



11th Harmonisation Conference
Cambridge 2007

A simple approach for rapid operational air quality modelling at airports

Steven Barrett and Rex Britter

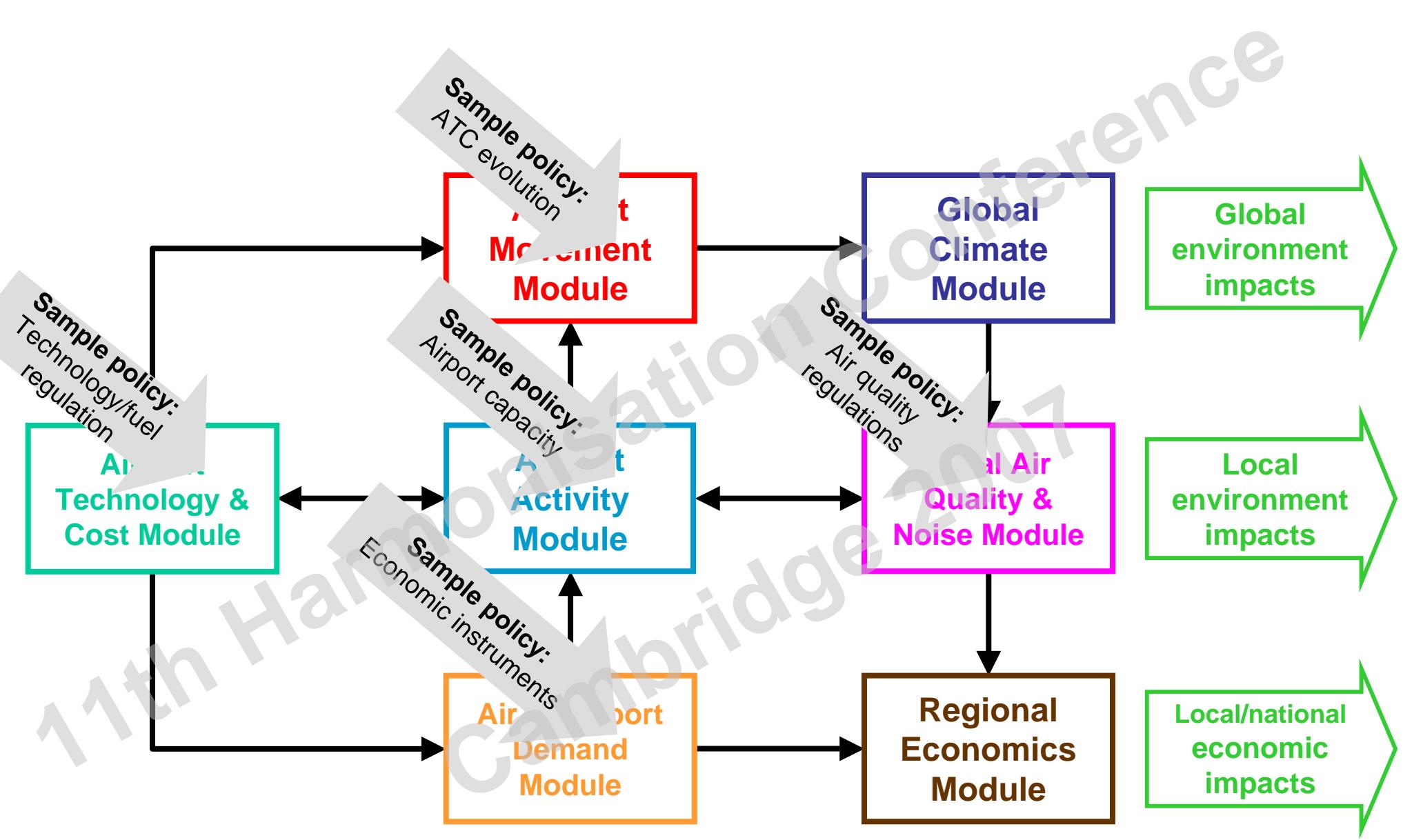
Department of Engineering
University of Cambridge



AVIATION INTEGRATED MODELLING PROJECT

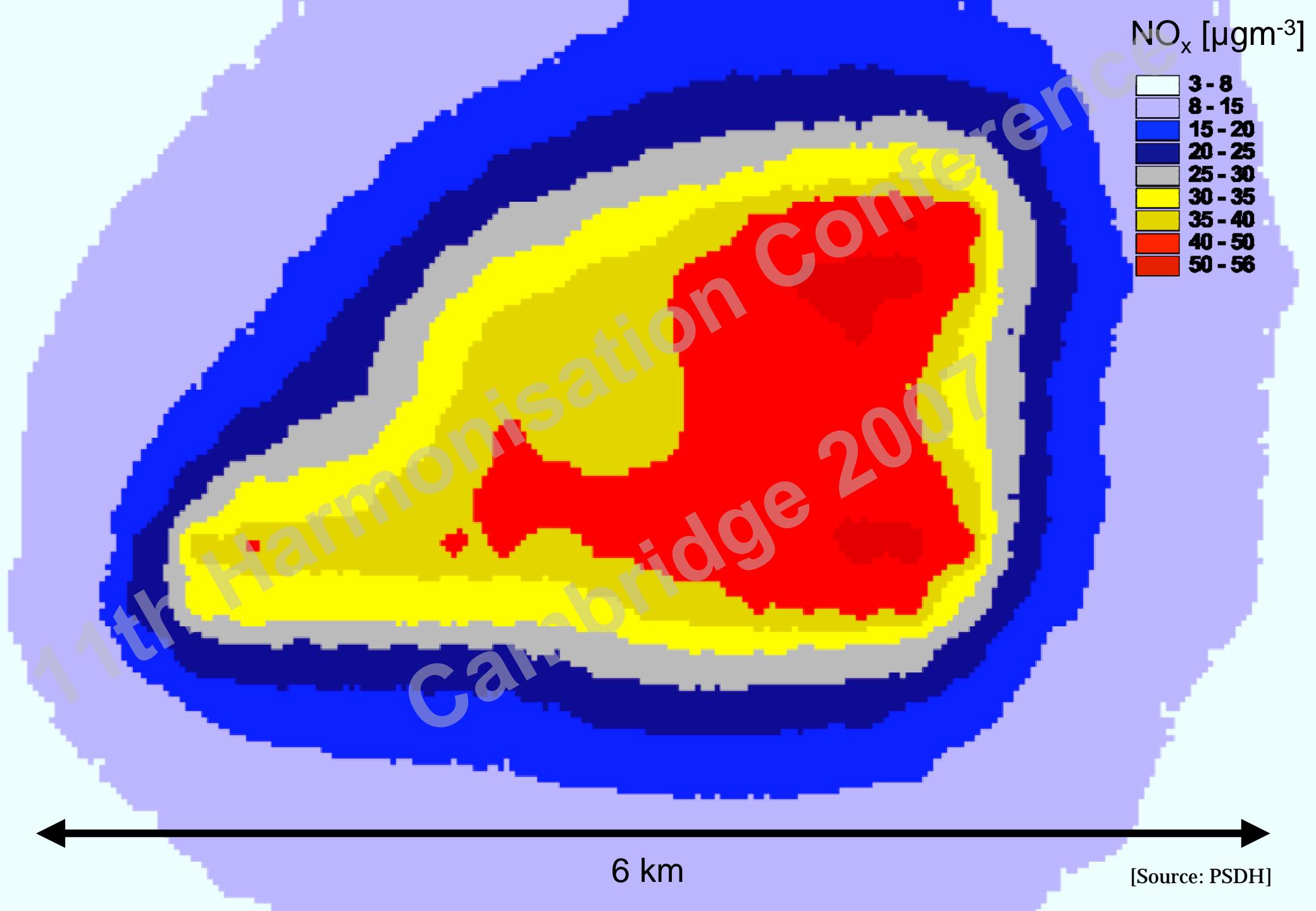
www.AIMPROJECT.AERO





NO_x [μgm^{-3}]

3 - 8
8 - 15
15 - 20
20 - 25
25 - 30
30 - 35
35 - 40
40 - 50
50 - 56



6 km

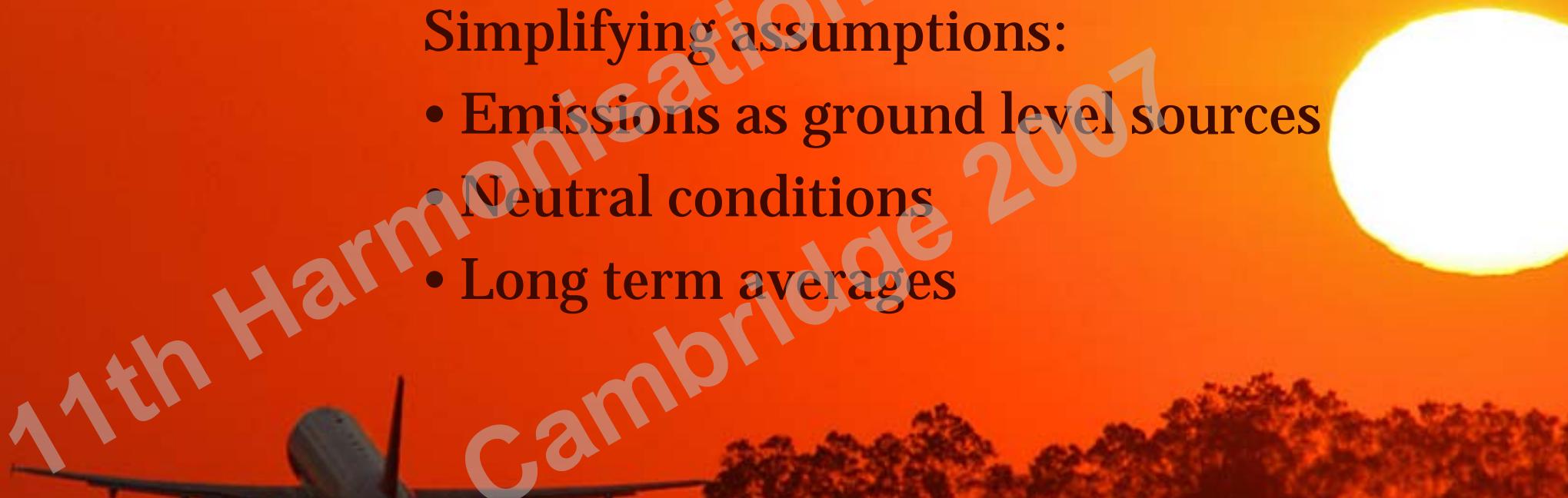
[Source: PSDH]

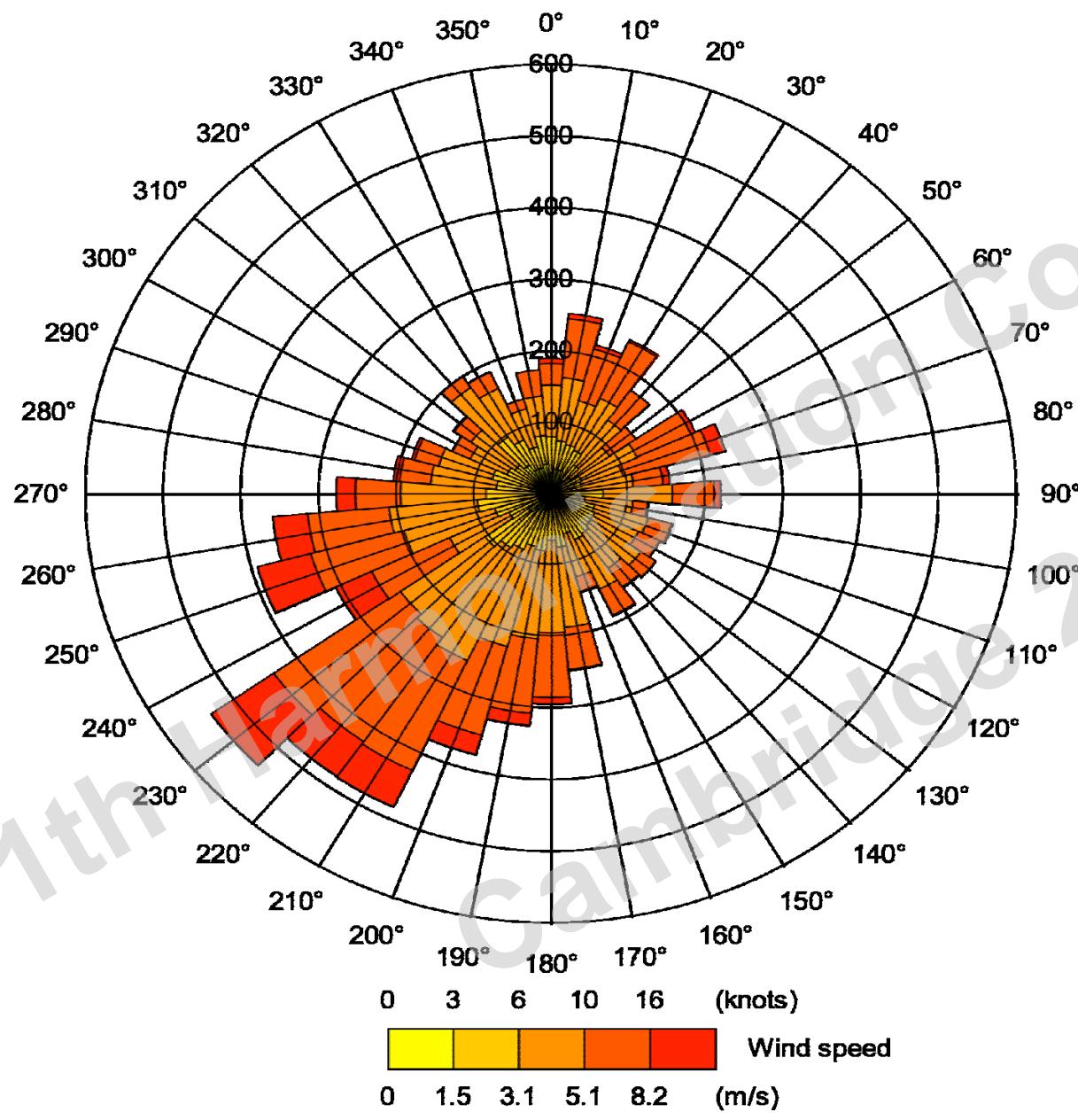
Objectives:

- Low data input requirements
- Short run-times

Simplifying assumptions:

- Emissions as ground level sources
- Neutral conditions
- Long term averages





$$p(u_r, \theta)$$

[Source: CERC]

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N p(\theta, u_r) \chi(x, y; u_r, \theta) du_r d\theta$$

11th Harmonisation Conference
Cambridge 2007

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N p(\theta, u_r) \chi(x, y; u_r, \theta) du_r d\theta$$

$$\hat{u} = \frac{u_r}{u_*} = \frac{\ln(z_r / z_0)}{\kappa}$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N p(\theta, u_r) \chi(x, y; u_r, \theta) du_r d\theta$$

$$\hat{u} = \frac{u_r}{u_*} = \frac{\ln(z_r / z_0)}{\kappa}$$

$$\chi(x, y, z) / Q = \chi_l(x, y) \chi_v(x, z)$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N p(\theta, u_r) \chi(x, y; u_r, \theta) du_r d\theta$$

$$\hat{u} = \frac{u_r}{u_*} = \frac{\ln(z_r / z_0)}{\kappa}$$

$$\chi(x, y, z) / Q = \chi_l(x, y) \chi_v(x, z)$$

$$\chi_v(x, z) = \frac{1}{\kappa u_* x} \exp\left(-\frac{\bar{u}z}{\kappa u_* x}\right)$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N p(\theta, u_r) \chi(x, y; u_r, \theta) du_r d\theta$$

$$\hat{u} = \frac{u_r}{u_*} = \frac{\ln(z_r / z_0)}{\kappa}$$

$$\chi(x, y, z) / Q = \chi_l(x, y) \chi_v(x, z)$$

$$\chi_v(x, z) = \frac{1}{\kappa u_* x} \exp\left(-\frac{\bar{u}z}{\kappa u_* x}\right)$$

$$\chi_l(x, y) = \frac{1}{\sigma_y \sqrt{2\pi}} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N p(\theta, u_r) \chi(x, y; u_r, \theta) du_r d\theta$$

$$\hat{u} = \frac{u_r}{u_*} = \frac{\ln(z_r / z_0)}{\kappa}$$

$$\chi(x, y, z) / Q = \chi_l(x, y) \chi_v(x, z)$$

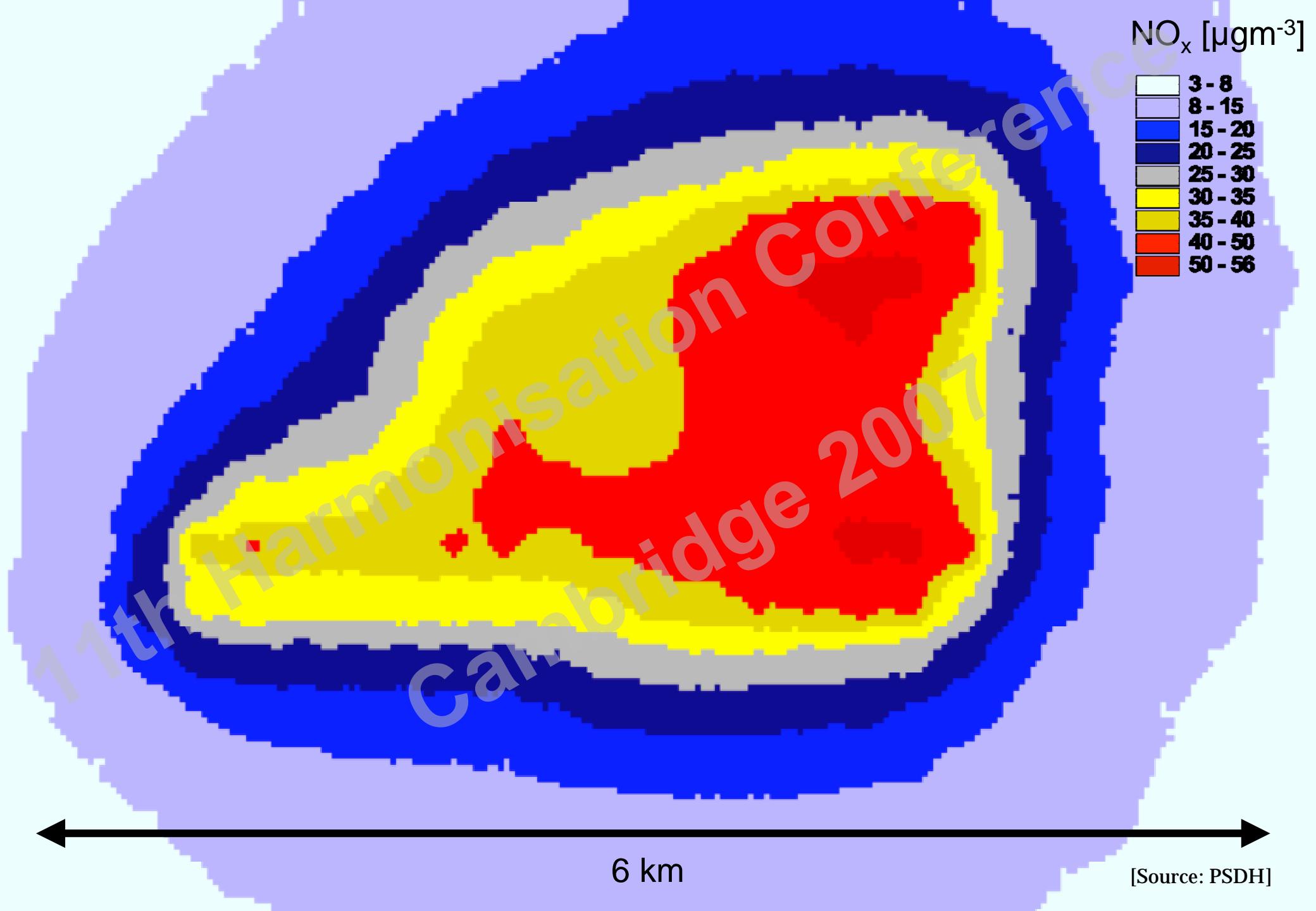
$$\chi_v(x, z) = \frac{1}{\kappa u_* x} \exp\left(-\frac{\bar{u}z}{\kappa u_* x}\right)$$

$$\chi_l(x, y) = \frac{1}{\sigma_y \sqrt{2\pi}} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\sigma_y = 0.16x$$

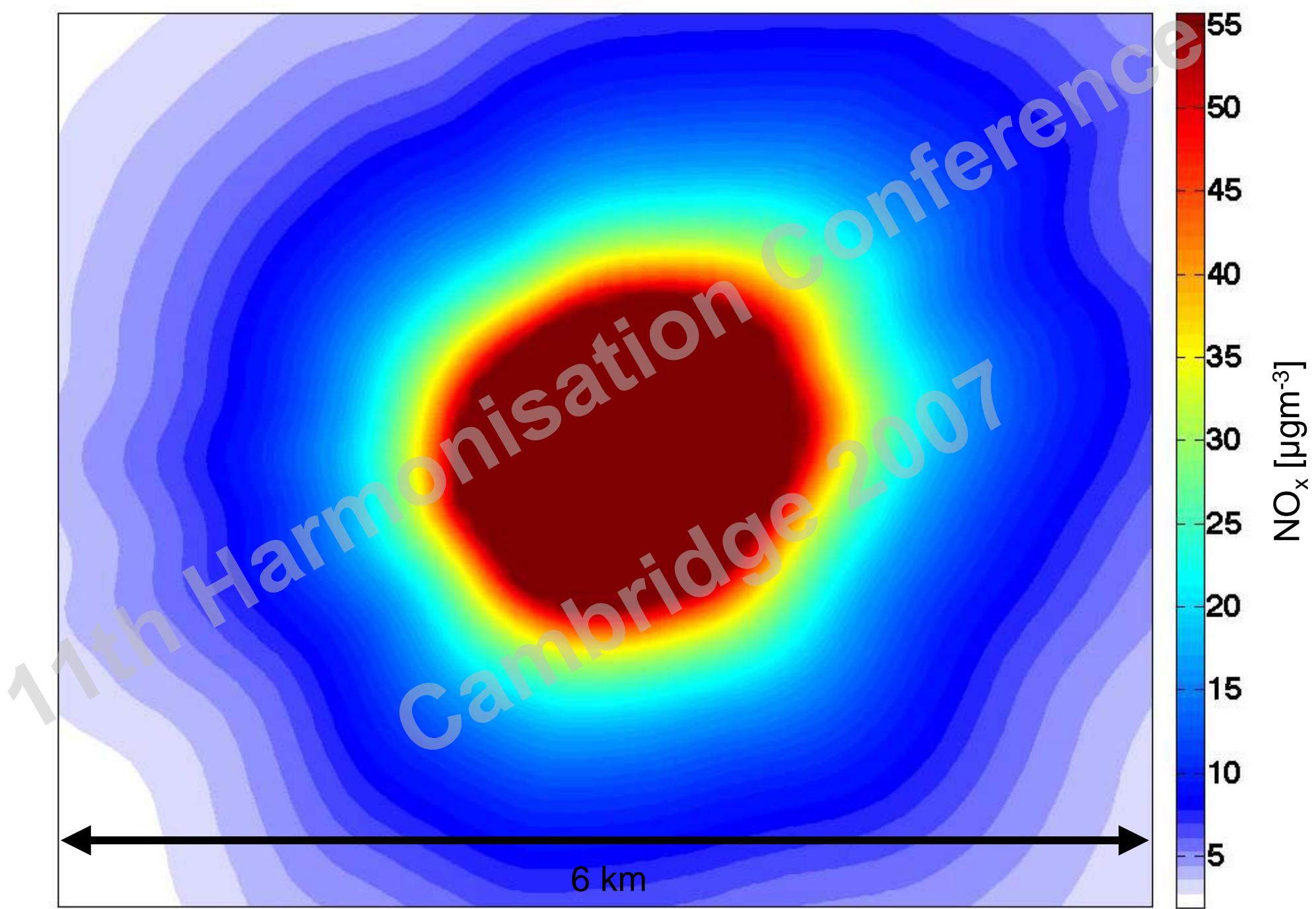
NO_x [μgm^{-3}]

3 - 8
8 - 15
15 - 20
20 - 25
25 - 30
30 - 35
35 - 40
40 - 50
50 - 56



6 km

[Source: PSDH]



$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta$$

11th Harmonisation Conference
Cambridge 2007

$$\begin{aligned}\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\ &= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \int u_r^{-1} p(\theta, u_r) du_r d\theta\end{aligned}$$

11th Harmonisation Conference
Cambridge 2007

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta$$

$$= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \int u_r^{-1} p(\theta, u_r) du_r d\theta$$

$$\chi(x, 0, z) = \underbrace{\frac{Q_i}{\kappa u_* x}}_{\chi_v} \times \underbrace{\frac{1}{\sigma_y \sqrt{2\pi}}}_{\chi_l} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta$$

$$= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \int u_r^{-1} p(\theta, u_r) du_r d\theta$$

$$\chi(x, 0, z) = \underbrace{\frac{Q_i}{\kappa u_* x}}_{\chi_v} \times \underbrace{\frac{1}{\sigma_y \sqrt{2\pi}} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)}_{\chi_l}$$

$$\hat{u} = \frac{u_r}{u_*}$$

$$\begin{aligned}\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\ &= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \int u_r^{-1} p(\theta, u_r) du_r d\theta\end{aligned}$$

$$\chi(x, 0, z) = \underbrace{\frac{Q_i \hat{u}}{\kappa u_r x}}_{\chi_v} \times \underbrace{\frac{1}{\sigma_y \sqrt{2\pi}}}_{\chi_l} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\hat{u} = \frac{u_r}{u_*}$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta$$

$$= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \int u_r^{-1} p(\theta, u_r) du_r d\theta$$

$$\chi(x, 0, z) = \underbrace{\frac{Q_i \hat{u}}{\kappa u_r x}}_{\chi_v} \times \underbrace{\frac{1}{\sigma_y \sqrt{2\pi}}}_{\chi_l} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\hat{u} = \frac{u_r}{u_*}$$

$$\hat{\chi} = \chi u_r / Q_i$$

$$\langle \chi(x, y) \rangle = \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta$$

$$= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \int u_r^{-1} p(\theta, u_r) du_r d\theta$$

$$\hat{\chi}(x, 0, z) = \underbrace{\frac{\hat{u}}{\kappa \chi}_{\chi_v}}_{\chi_l} \times \underbrace{\frac{1}{\sigma_y \sqrt{2\pi}}}_{\chi_l} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\hat{u} = \frac{u_r}{u_*}$$

$$\hat{\chi} = \chi u_r / Q_i$$

$$\begin{aligned}\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\ &= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) d\theta\end{aligned}$$

$$\hat{\chi}(x, 0, z) = \underbrace{\frac{\hat{u}}{\kappa \chi}_{\chi_v}}_{\chi_l} \times \underbrace{\frac{1}{\sigma_y \sqrt{2\pi}}}_{\chi_l} \exp\left(-\frac{y^2}{2\sigma_y^2}\right)$$

$$\hat{u} = \frac{u_r}{u_*}$$

$$\hat{\chi} = \chi u_r / Q_i$$

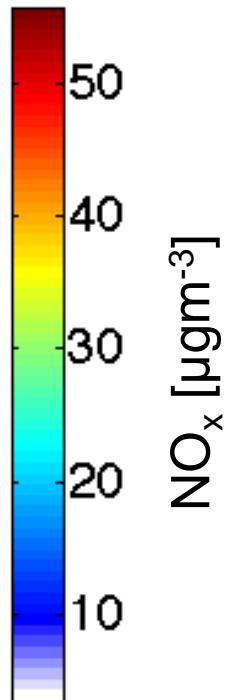
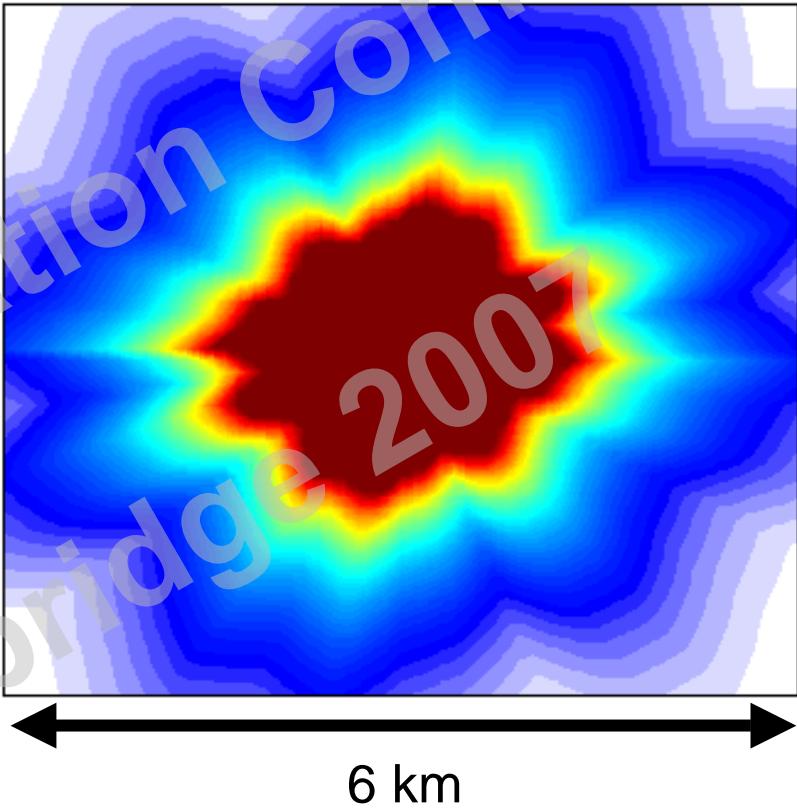
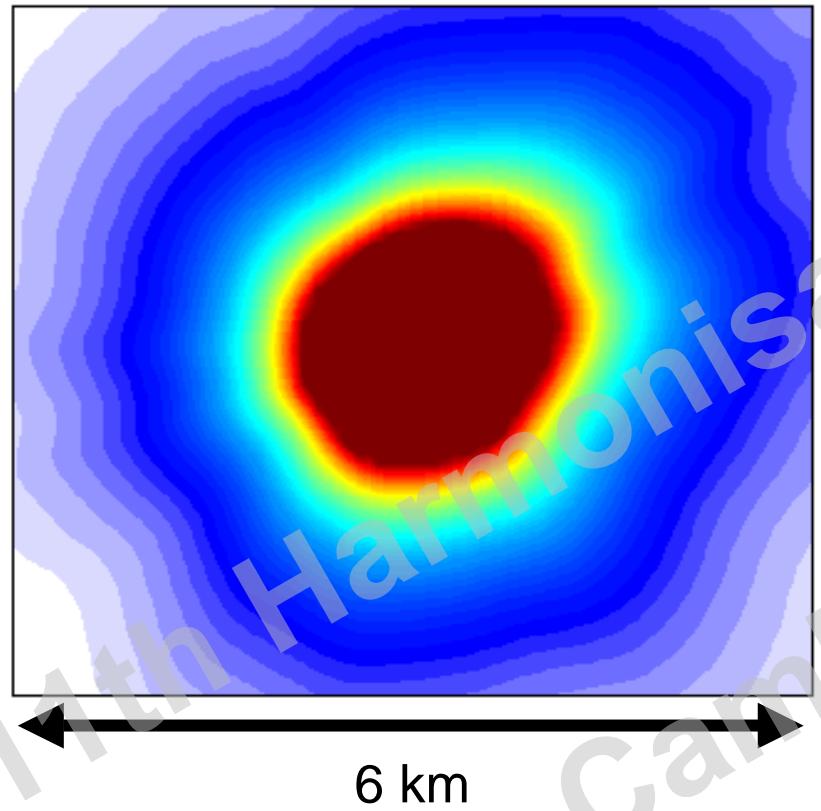
$$\begin{aligned}\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\ &= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) d\theta\end{aligned}$$

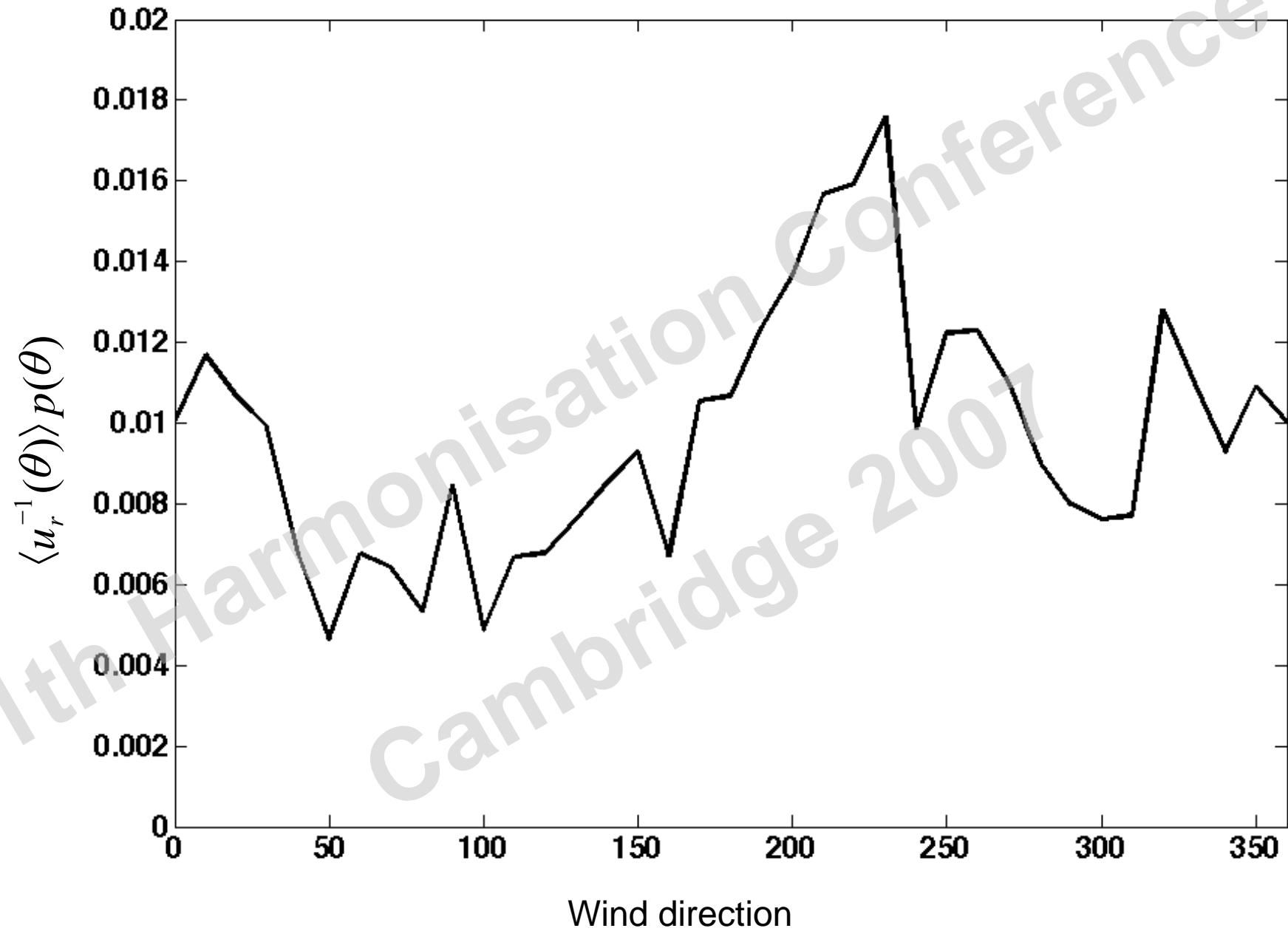
11th Harmonisation Conference
Cambridge 2007

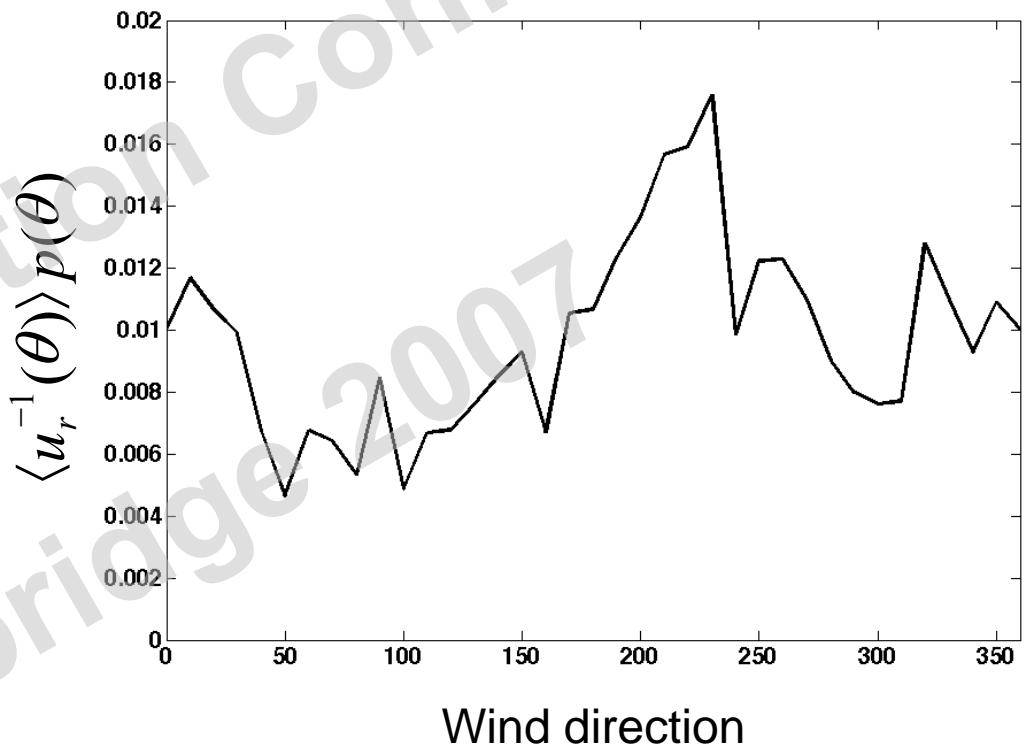
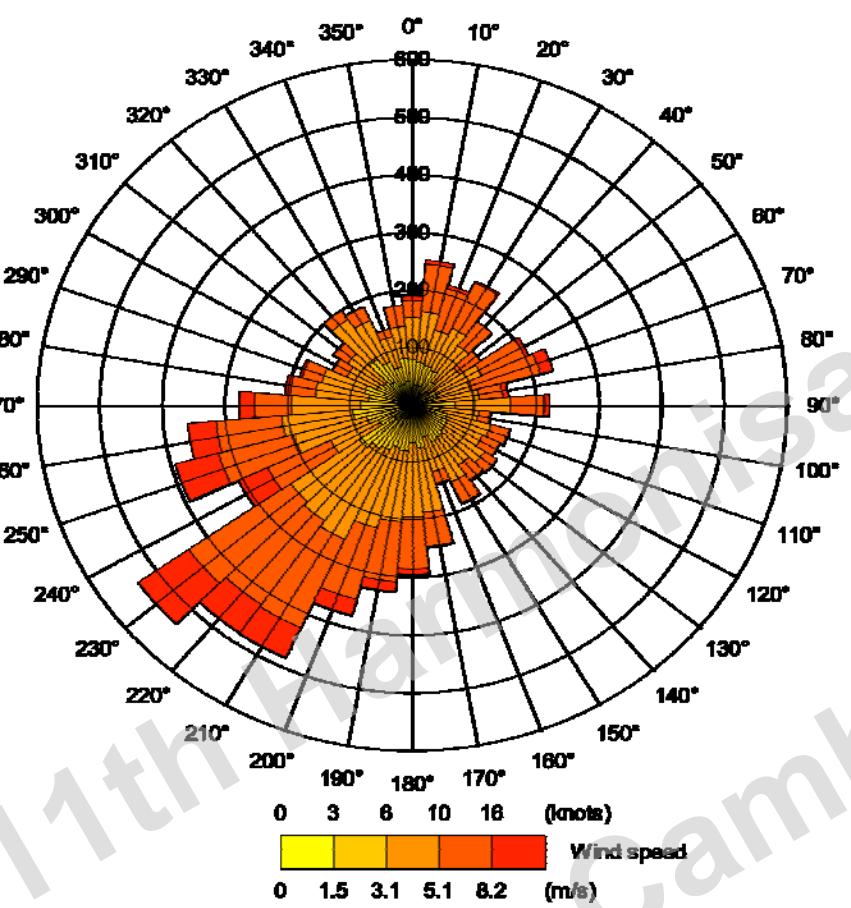
$$\begin{aligned}
\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\
&= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) d\theta \\
&= \sum_{i=1}^N Q_i \int \hat{\chi}_v(x; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) \chi_l(x, y; \theta) d\theta \\
&\quad (\hat{\chi}_v = \chi_v u_r)
\end{aligned}$$

$$\begin{aligned}
\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\
&= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) d\theta \\
&= \sum_{i=1}^N Q_i \int \hat{\chi}_v(x; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) \chi_l(x, y; \theta) d\theta \\
&\quad (\hat{\chi}_v = \chi_v u_r) \\
&\approx \sum_{i=1}^N Q_i \frac{\hat{\chi}_v(x; \theta)}{x} \langle u_r^{-1}(\theta) \rangle p(\theta) \int \chi_l(x, y; \theta) dy \\
&\quad (dy \approx x d\theta)
\end{aligned}$$

$$\begin{aligned}
\langle \chi(x, y) \rangle &= \int \int \sum_{i=1}^N \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta \\
&= \sum_{i=1}^N Q_i \int \hat{\chi}(x, y; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) d\theta \\
&= \sum_{i=1}^N Q_i \int \hat{\chi}_v(x; \theta) \langle u_r^{-1}(\theta) \rangle p(\theta) \chi_l(x, y; \theta) d\theta \\
&\quad (\hat{\chi}_v = \chi_v u_r) \\
&\approx \sum_{i=1}^N Q_i \frac{\hat{\chi}_v(x; \theta)}{x} \langle u_r^{-1}(\theta) \rangle p(\theta) \int \chi_l(x, y; \theta) dy \\
&\quad (dy \approx x d\theta) \\
&\approx \sum_{i=1}^N Q_i \frac{\hat{u}}{\kappa R_i^2} \langle u_r^{-1}(\theta) \rangle p(\theta)
\end{aligned}$$







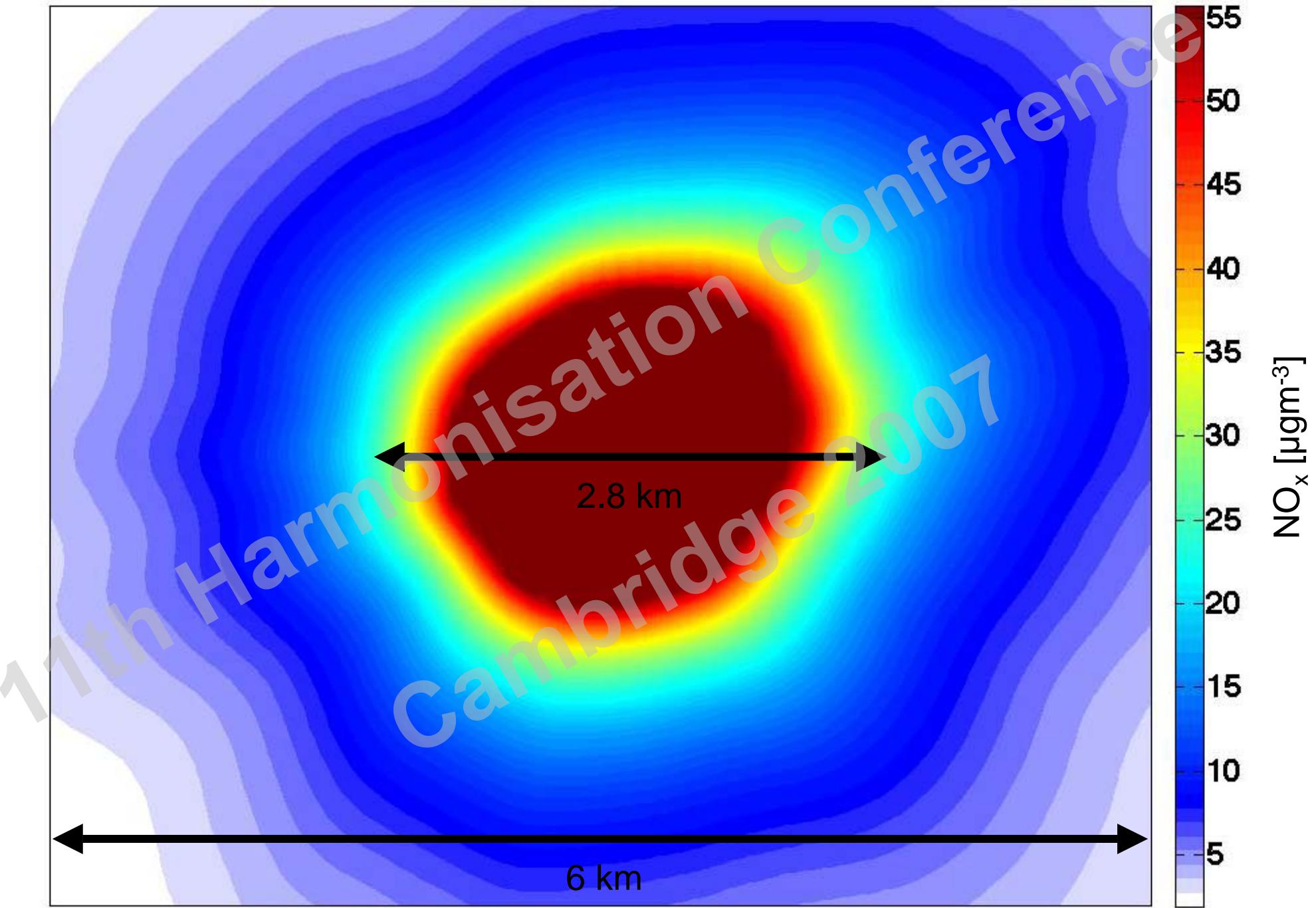
$$\langle \chi(x, y) \rangle = \iint \chi(x, y; u_r, \theta) p(\theta, u_r) du_r d\theta$$

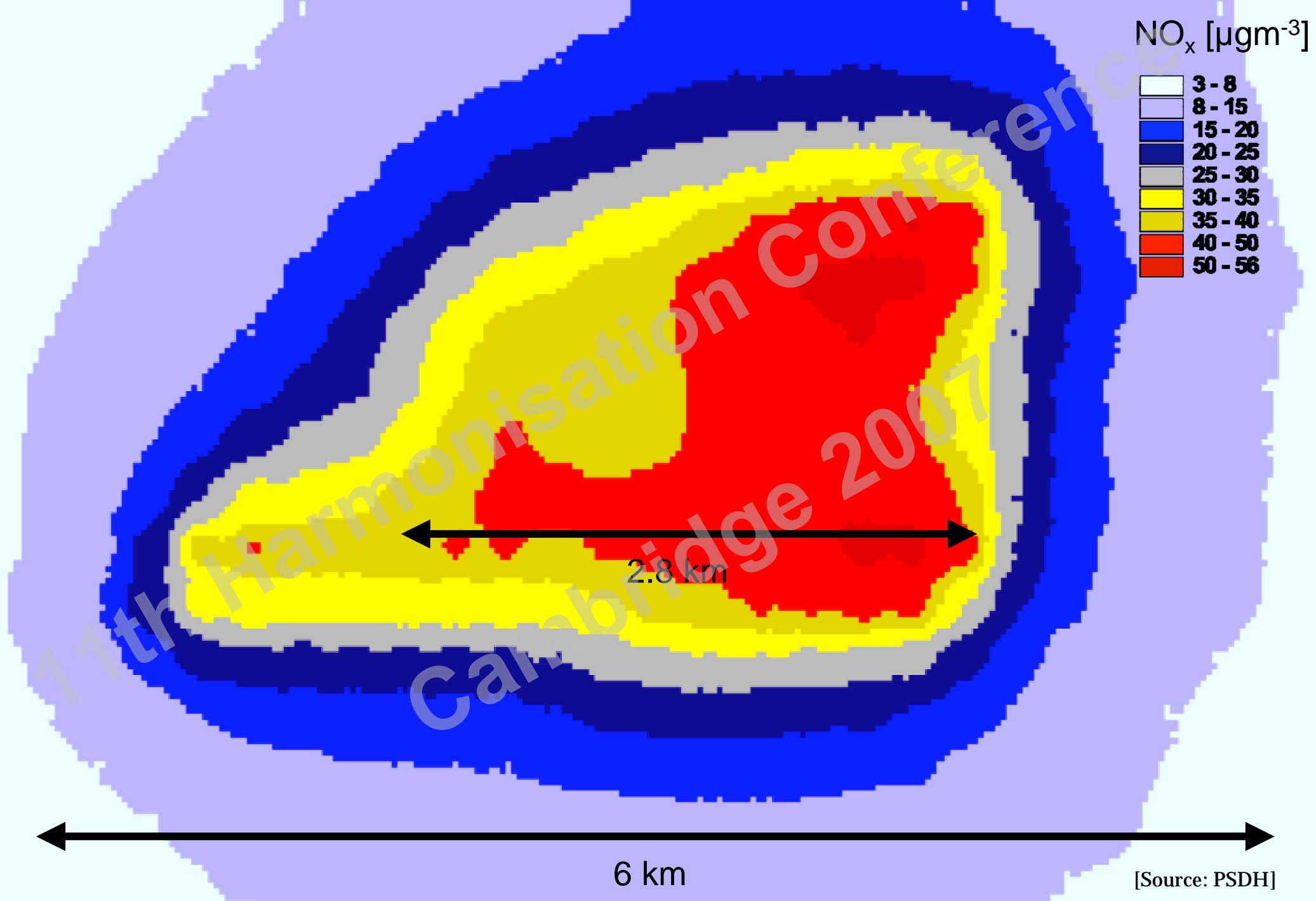
$$p(\theta) = \frac{1}{2\pi}$$

$$\langle u_r \rangle^{-1} \sim \langle u_r^{-1} \rangle$$

$$A_r^* = \frac{Q\hat{u}}{\kappa \langle u_r \rangle \chi_r}$$

$$\chi_r = 50 \mu\text{g}/\text{m}^3 \quad \Rightarrow \quad A_r^* = 6.2 \text{ km}^2$$



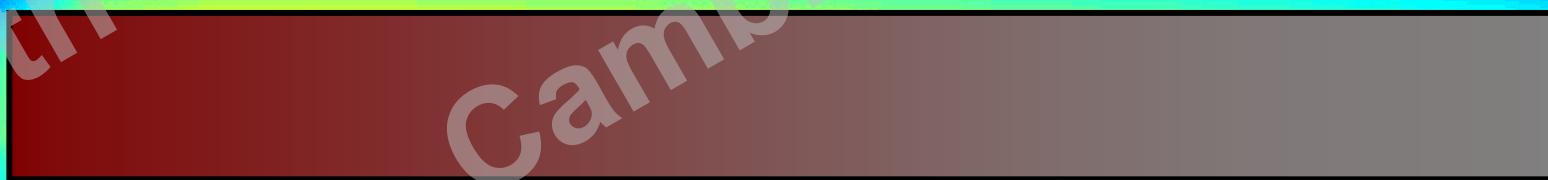
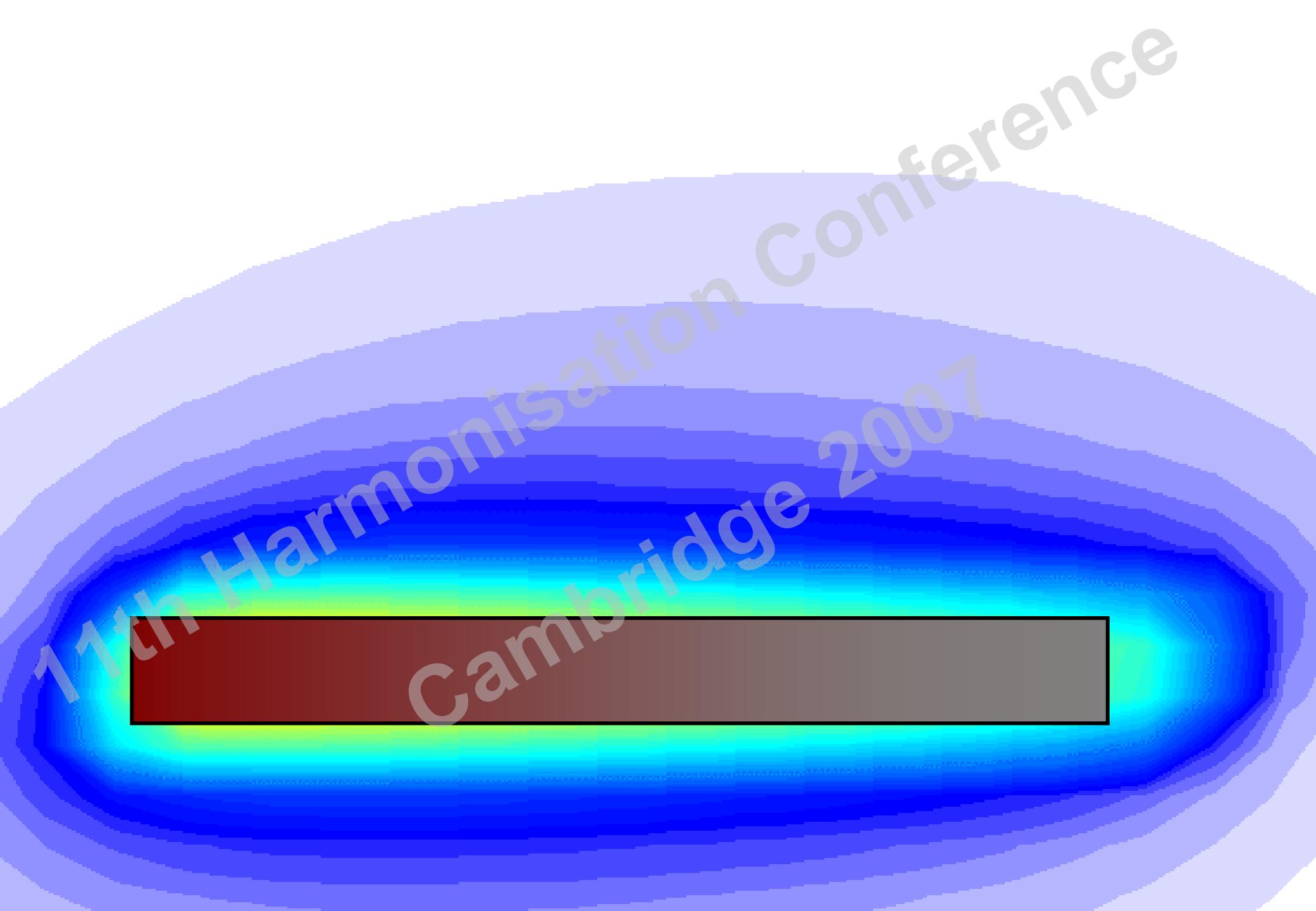


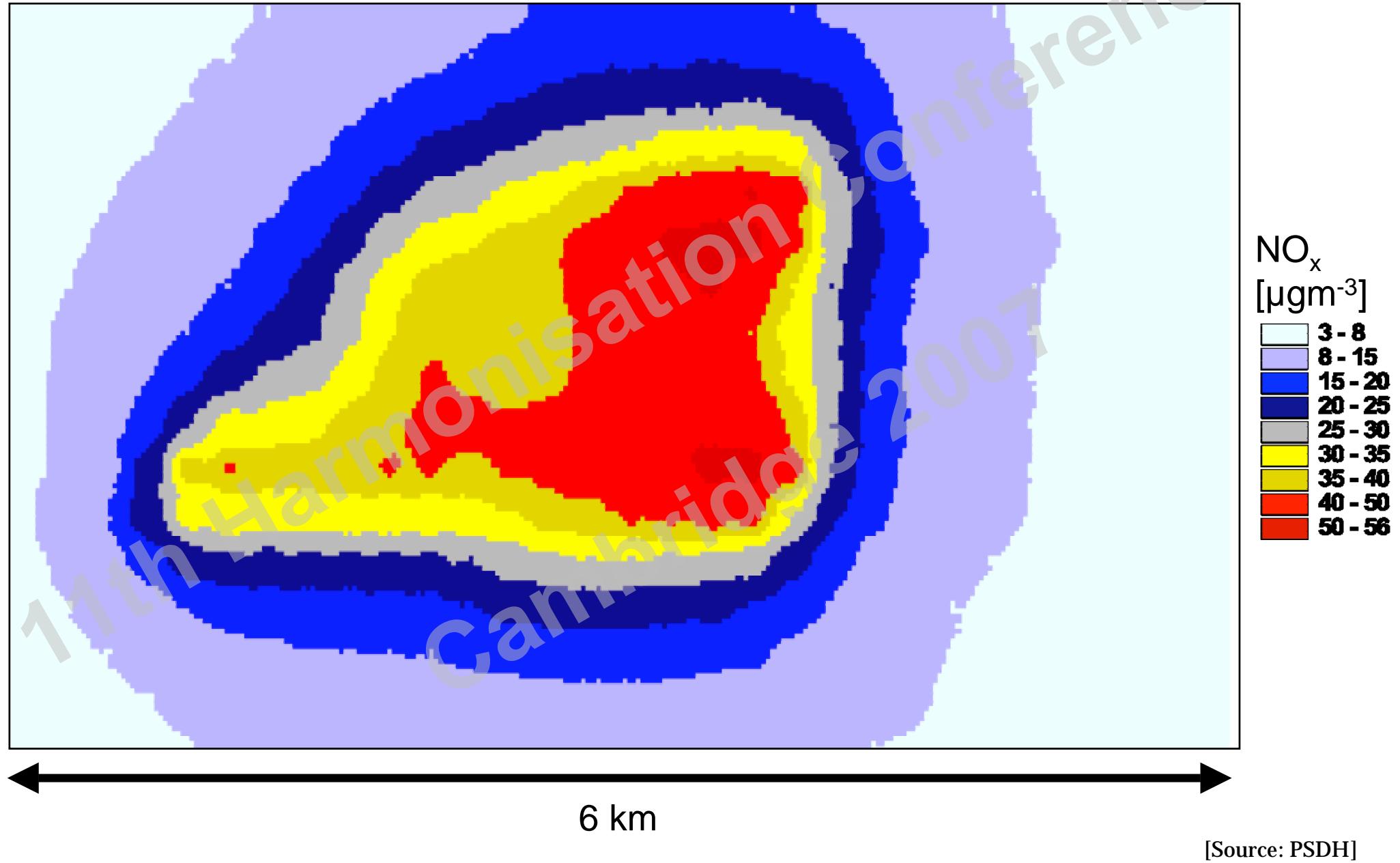


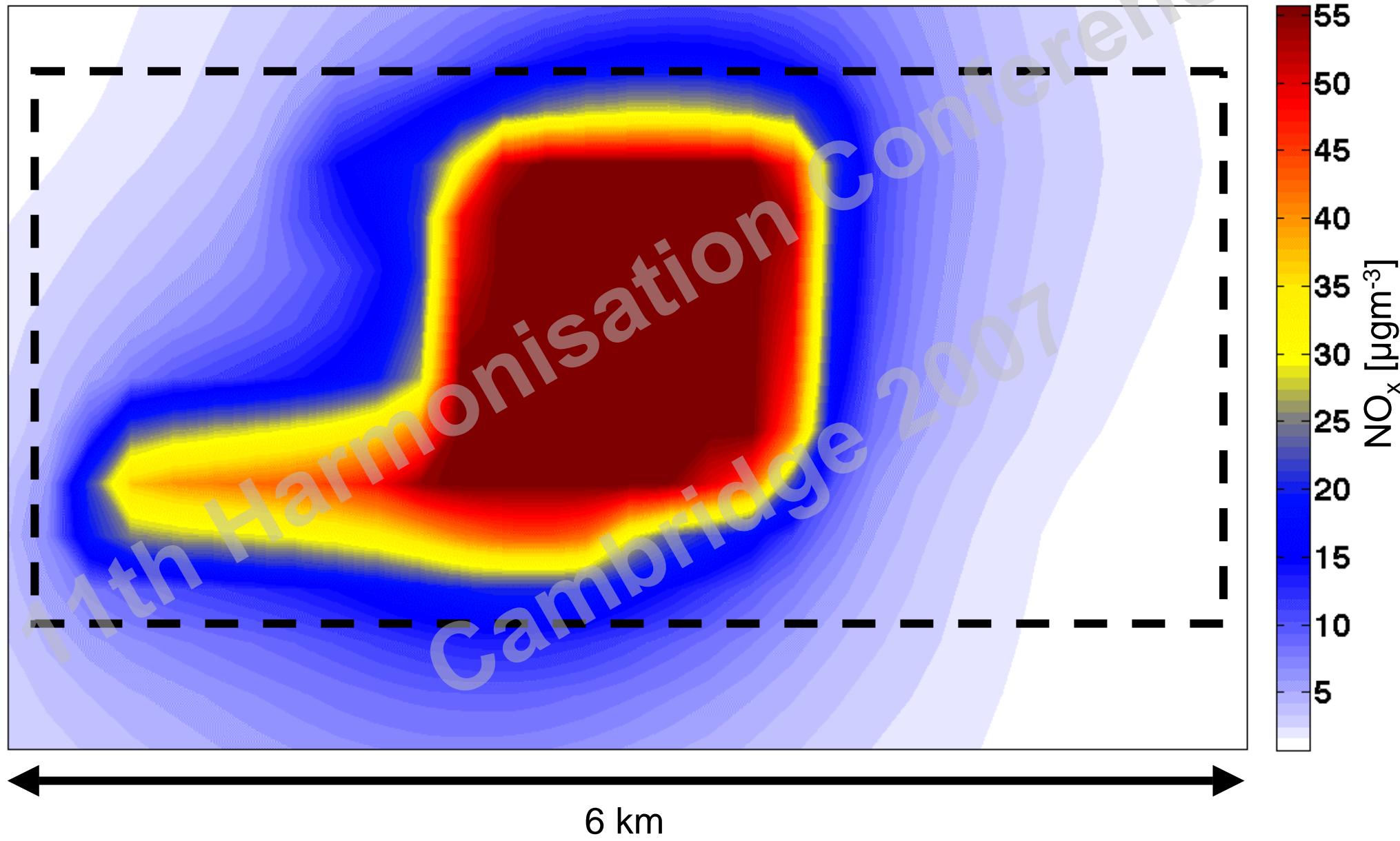
11th Harmonisation Conference
Cambridge 2016



11th Harmonisation Conference
Cambridge 2007

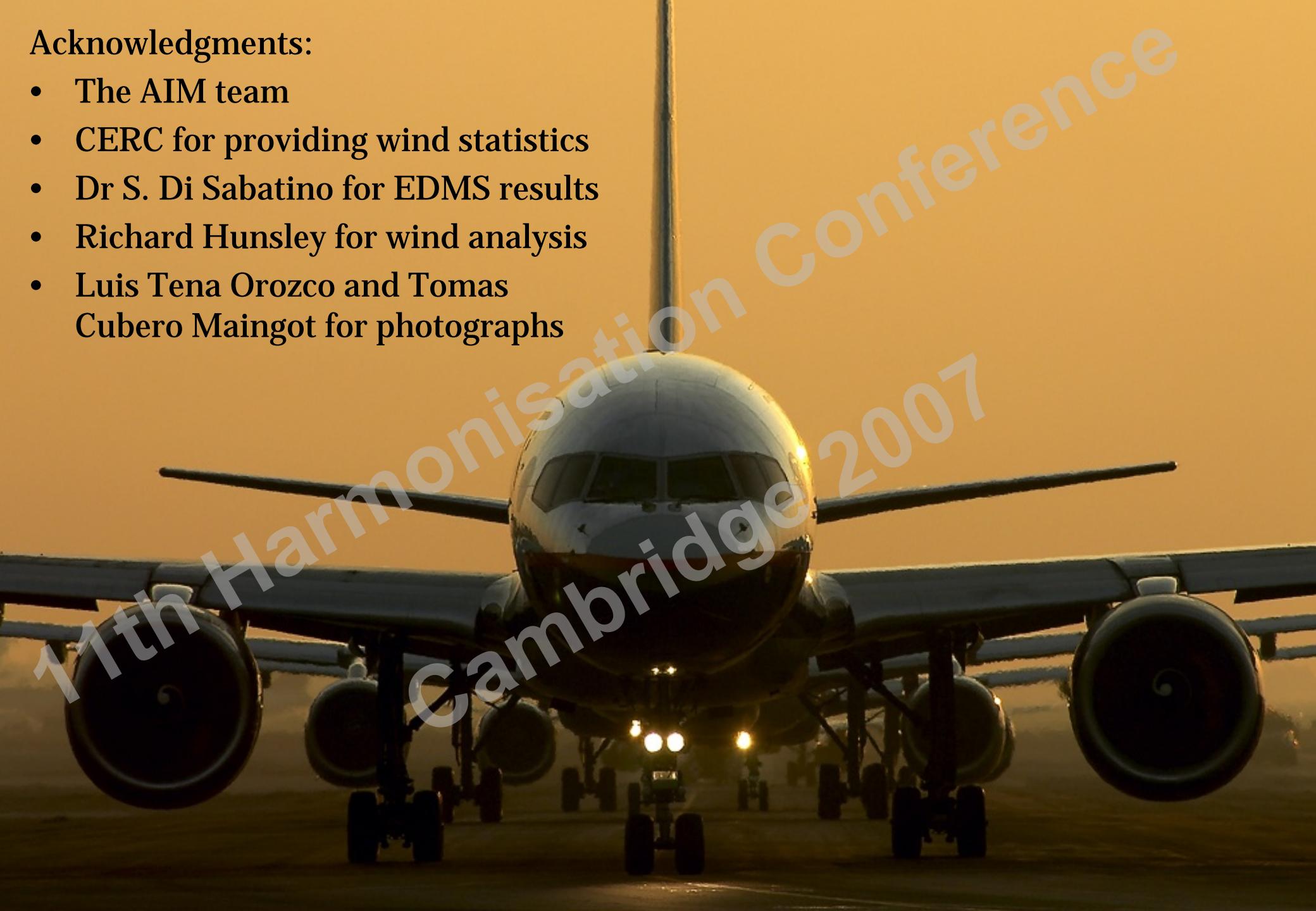






Acknowledgments:

- The AIM team
- CERC for providing wind statistics
- Dr S. Di Sabatino for EDMS results
- Richard Hunsley for wind analysis
- Luis Tena Orozco and Tomas Cubero Maingot for photographs



AVIATION INTEGRATED MODELLING PROJECT

www.AIMPROJECT.AERO



Overview of assumptions and restrictions

Assumption/Restriction	Rationale
Emissions represented as ground level sources, neglect influence of emissions at altitude	As a baseline we neglect all above-ground emissions to reduce user burden in the context of a simple screening model, <i>Wayson and Fleming</i> (2000) results show impact of emissions at altitude
Buoyancy, trailing vortices, downwash, jet momentum neglected	Interpretation of CERC study for PSDH indicates this will be acceptable for a screening model, reduced user burden
Dispersion considered for conserved scalars only	Appropriate for PM over time scales of interest, NO _x chemistry can be applied empirically (e.g. <i>Jenkin</i> , 2004)
Single roughness length	Reduced user burden, average concentrations would have ~15% error if z_0 had a factor of two error, <i>Hanna and Britter</i> (2002)
Very low wind conditions neglected	Use of minimum wind speed
Neutral conditions assumed	Assumed for simplicity and reduced user burden, acceptable given typically $ L ^{-1} \sim 0.01 \text{ m}^{-1}$ in urban conditions, where L is the Monin-Obukhov length (see <i>Hanna and Britter</i> , 2002)
Only long-term averages can be calculated	Corresponds to most immediate regulatory constraint
Flat urban airport	Often applicable, required for other assumptions

11th Harmonisation Conference
Cambridge 2007

11th Harmonisation Conference
Cambridge 2007

