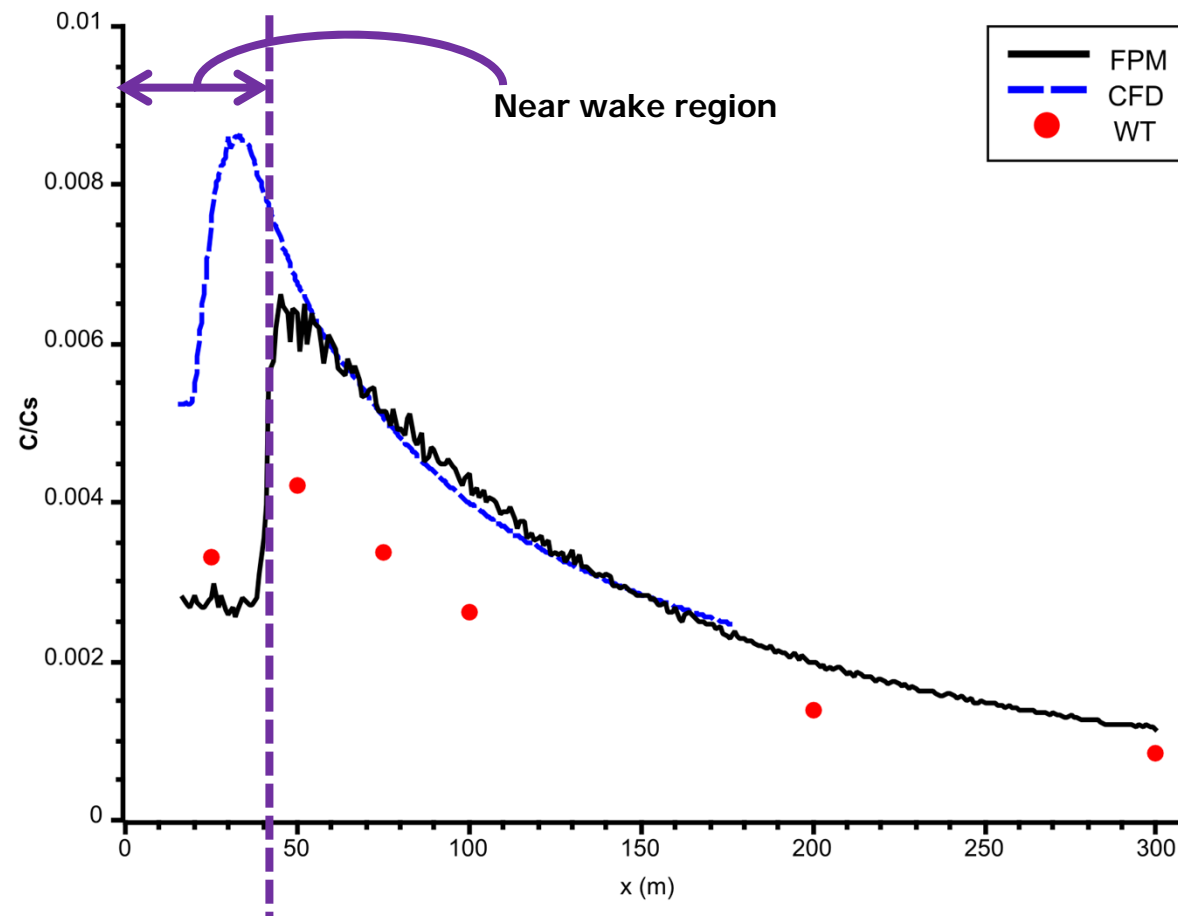
- **Model:** complex obstacle,  $H = 8.8$  m (height);
- **Domain:**  $45H$ ,  $13H$  and  $6H$ ;
- **Source** located upwind  $25H$  of domain entrance;
- **Non-structured tetrahedral mesh**, finer resolution about  $H/32$ ;
- $>5.23$  million nodes;
- **WALE** sub grid model;
- **Timestep:**  $0.02741$  s; runtime of 16450 timesteps;
- **Inflow turbulence** generated by roughness elements.





# Results

- Downwind average concentration for a receptor located 1.6 m above ground ( $y=0$ ).

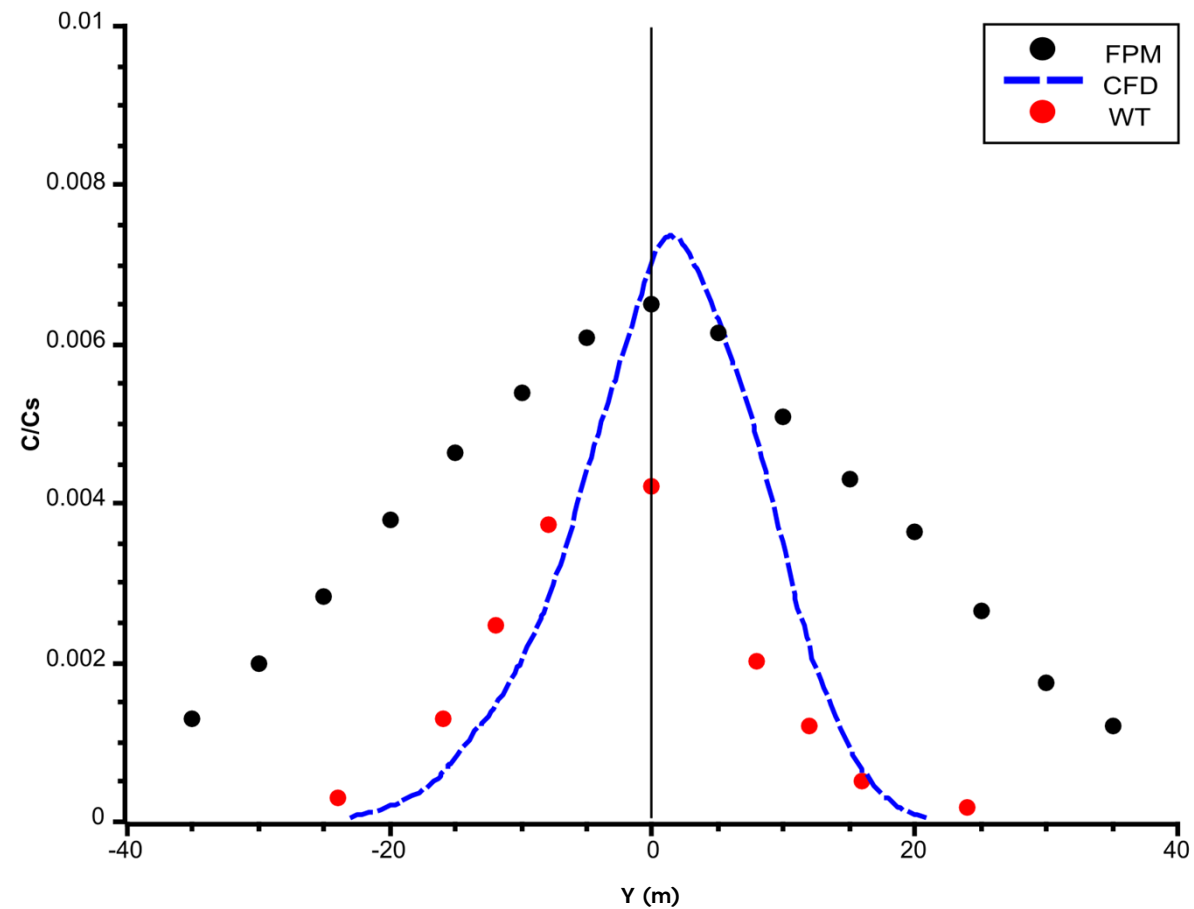






# Results

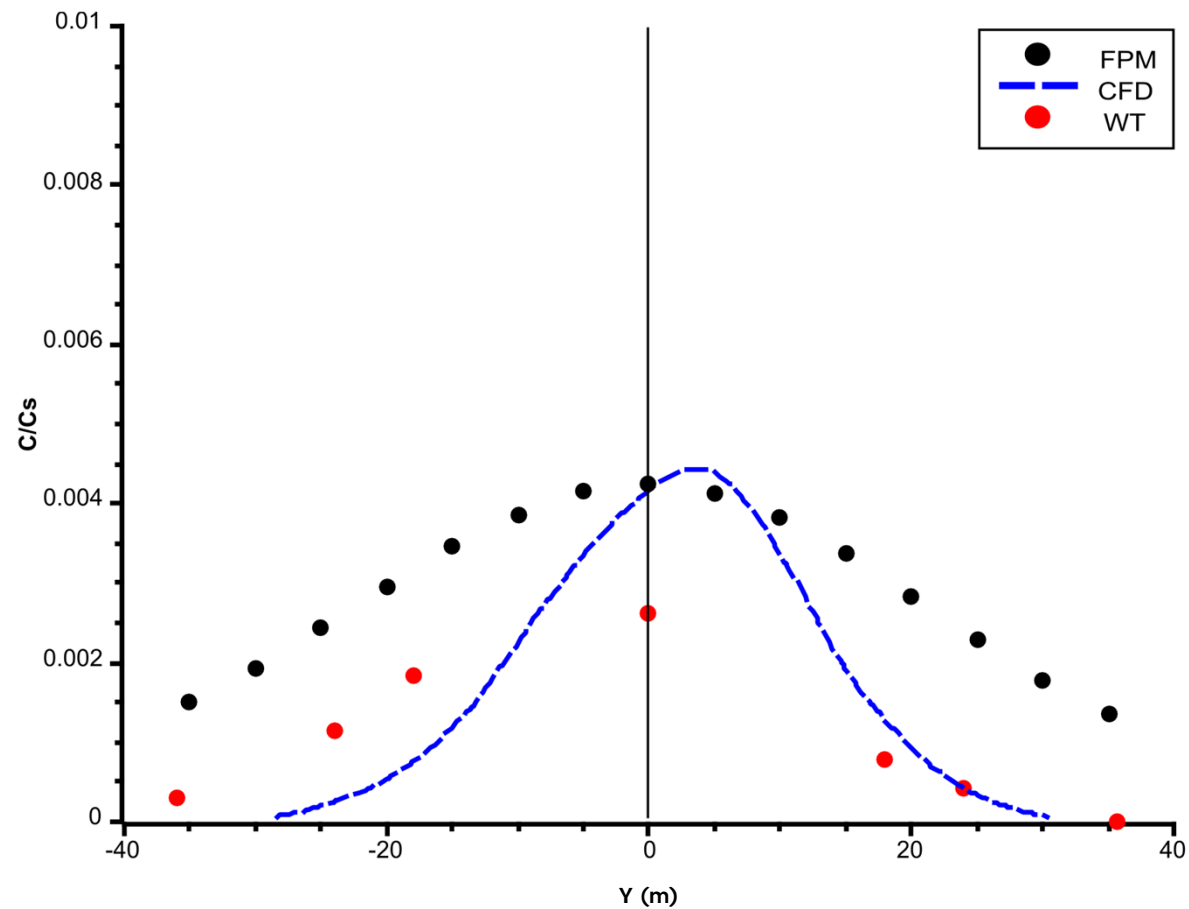
- Lateral average concentration for a receptor located 1.6 m above ground at  $x=50$  m from the source.





# Results

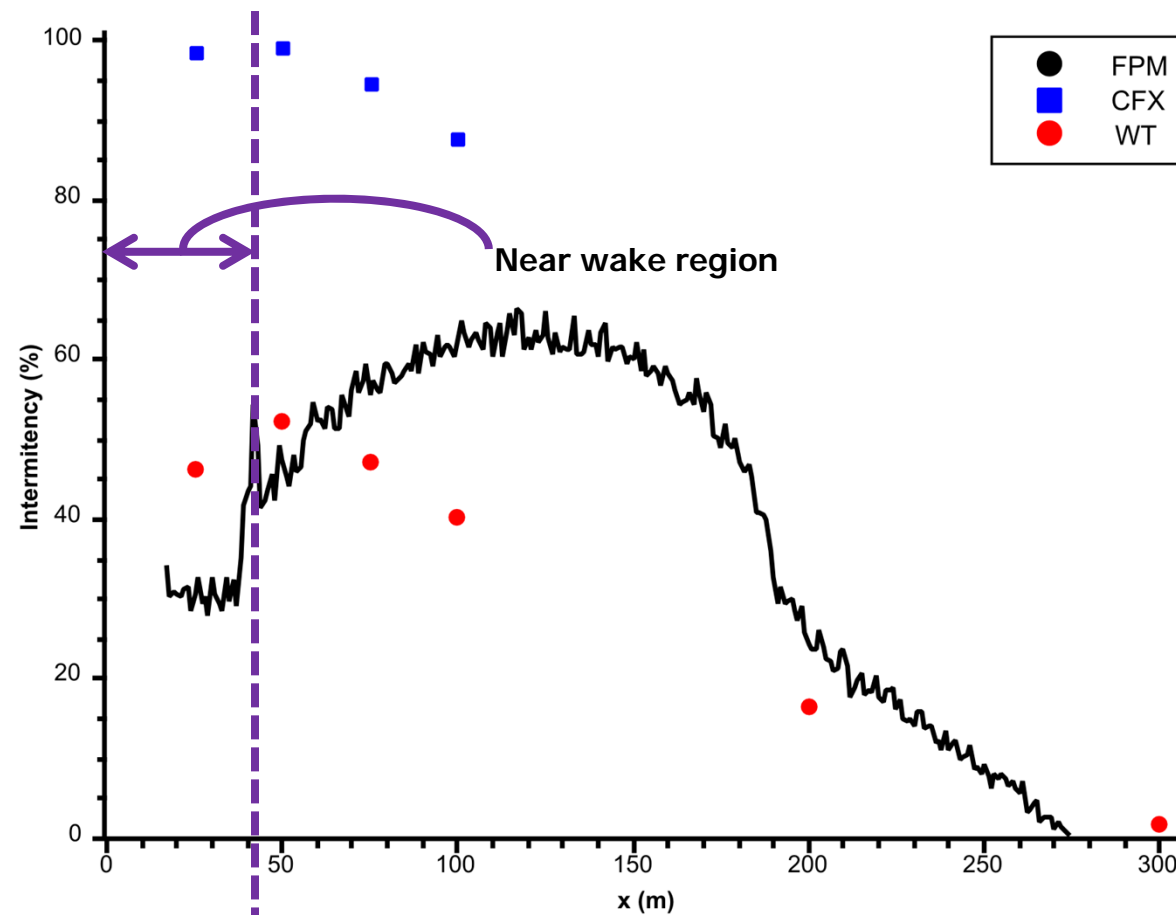
- Lateral average concentration for a receptor located 1.6 m above ground at  $x=100$  m from the source.





# Results

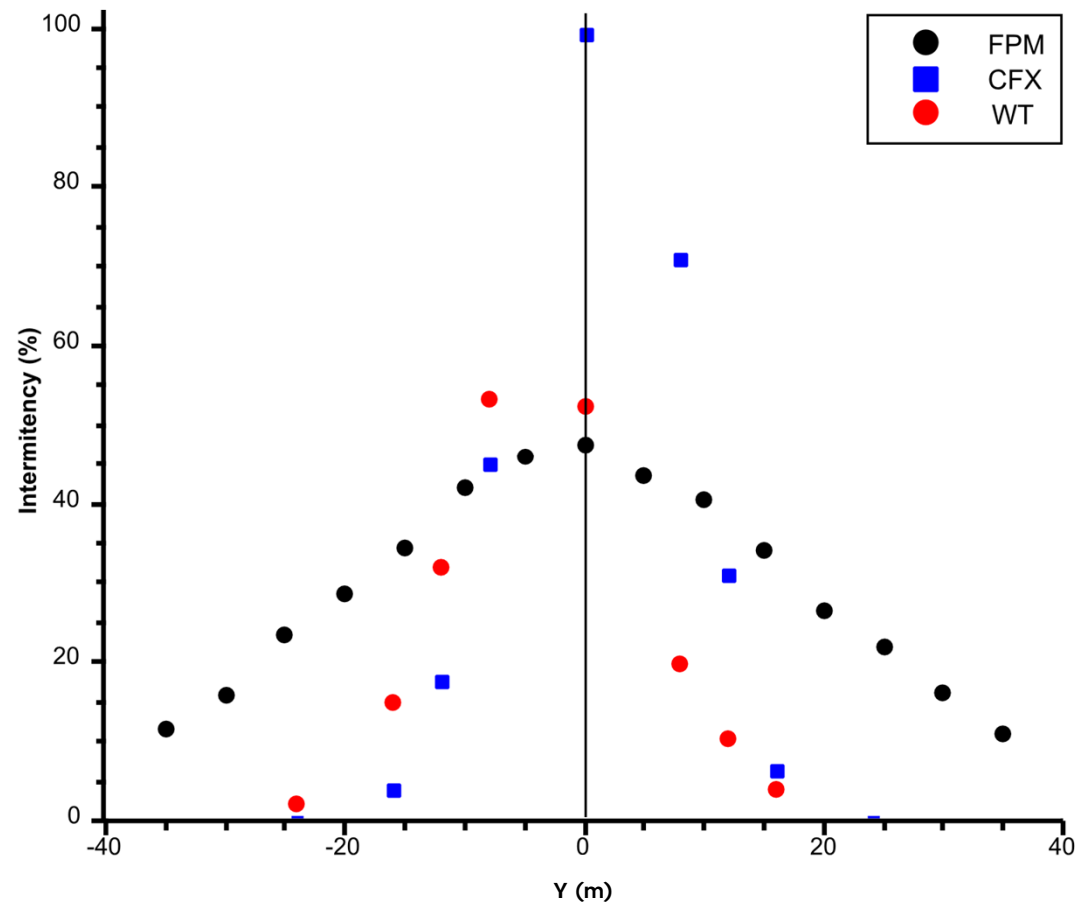
- Downwind intermittency for a receptor located 1.6 m above ground ( $C_{\text{thresh}} = 0.25\% C_s$ ).





# Results

- Lateral intermittency for a receptor located 1.6 m above ground at  $x=50$  m from the source ( $C_{\text{thresh}} = 0.25\% C_s$ ).





# Conclusion

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- Good agreement between FPM, LES and FPM for the downwind average concentration – results within an order of magnitude;
- FPM overpredicted lateral average concentration distribution; LES and WT with good agreement;
- Results suggest FPM is a viable tool for odour dispersion modelling in the presence of obstacles;



# Thank you for your attention

## Contact Information:

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