

# An Application of Backscatter Lidar to Model the Odour Nuisance Arising from Aircraft Tyre Smoke

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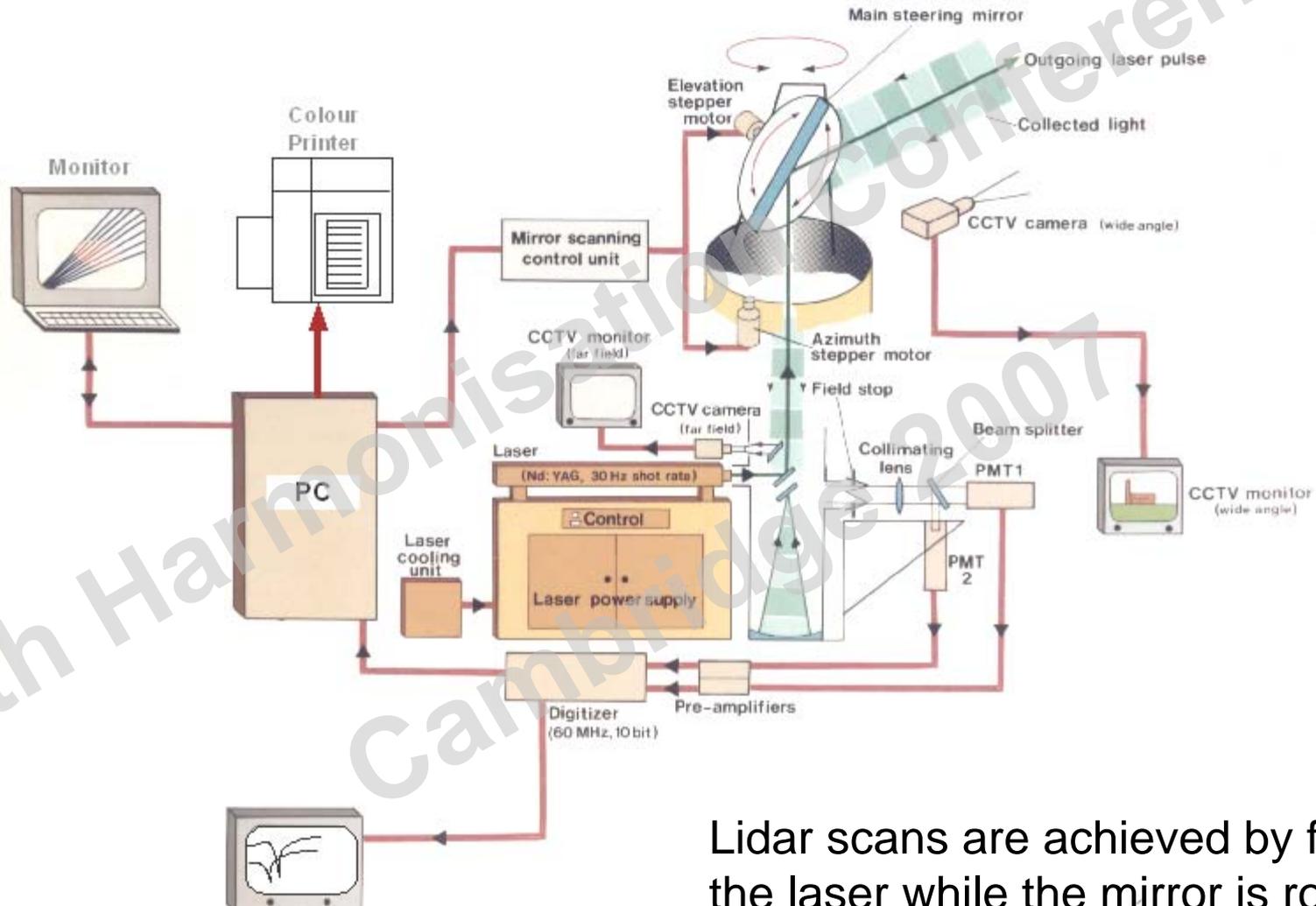
# The Rapid Scanning Lidar Facility *Manchester Metropolitan University*



*RASCAL in operation at Heathrow, May 2005*

- Self contained mobile unit
- Onboard power generation for autonomous operation
- Onboard met station with 10 m extendable mast
- Beam scanning in azimuth or elevation up to 60°
- Eye safe operation
- Track record of successful field study operations

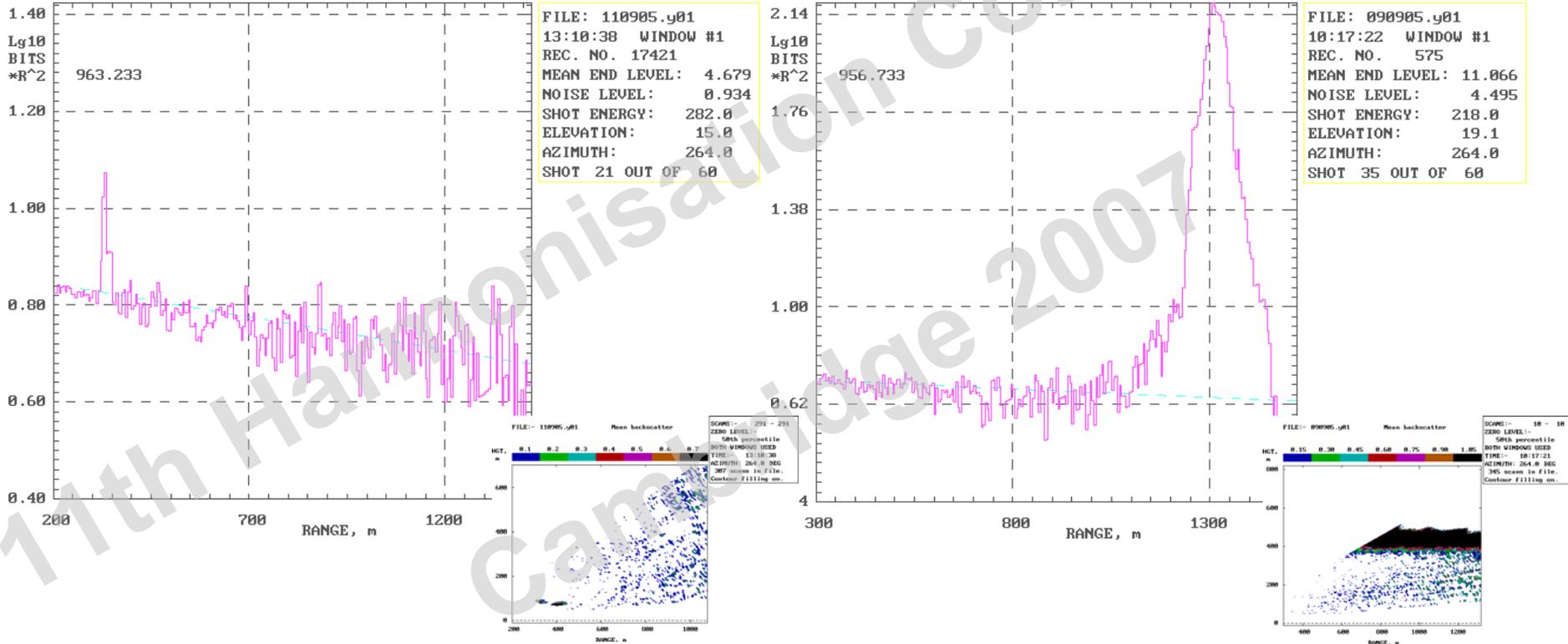
# Schematic of RASCAL Optics & Data Capture Systems



Lidar scans are achieved by firing the laser while the mirror is rotated

# Signal processing

- Background fit compensates for:
  - Geometric spread of beam with range
  - Optical extinction

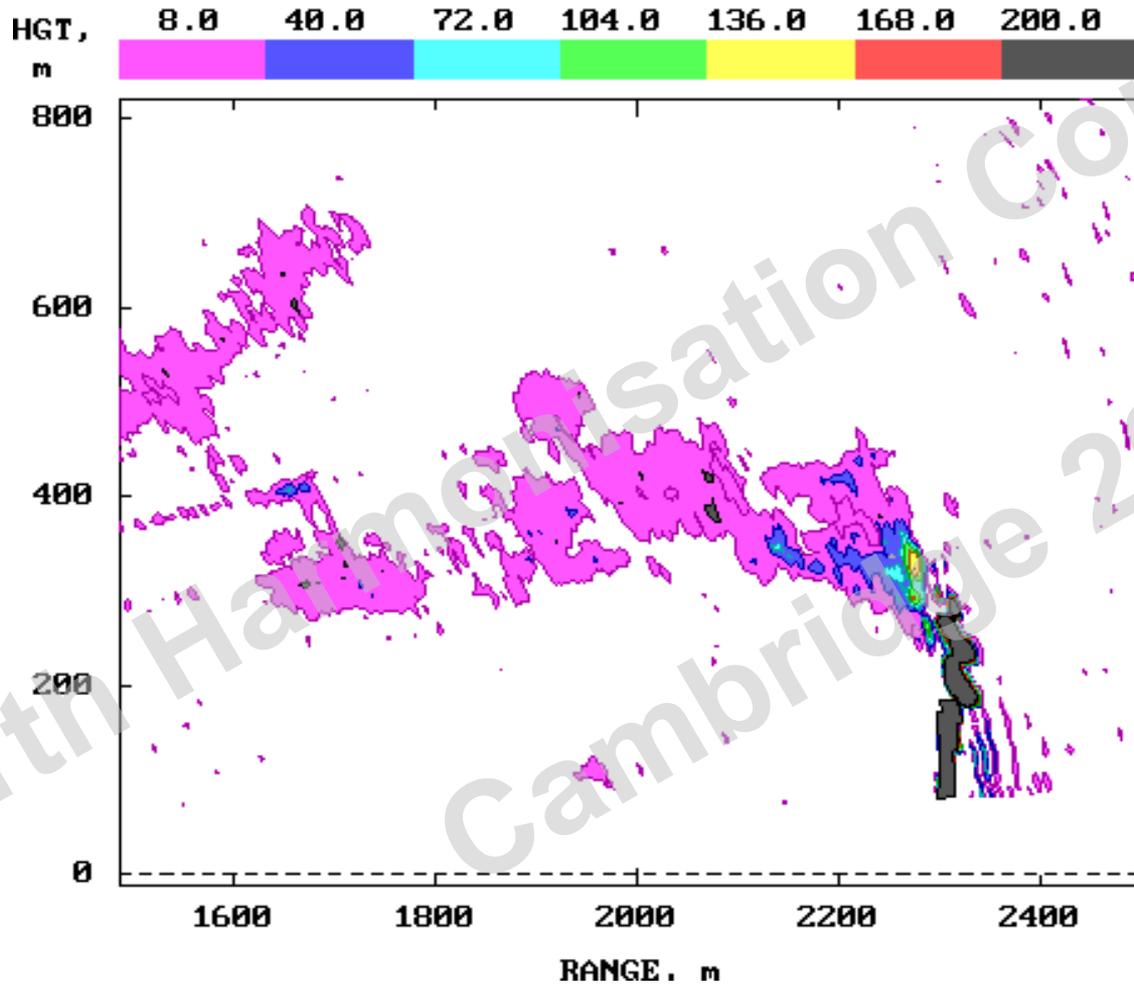


Left: return from an aircraft exhaust plume at 320 m  
Right: return from a distant cloud at range >1200 m

FILE:- 040589.y09

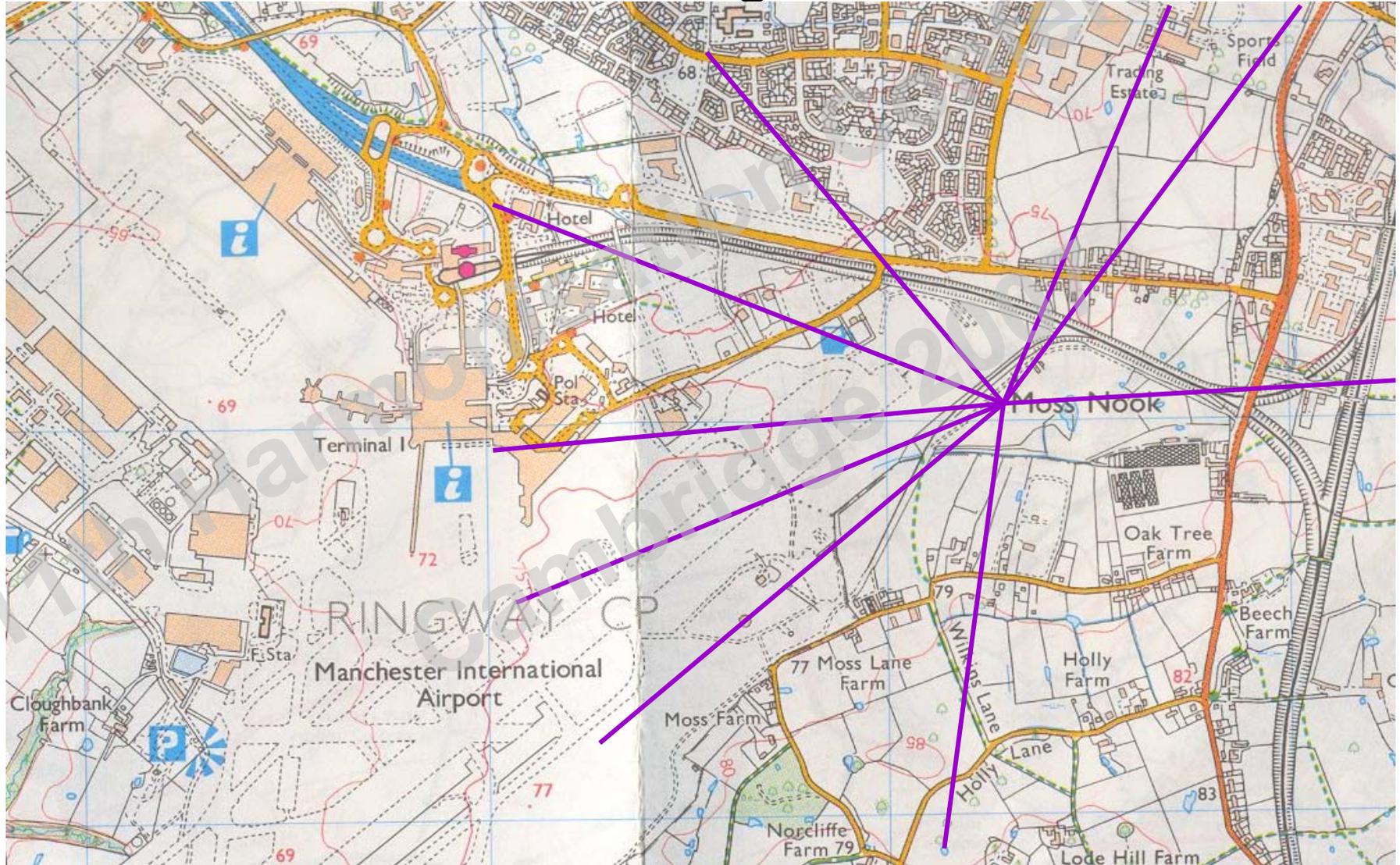
Mean backscatter

SCANS:- 6 - 6  
ZERO LEVEL:-  
50th percentile  
WINDOW #1 ONLY  
TIME:- 15:02:11  
AZIMUTH: 55.8 DEG  
6 scans in file.  
Contour filling on.

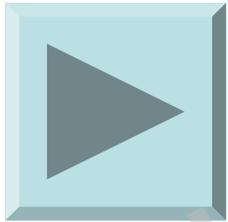


Plume from Didcot power station in convective conditions

# Plan of Manchester Airport with Overlay of Lidar Scanning Directions



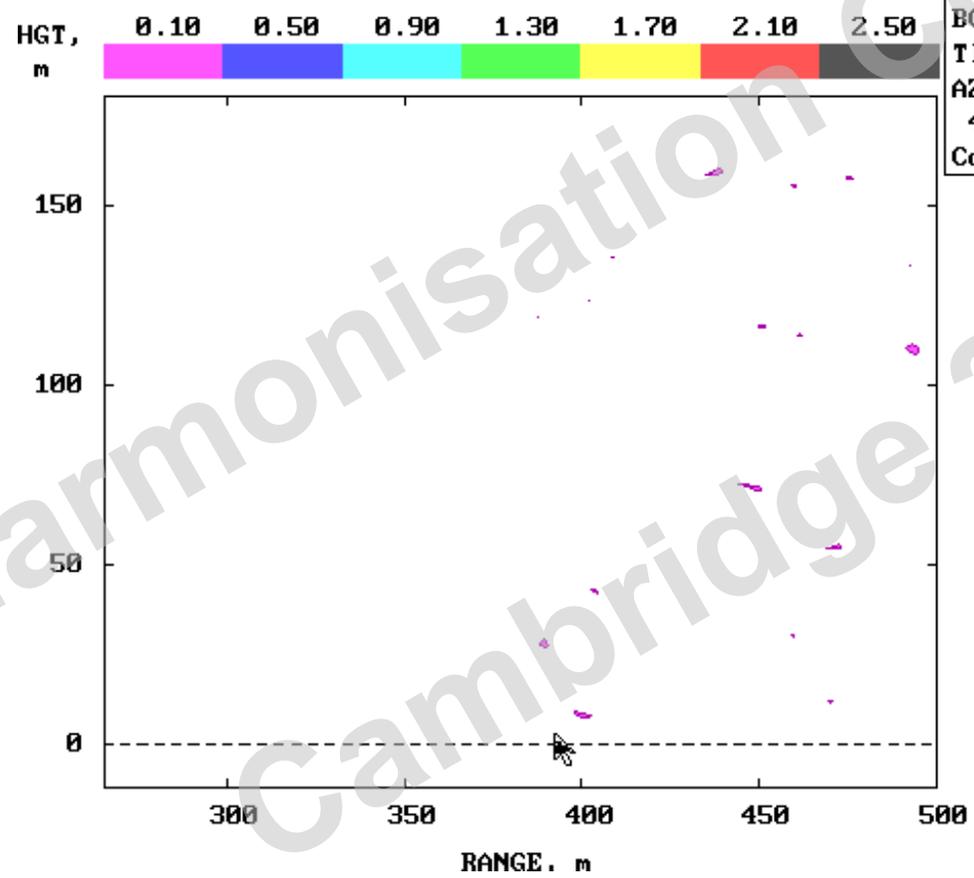
# Observations of Tyre Smoke on Landing



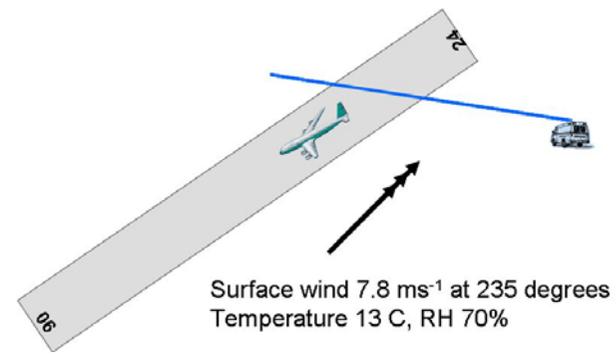
Manchester Airport, 30 March 2006

11th Harmonisation Conference  
Cambridge 2007

FILE:- 300306.y03 Mean backscatter

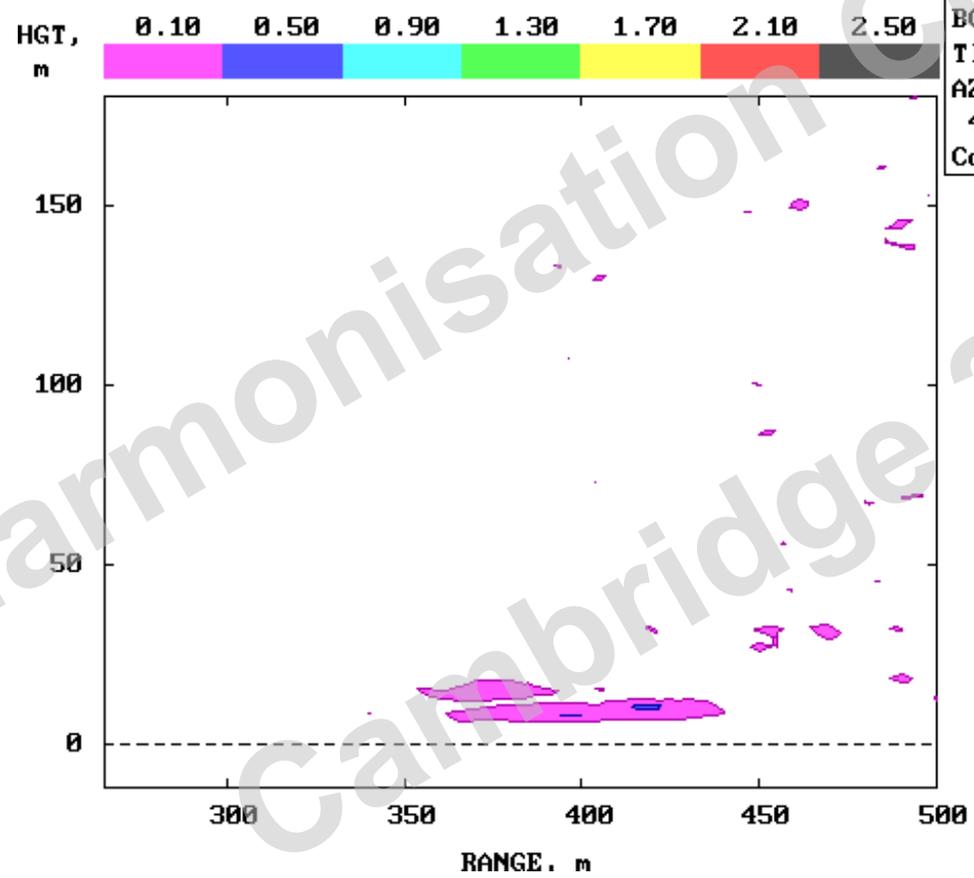


SCANS:- 114 - 114  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:32  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

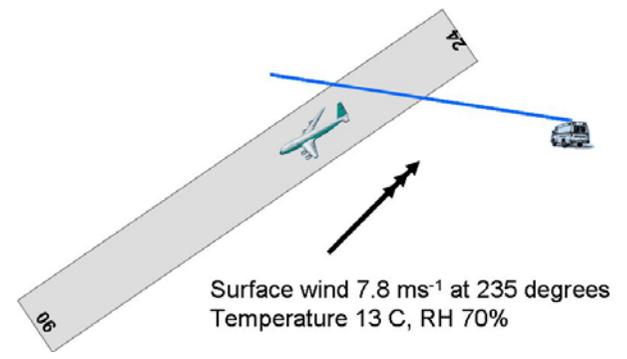


11th Harmonisation Conference

FILE:- 300306.y03 Mean backscatter

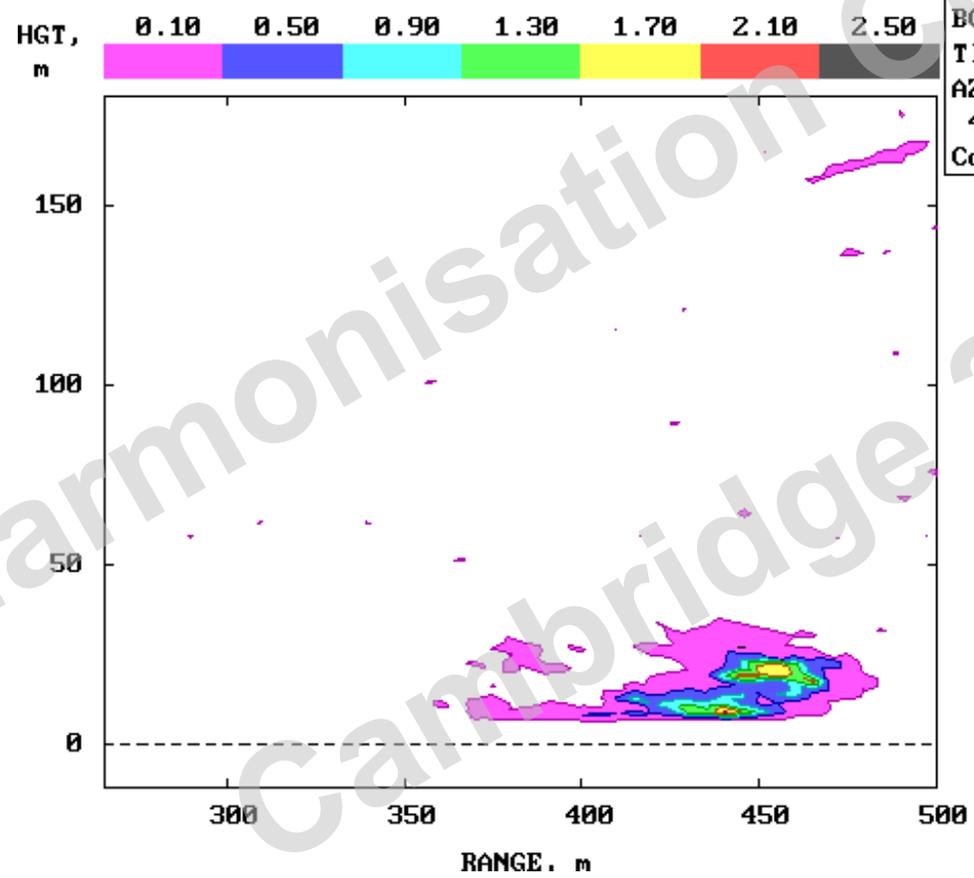


SCANS:- 115 - 115  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:36  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

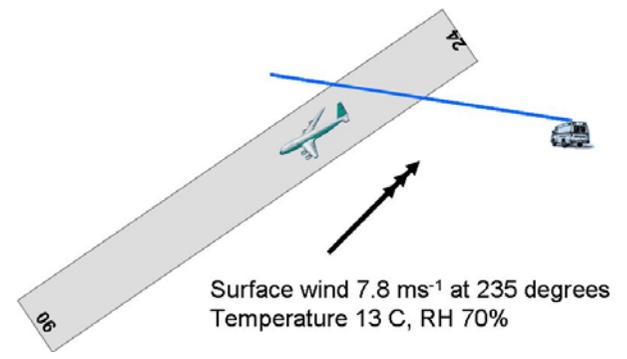


11th Harmonisation Conference

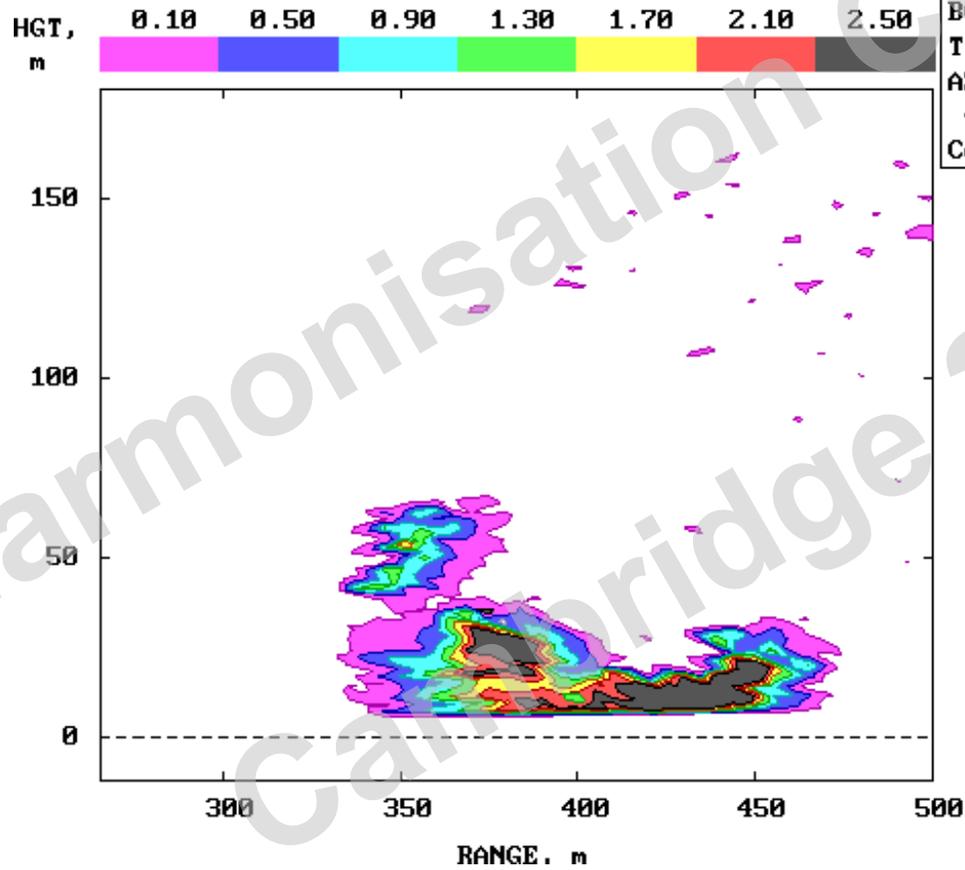
FILE:- 300306.y03      Mean backscatter



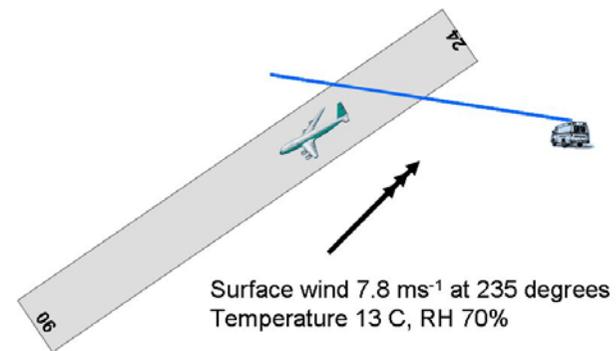
SCANS:- 116 - 116  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:40  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.



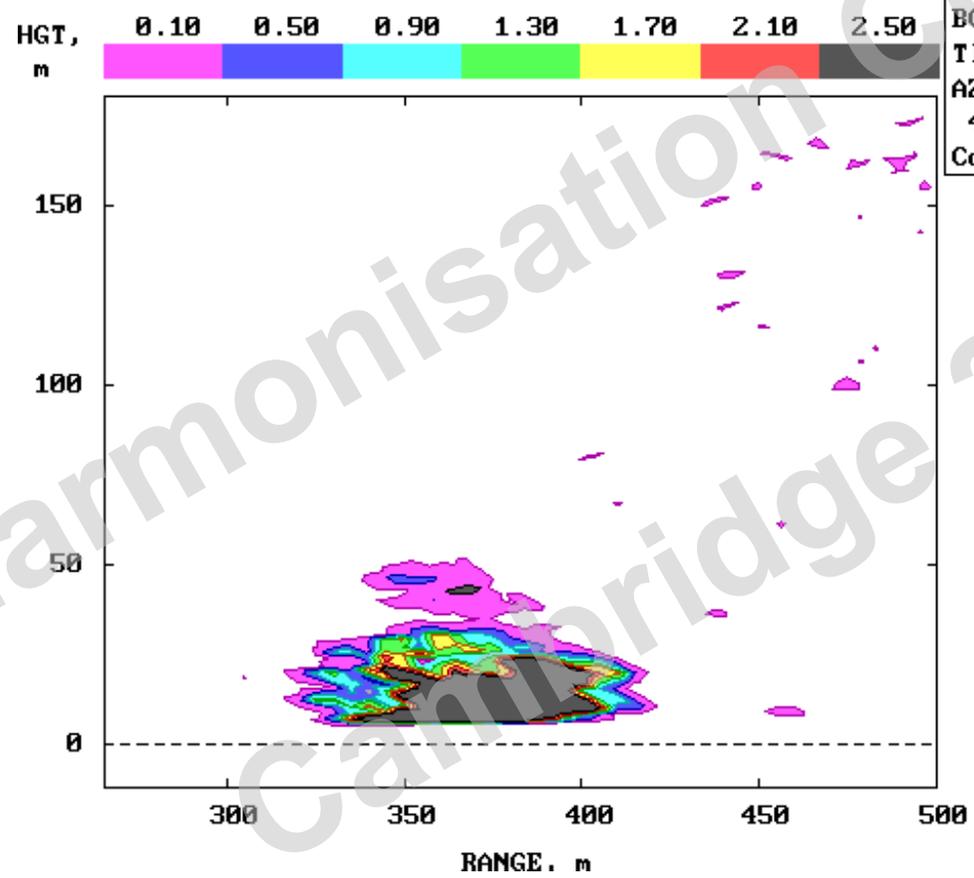
FILE:- 300306.y03 Mean backscatter



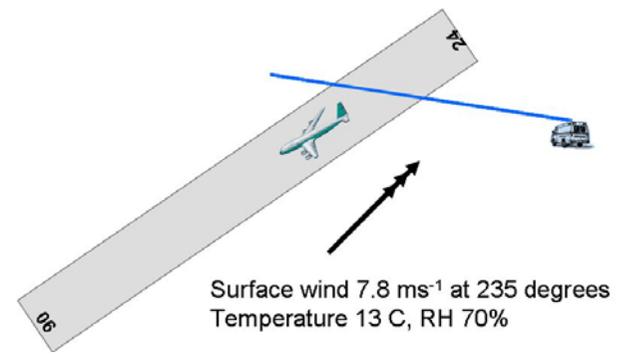
SCANS:- 117 - 117  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:44  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.



FILE:- 300306.y03      Mean backscatter

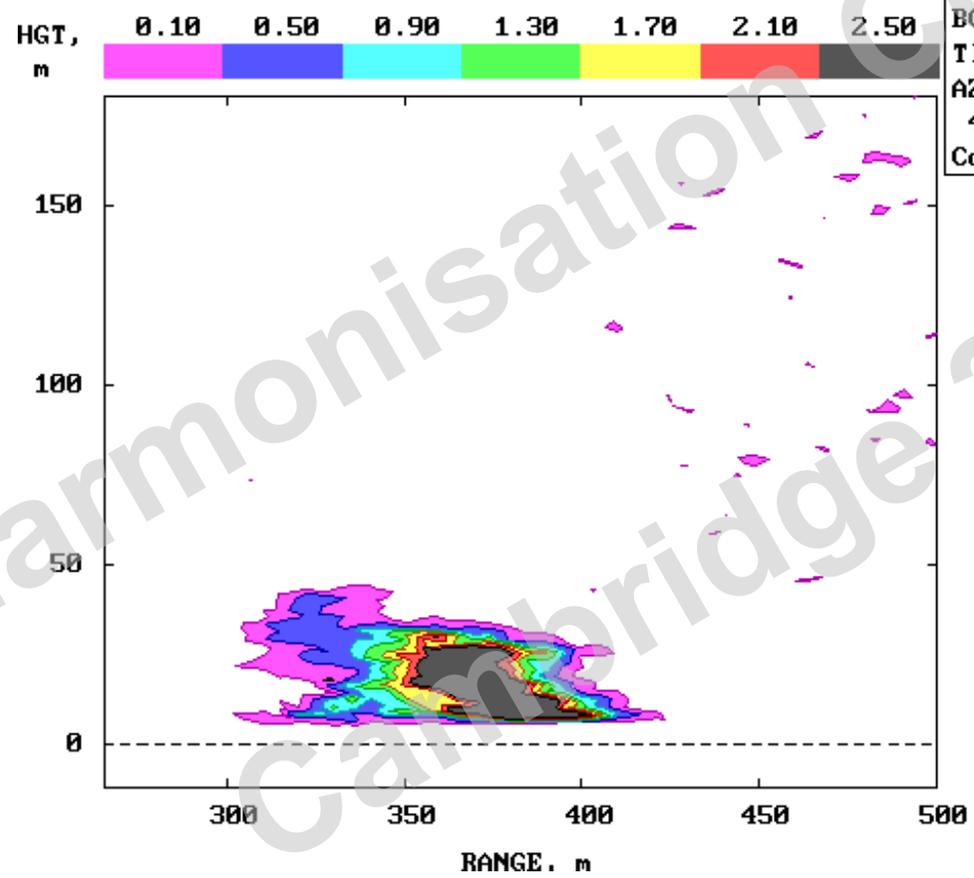


SCANS:- 118 - 118  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:48  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

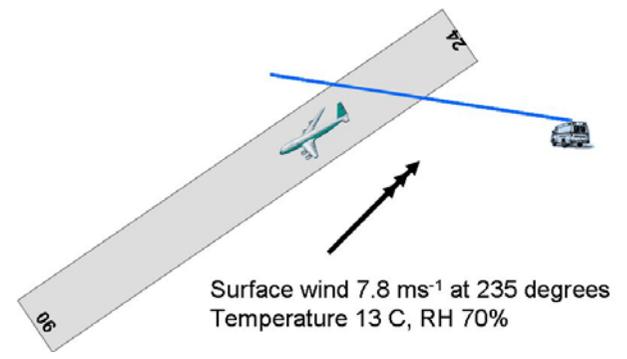


11th Harmonisation Conference 2007

FILE:- 300306.y03 Mean backscatter

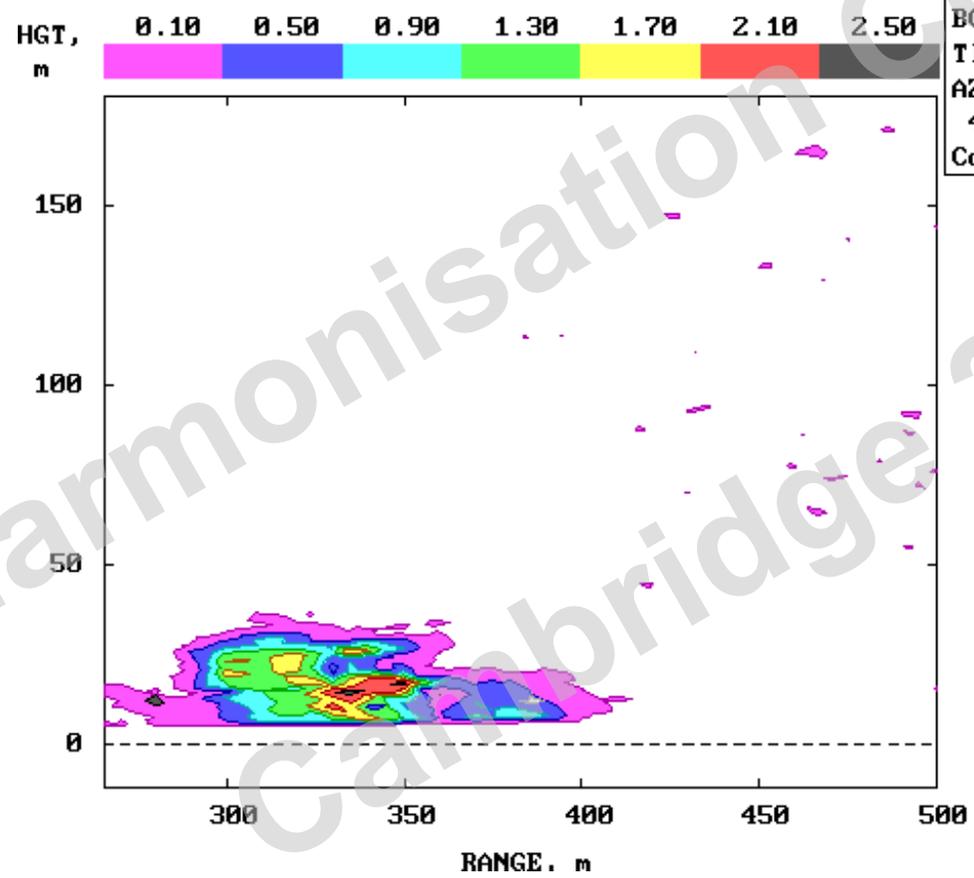


SCANS:- 119 - 119  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:52  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

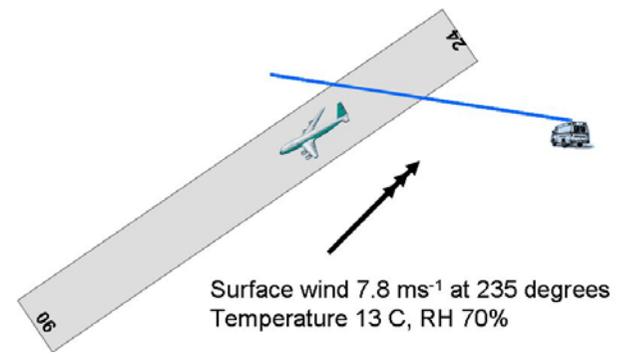


11th Harmonisation Conference Cambridge 2007

FILE:- 300306.y03 Mean backscatter

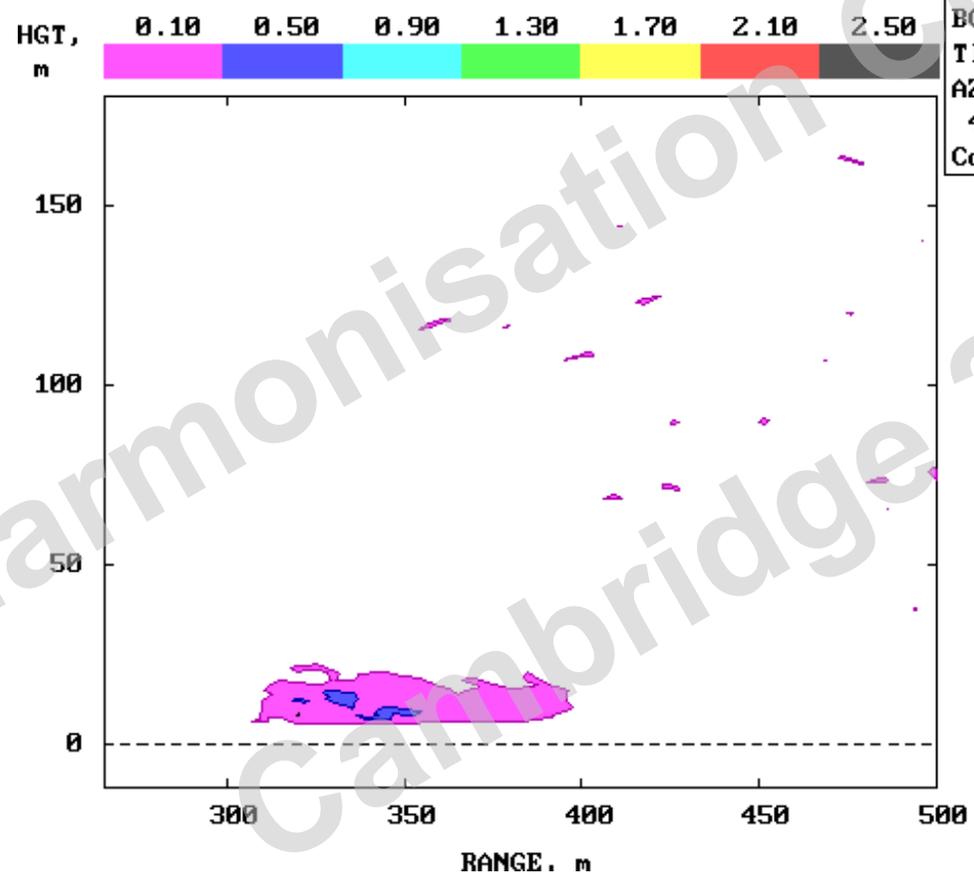


SCANS:- 120 - 120  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:26:56  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

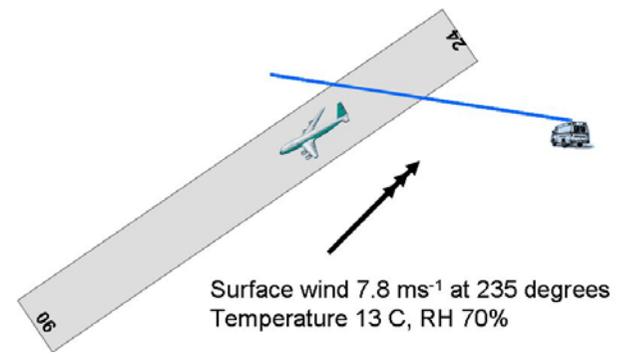


11th Harmonisation Conference

FILE:- 300306.y03 Mean backscatter

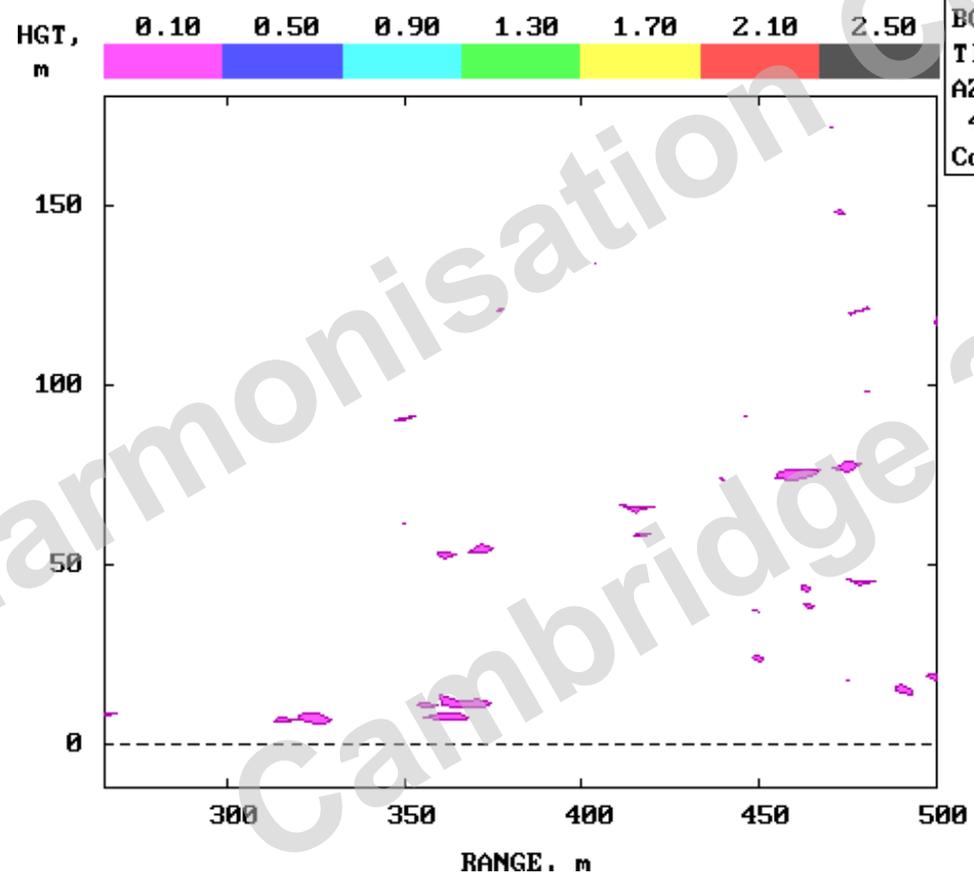


SCANS:- 121 - 121  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:27:00  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

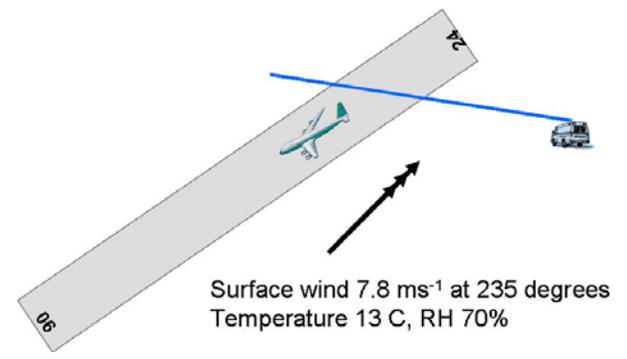


11th Harmonisation Conference

FILE:- 300306.y03 Mean backscatter

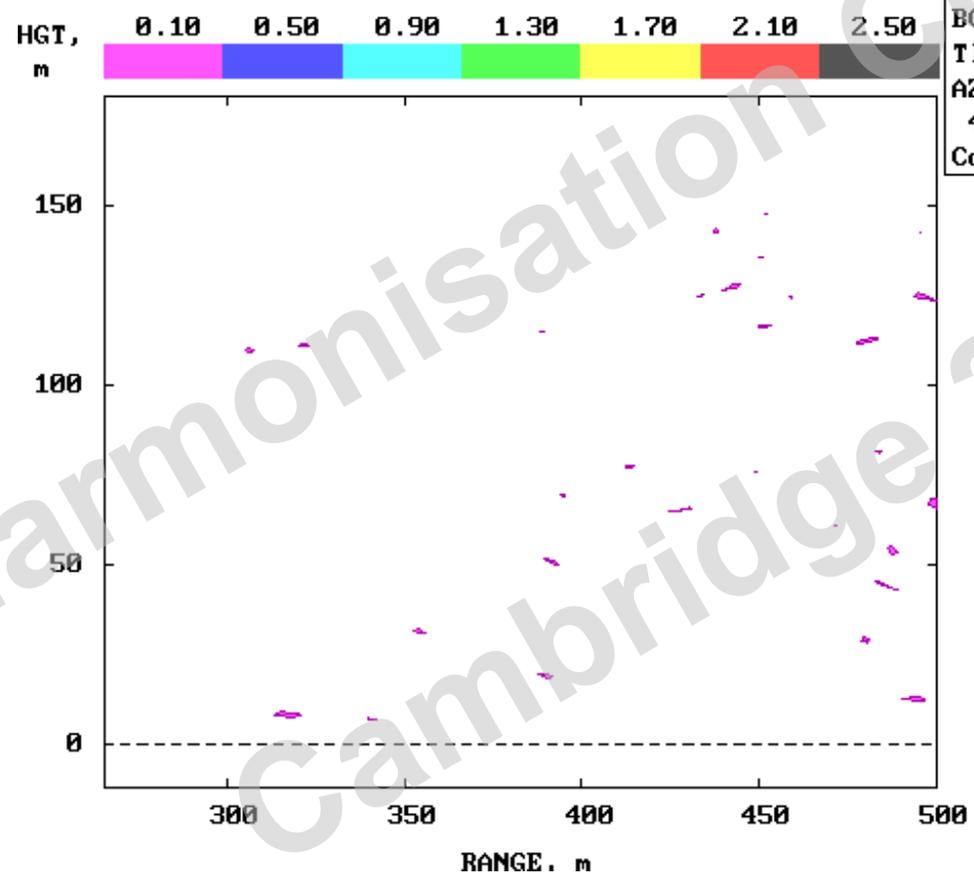


SCANS:- 122 - 122  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:27:04  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

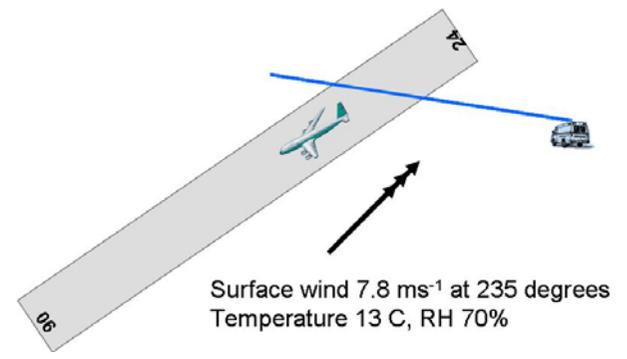


11th Harmonisation Conference

FILE:- 300306.y03 Mean backscatter

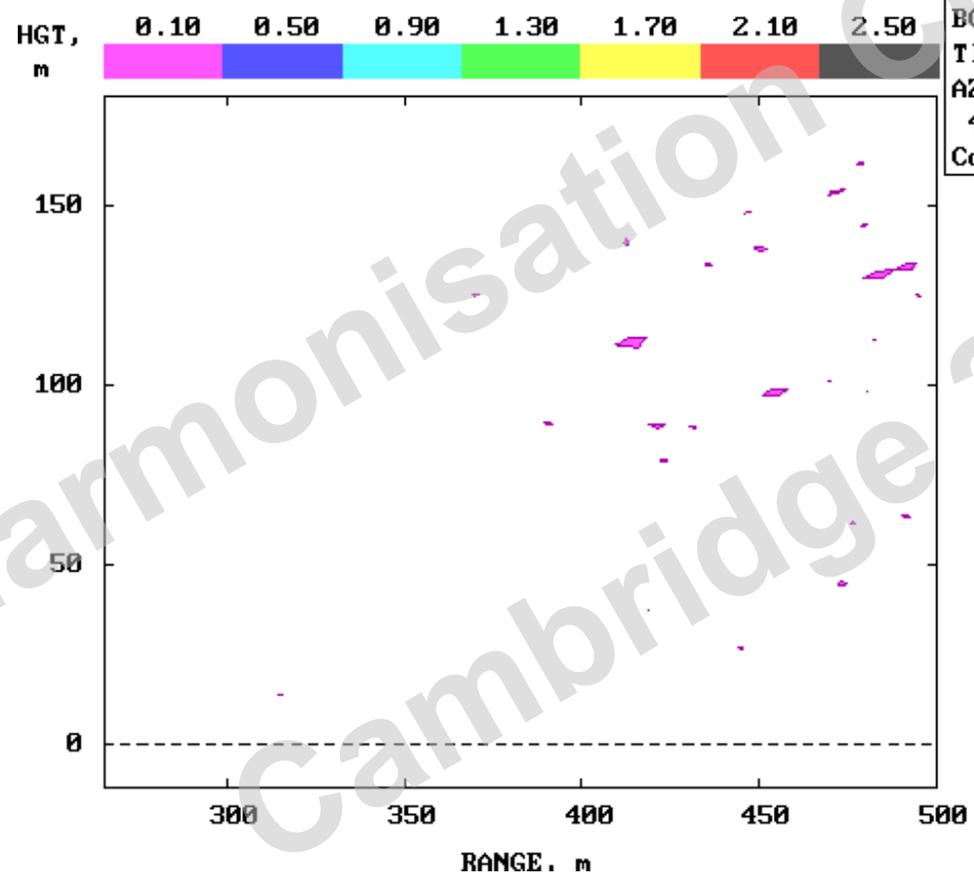


SCANS:- 123 - 123  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:27:08  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.

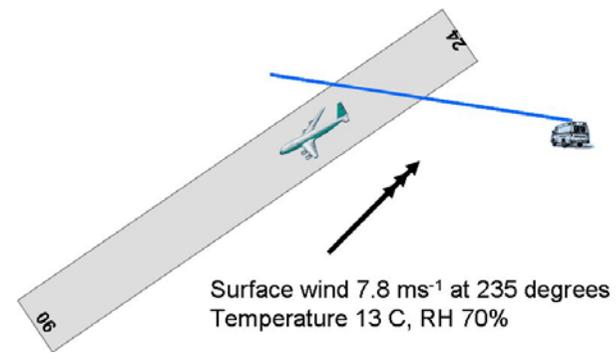


11th Harmonisation Conference

FILE:- 300306.y03 Mean backscatter



SCANS:- 124 - 124  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 12:27:12  
AZIMUTH: 277.4 DEG  
484 scans in file.  
Contour filling on.



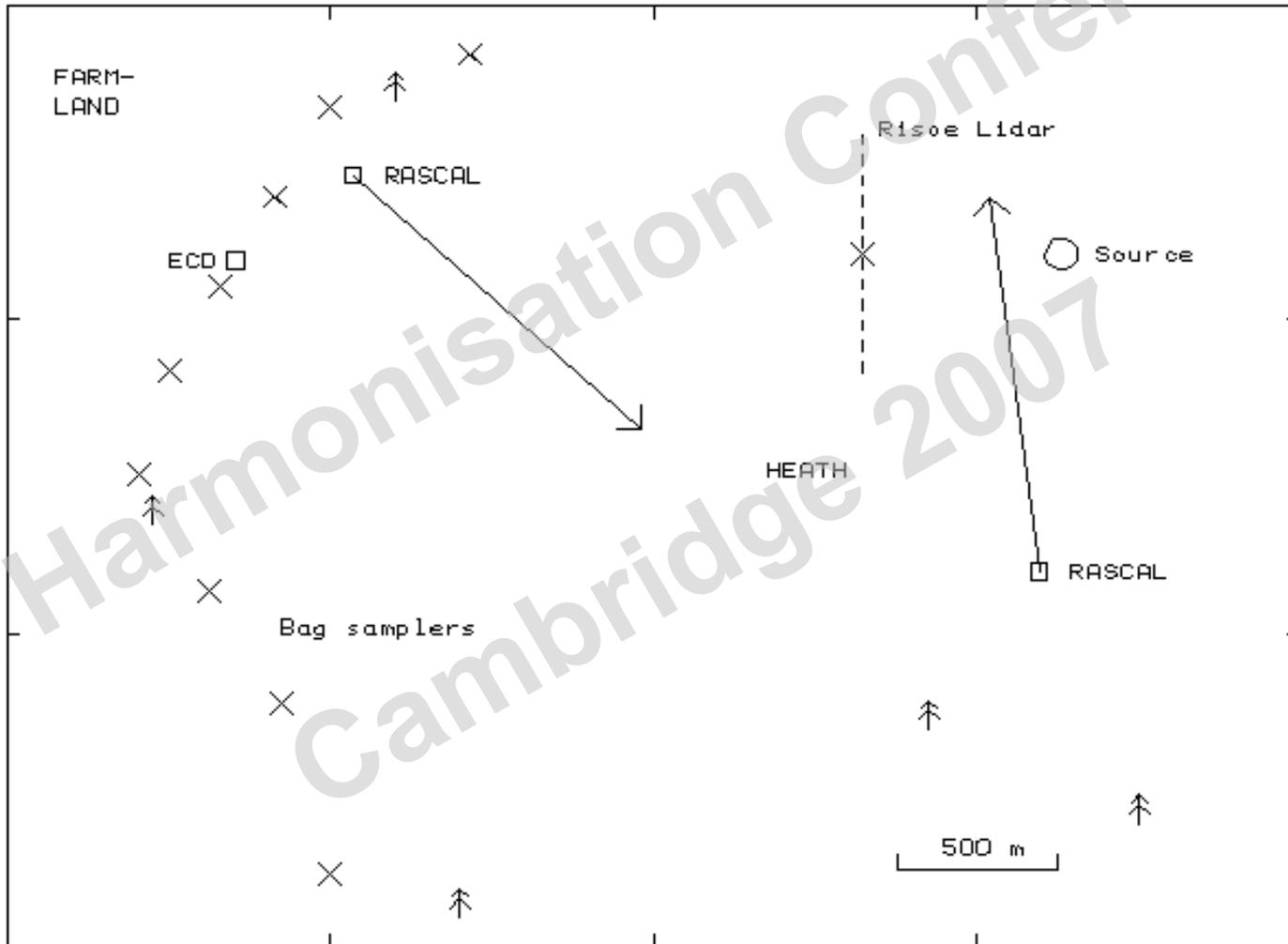
# Issues Regarding Odour Perception

- Adaptation of the nose
- Habituation of the brain
- Non-linear overall response:

Steven's Law,

$$I = k C^n$$

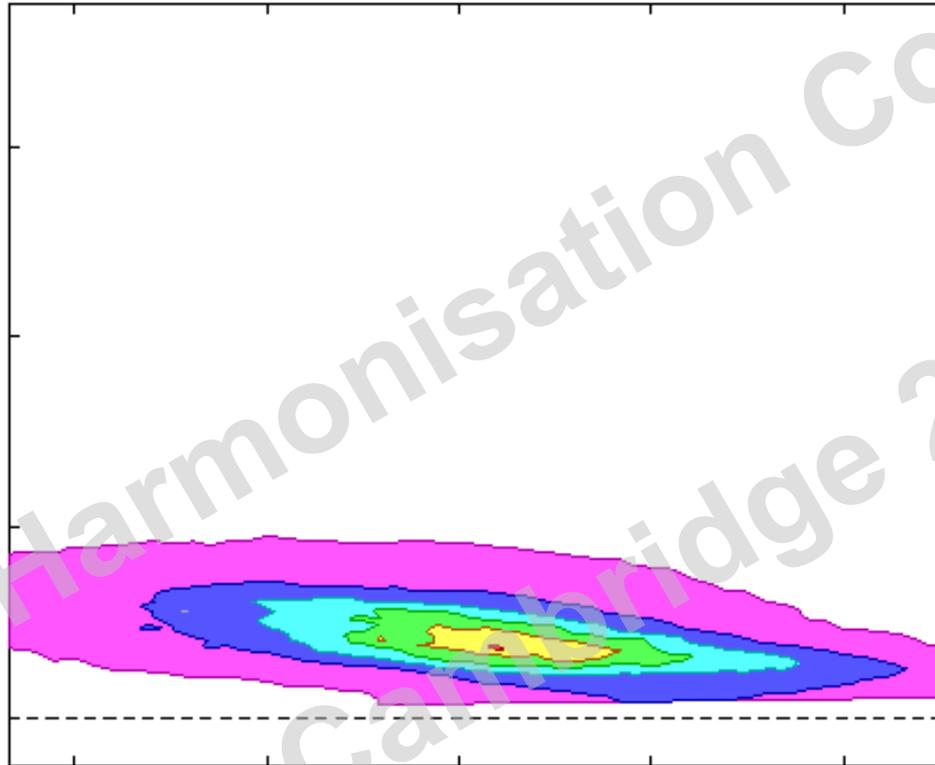
# Test-bed: Borris Heath 11-12/7/1995



FILE:- 110795.y06

Mean backscatter

HGT, 0.20 4.70 9.20 13.70 18.20 22.70 27.20  
m



SCANS:- 2 - 264  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 05:42:51  
AZIMUTH: 132.0 DEG  
264 scans in file.  
Contour filling on.

$$T(20.0) - T(0.23) = 4.0 \text{ } ^\circ\text{C}$$

$$u(10.0) = 3.7 \text{ m s}^{-1}$$

$$x = 1979.1 \text{ m}$$

Backscatter from near-surface plume (21 m release) plume in stable conditions, Borris Heath, 11/7/1995, 23:25:13 – 23:55:07

# Proposed Model of Adaptation

- Signal from nose to brain,  $I' = S.I$
- Sensitivity,  $S$  is subject to a simple adsorption model:

$$\frac{dS}{dt} = \frac{1-S}{\tau_C} - \frac{C S}{C_0 \tau_B} \quad 0 \leq S \leq 1$$

That is, the olfactory cells are blocked at a rate proportional to  $C$  and then clear themselves over a timescale  $\tau_C \approx 5$  s.

FILE:- 110795.y06

Intermittency

SCANS:- 2 - 264

ZERO LEVEL:-

50th percentile

BOTH WINDOWS USED

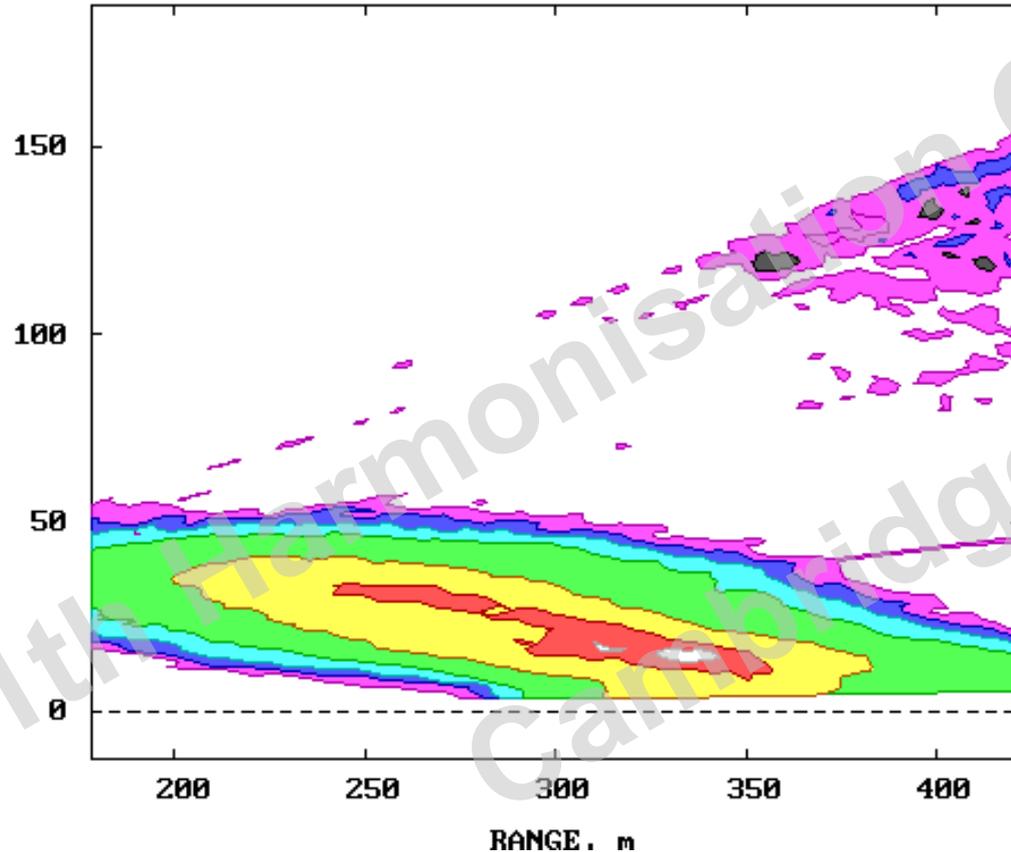
TIME:- 05:42:51

AZIMUTH: 132.0 DEG

264 scans in file.

Contour filling on.

HGT, 0.02 0.05 0.10 0.20 0.50 0.80 0.90  
m

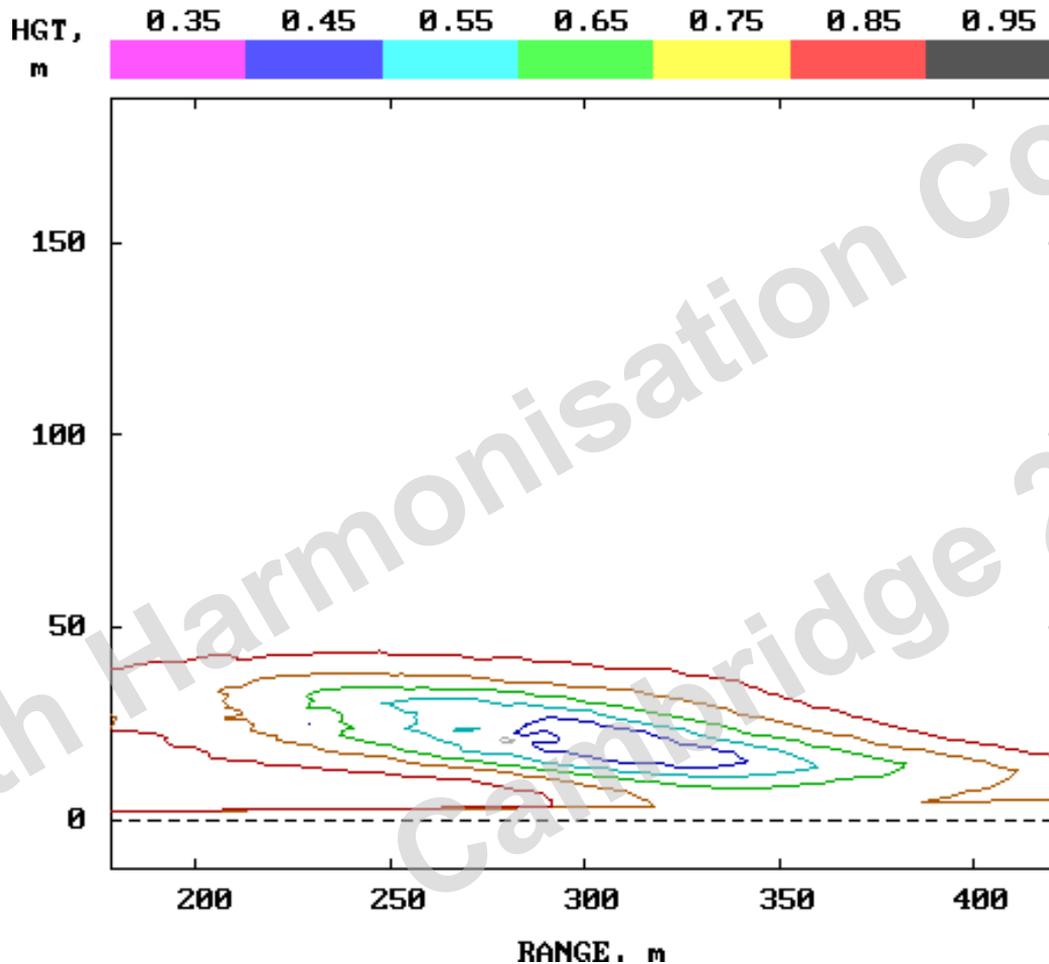


Intermittency of near-surface plume in stable conditions,  
Borris Heath 1995

FILE:- 110795.y06

Sensitivity

SCANS:- 2 - 264  
ZERO LEVEL:-  
50th percentile  
BOTH WINDOWS USED  
TIME:- 05:42:51  
AZIMUTH: 132.0 DEG  
264 scans in file.  
Contour filling off.



Mean sensitivity in near-surface plume in stable conditions

$C$  = Backscatter (bits),

$C_0\tau_B = 50$  bits-s,

$\tau_C = 5$  s.

FILE:- 110795.y06

Olfactory signal

SCANS:- 2 - 264

ZERO LEVEL:-

50th percentile

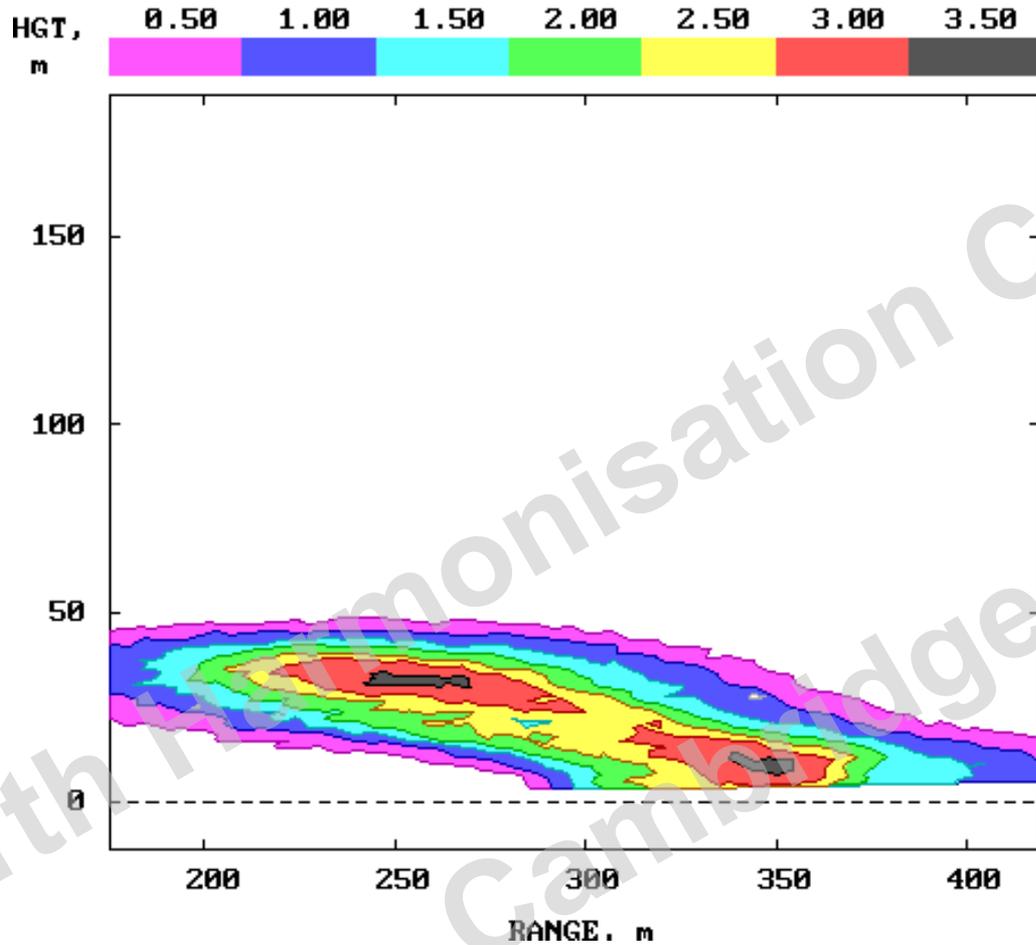
BOTH WINDOWS USED

TIME:- 05:42:51

AZIMUTH: 132.0 DEG

264 scans in file.

Contour filling on.



Mean olfactory signal in near-surface plume in stable conditions

$$I' = S. kC^n, \quad k = 5, \quad n = 0.26$$

# Model of Habituation

- Brain rapidly loses interest in a steady signal
- Assume perception,  $P$  is only of increases in olfactory signal over timescale  $\tau_P$ , *i.e.*

$$P = \begin{cases} \tau_P \frac{dI'}{dt} / \text{Max}(I', I_0), & \frac{dI'}{dt} > 0 \\ 0, & \frac{dI'}{dt} \leq 0 \end{cases}$$

where  $I_0$  is the ambient background signal.

FILE:- 110795.y06

Perceived odour

SCANS:- 2 - 264

ZERO LEVEL:-

50th percentile

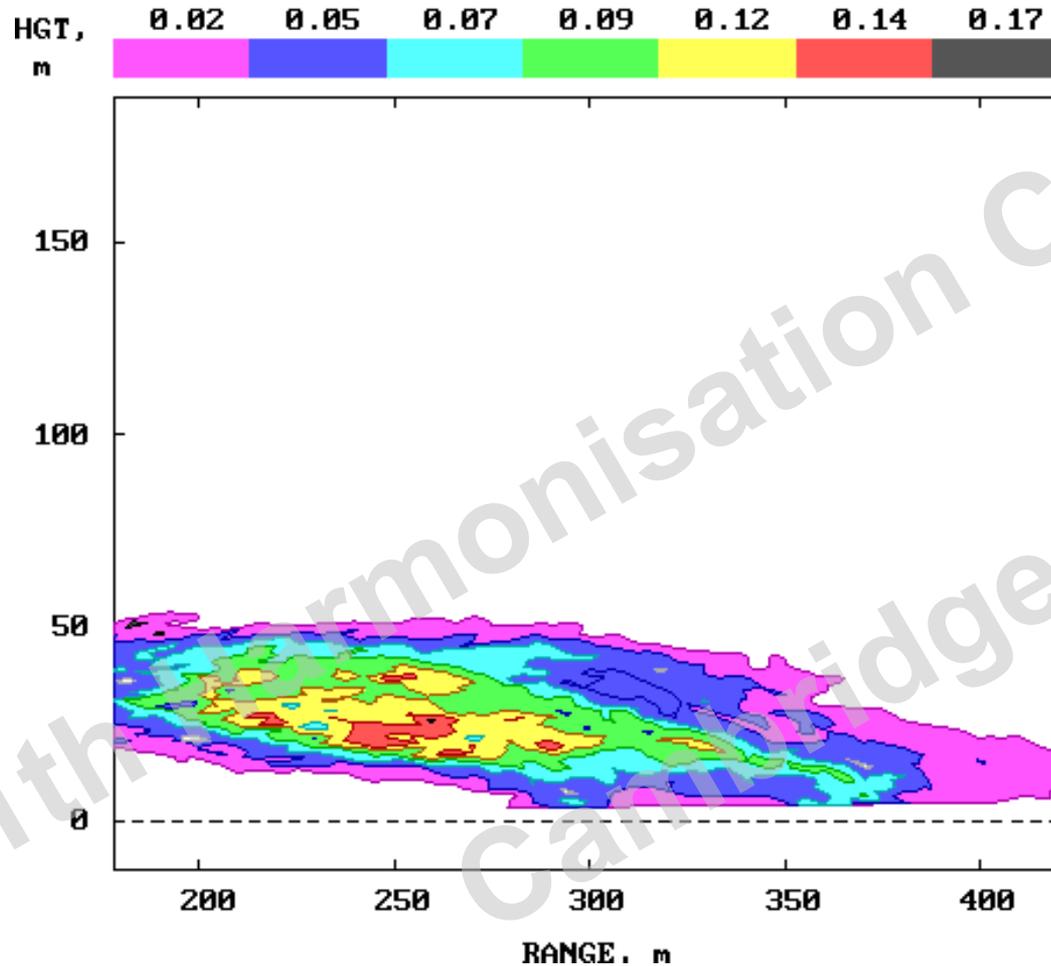
BOTH WINDOWS USED

TIME:- 05:42:51

AZIMUTH: 132.0 DEG

264 scans in file.

Contour filling on.



Mean perceived odour in near-surface plume in stable conditions

$$\tau_p = 2.5 \text{ s}, \quad I_0 = 1$$

FILE:- 110795.y01

Mean backscatter

SCANS:- 1 - 329

ZERO LEVEL:-

50th percentile

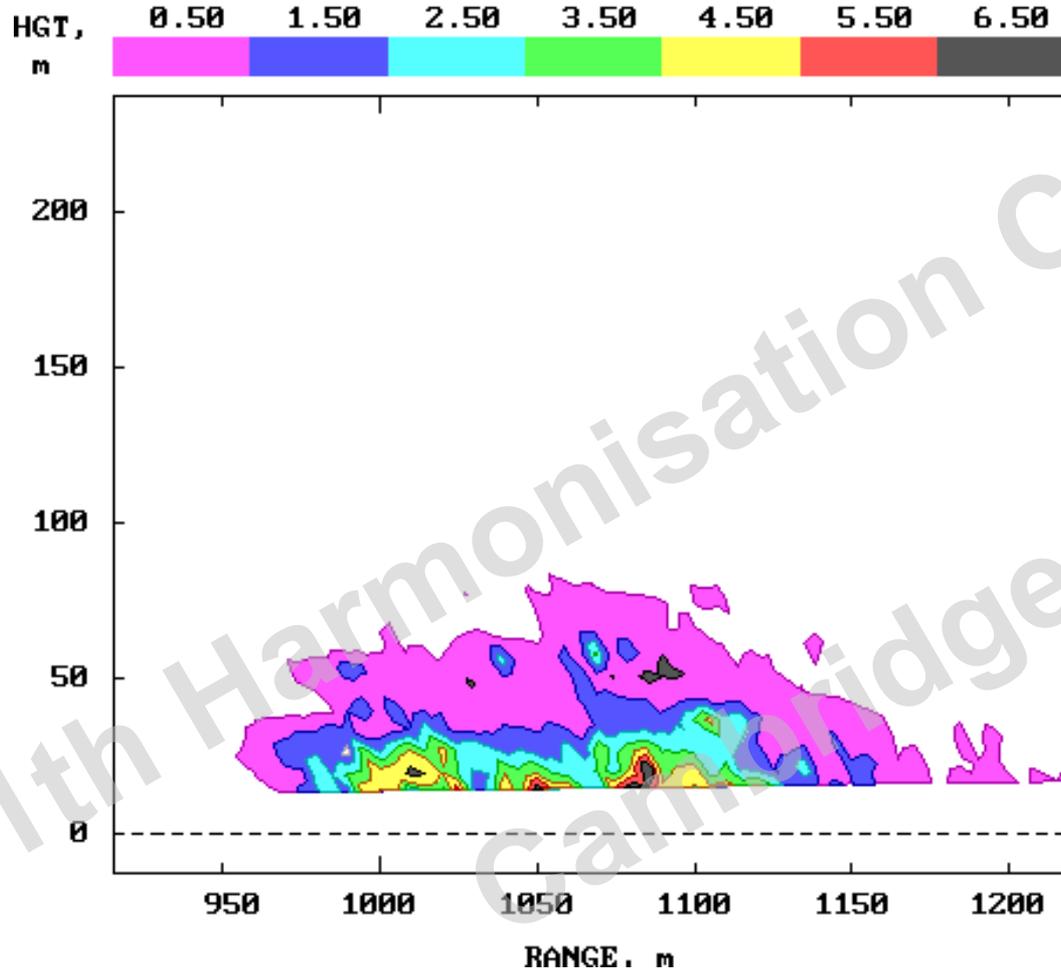
BOTH WINDOWS USED

TIME:- 15:39:27

AZIMUTH: 352.7 DEG

330 scans in file.

Contour filling on.



$$T(20.0) - T(0.23) = -3.8 \text{ } ^\circ\text{C}$$

$$u(10.0) = 6.7 \text{ m s}^{-1}$$

$$x = 207.8 \text{ m}$$

Backscatter from near-surface plume (21 m release) plume in convective conditions, Borris Heath, 11/7/1995, 15:08:39 – 15:39:27

FILE:- 110795.y01

Intermittency

SCANS:- 1 - 329

ZERO LEVEL:-

50th percentile

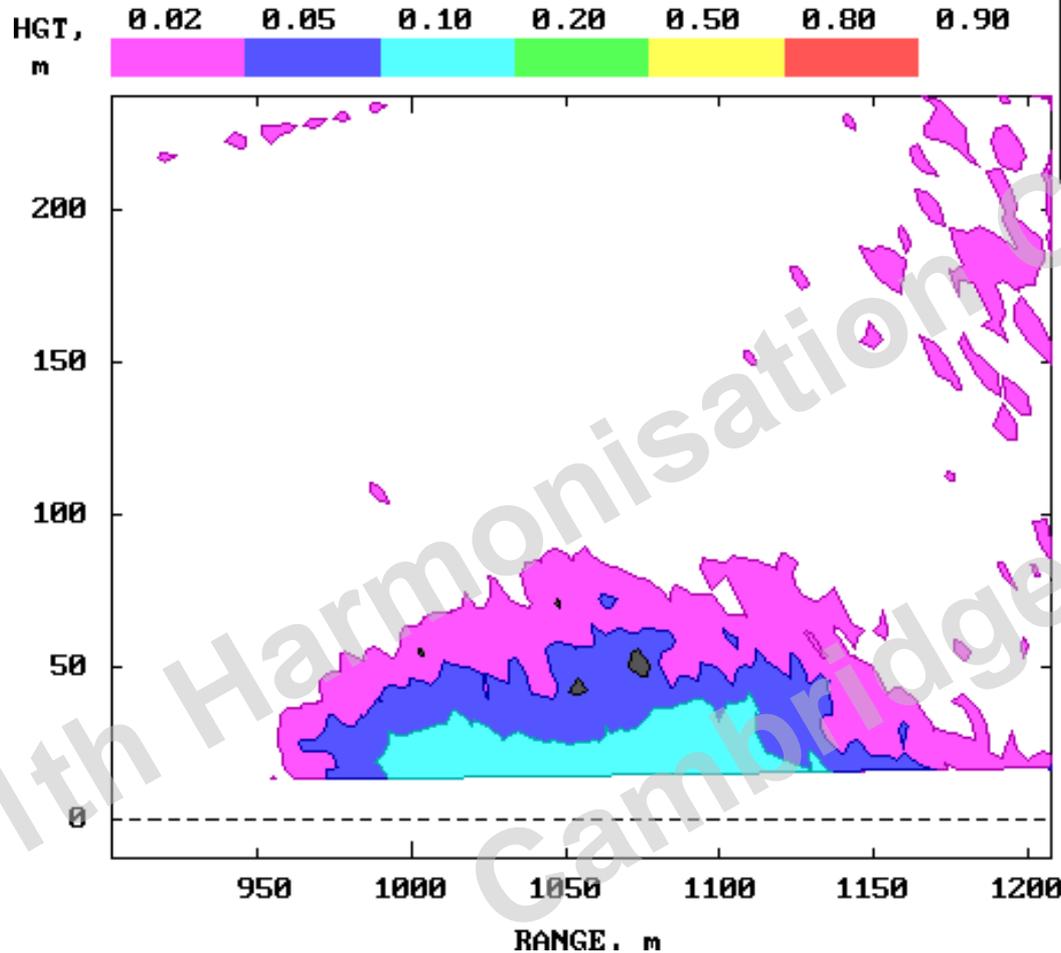
BOTH WINDOWS USED

TIME:- 15:39:27

AZIMUTH: 352.7 DEG

330 scans in file.

Contour filling on.



Intermittency of near-surface plume in convective conditions,  
Borris Heath 1995

FILE:- 110795.g01

Sensitivity

SCANS:- 1 - 329

ZERO LEVEL:-

50th percentile

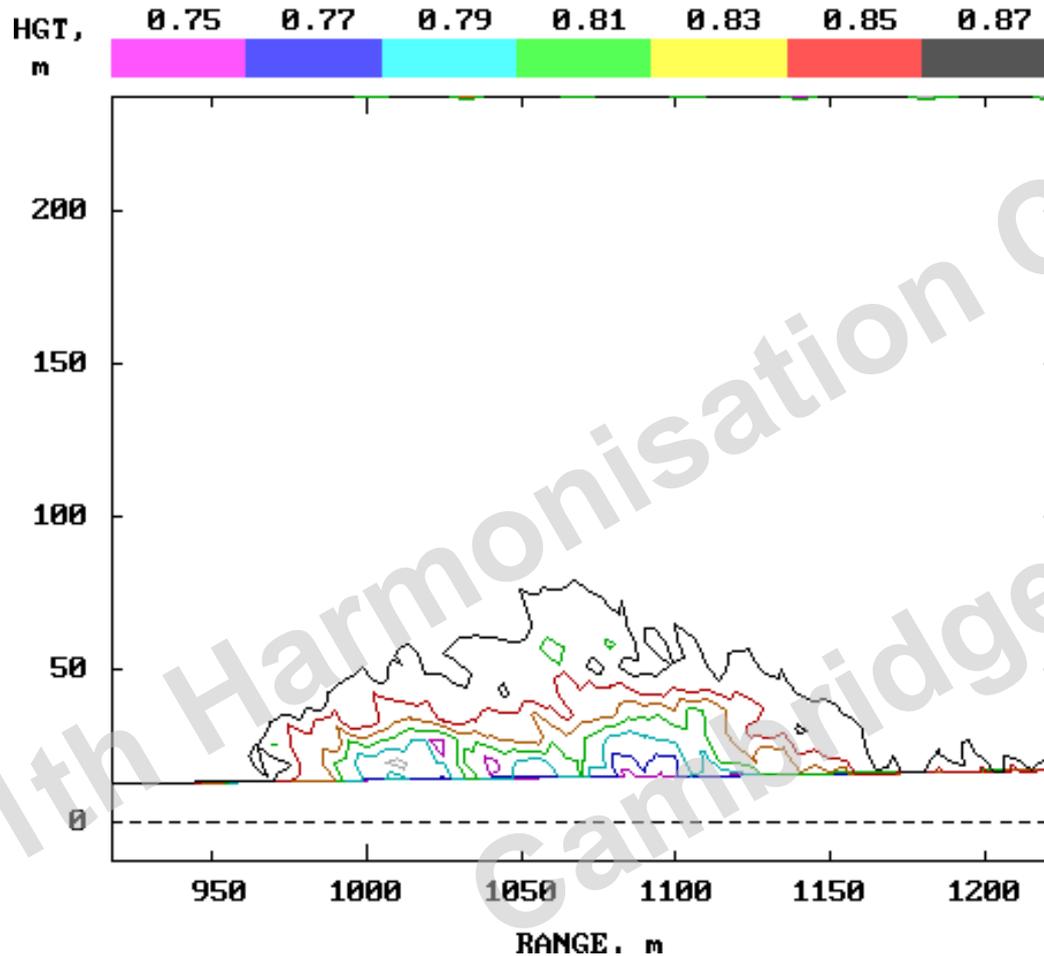
BOTH WINDOWS USED

TIME:- 15:39:27

AZIMUTH: 352.7 DEG

330 scans in file.

Contour filling off.



Mean sensitivity in near-surface plume in convective conditions

$$C = \text{Backscatter}, \quad C_0 \tau_B = 50 \text{ s}, \quad \tau_C = 5 \text{ s}.$$

FILE:- 110795.y01

Olfactory signal

SCANS:- 1 - 329

ZERO LEVEL:-

50th percentile

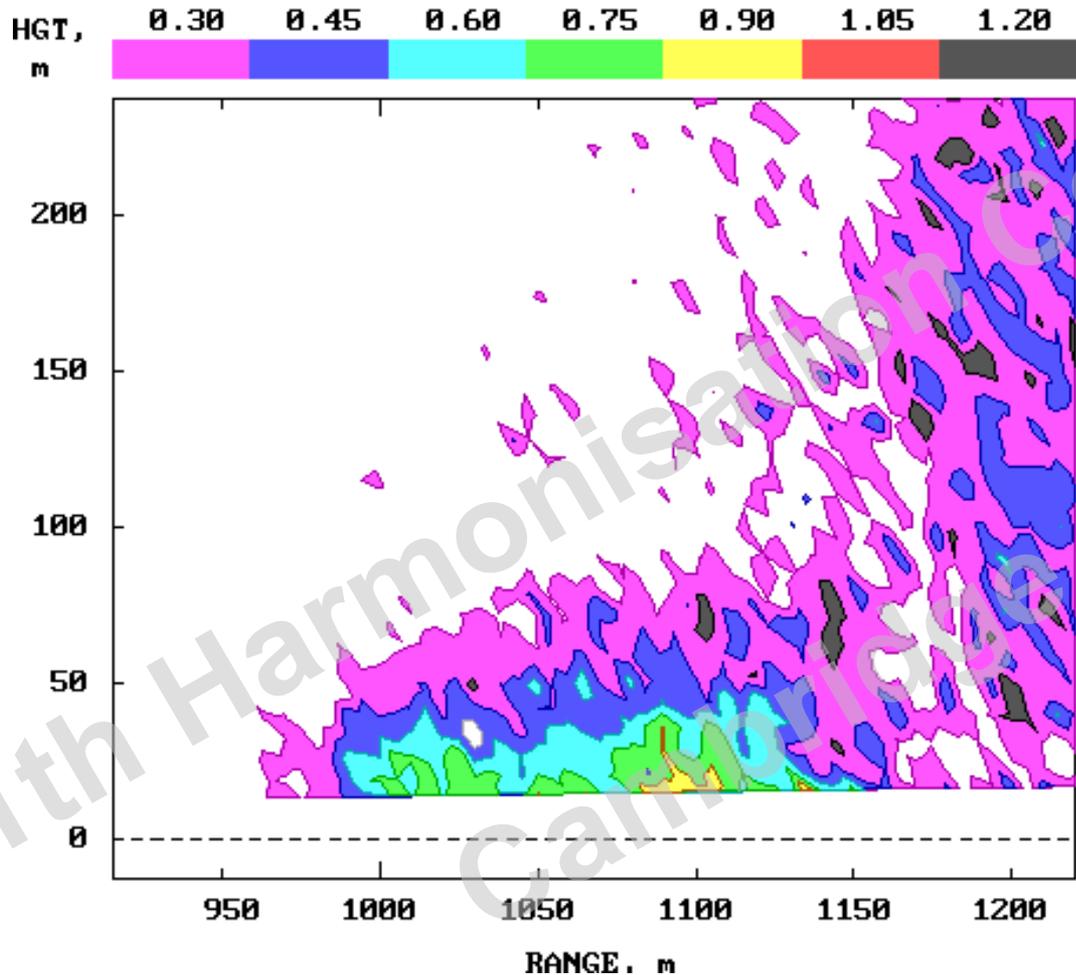
BOTH WINDOWS USED

TIME:- 15:39:27

AZIMUTH: 352.7 DEG

330 scans in file.

Contour filling on.



Mean olfactory signal in near-surface plume in convective conditions

$$I' = S. kC^n,$$

$$k = 5,$$

$$n = 0.26$$

FILE:- 110795.y01

Perceived odour

SCANS:- 1 - 329

ZERO LEVEL:-

50th percentile

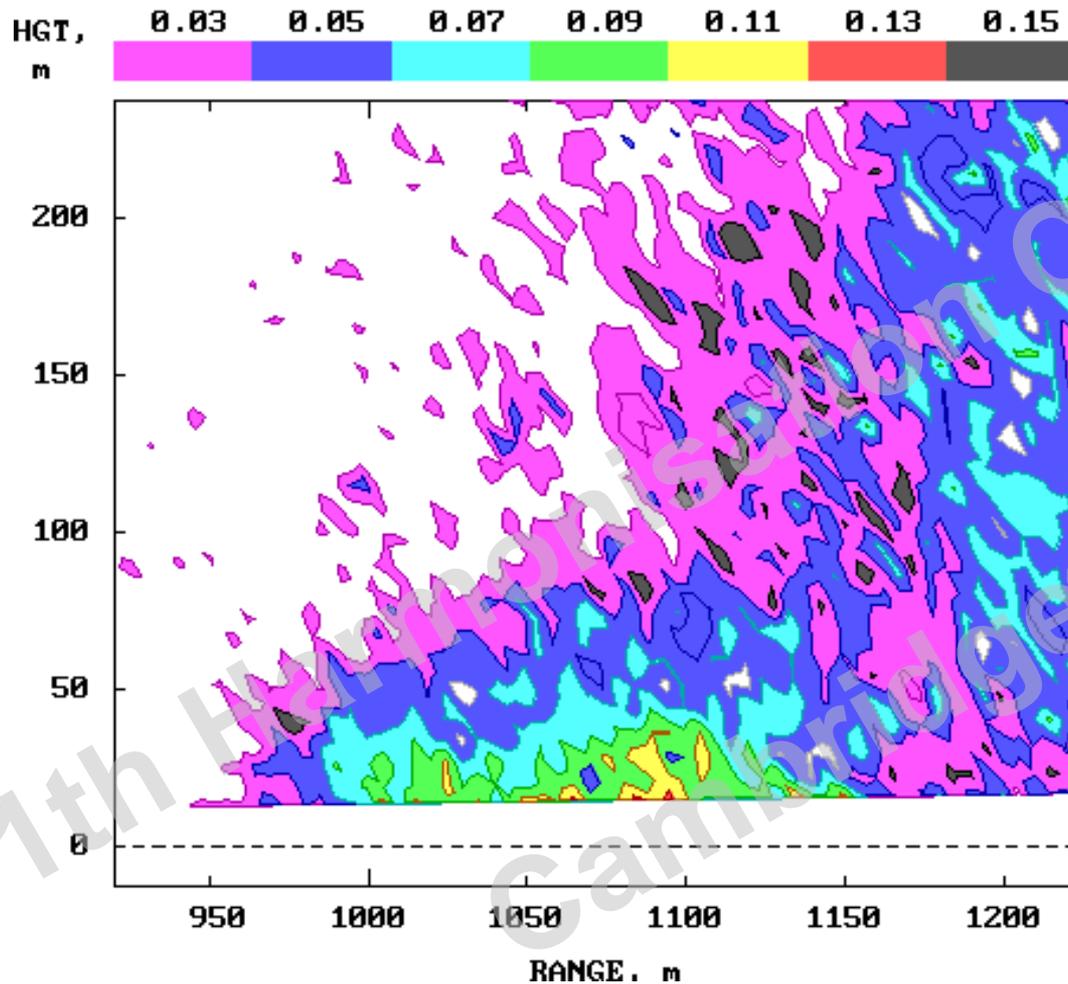
BOTH WINDOWS USED

TIME:- 15:39:27

AZIMUTH: 352.7 DEG

330 scans in file.

Contour filling on.

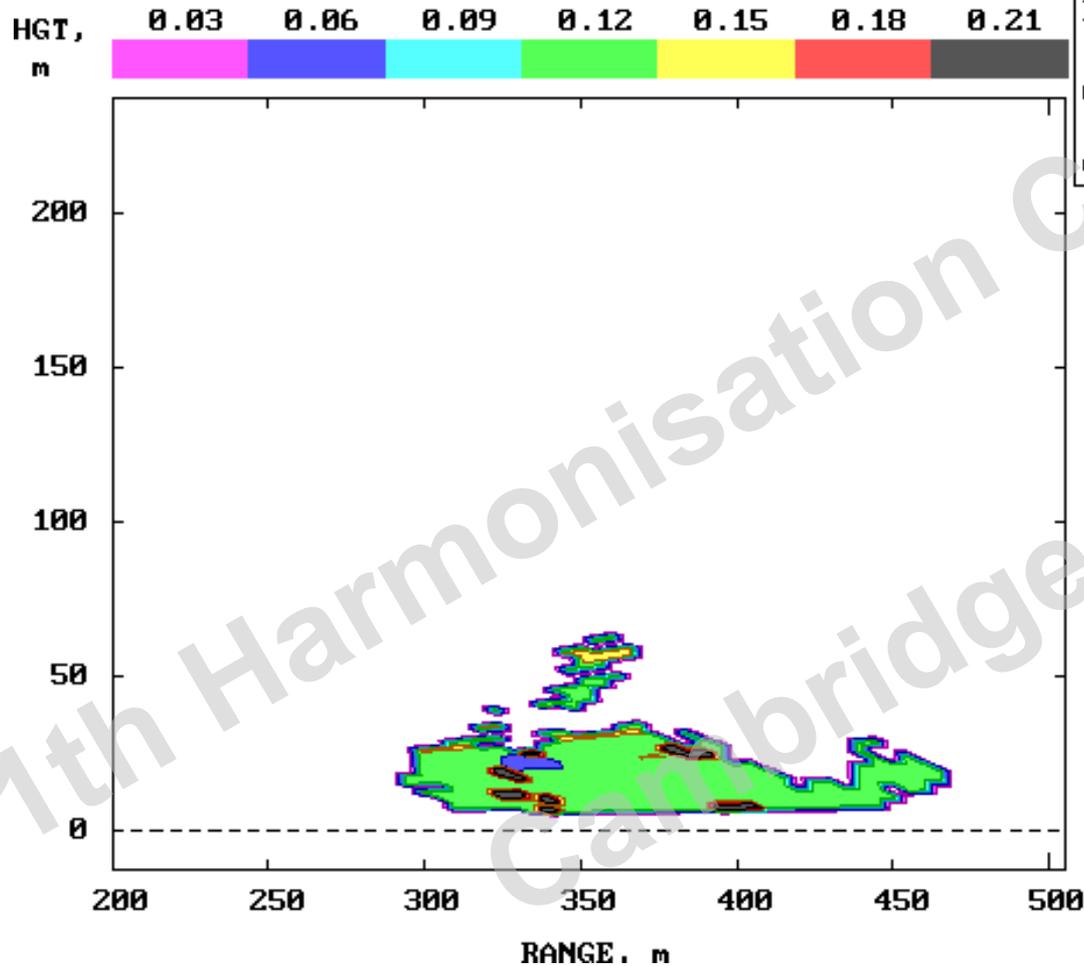


Mean perceived odour in near-surface plume in convective conditions

$$\tau_p = 2.5 \text{ s}, \quad I_0 = 1$$

FILE:- 300306.y03

Perceived odour



SCANS:- 114 - 122

ZERO LEVEL:-

50th percentile

BOTH WINDOWS USED

TIME:- 12:27:04

AZIMUTH: 277.4 DEG

484 scans in file.

Contour filling on.

Mean perceived odour from tyre smoke of individual landing at Ringway, 1227, 30/3/06. Same odour parameters as for Borriss.

# Conclusions

- In so far as aerosol is a tracer for odorants, then our model can enable Lidar to map odour nuisance. Faster scanning would be helpful.
- Where odours are well above background, nuisance reduces only weakly with dispersion.
- Odour perception is a dynamic and non-linear process: reliable parameters are required!