





COMPARISON OF THE ACCURACY OF K-EPSILON AND K-OMEGA SST TURBULENCE MODELS IN AN UNKNOWN SOURCE PARAMETERS ESTIMATION APPLICATION

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Aims and Objectives

Aim:

• To identify the location and the release rate of an unknown air pollutant source in an urban-like domain.

Objectives:

- To utilize two different turbulence models (k-epsilon and k-omega SST).
- To compare the accuracy of the two models in a Source Term Estimation (STE) application.
- To evaluate each model's accuracy in estimating source term.
- To utilize the Mock Urban Setting Test (MUST) wind tunnel experiment dataset.

Methodology

Wind field calculation – CFD forward simulation

Adjoint advection – diffusion equations resolving – CFD backward simulations

Source Receptors Functions (SRF) storing

Calculation – minimization of the cost function

Source location – release rate estimation

Wind field simulations

Forward simulation

- Steady-state
- Reynolds Averaged Navier Stokes (RANS) approach
- Two different turbulence models
 - k-epsilon
 - k-omega SST
- simpleFoam solver

Inlet boundary conditions • $u(z) = \frac{u^*}{\kappa} ln\left(\frac{z-z_0}{z_0}\right)$ • $k = \frac{(u^*)^2}{\sqrt{C_{\mu}}}$ • $epsilon = \frac{(u^*)^3}{\kappa(z+z_0)}$ • $omega = \frac{(u^*)^3}{\kappa(z+z_0)\sqrt{C_{\mu}}}$

Implementation: OpenFOAM CFD tool

Backward simulations

- Steady-state
- Modified ScalarTransportFoam solver
- Wind field of forward simulation is used reversed
- Calculation of the adjoint concentrations c_n^* :
 - Adjoint advection-diffusion equation (Marchuk, 1982; 1996)

$$\frac{\partial c_n^*}{\partial t} - u_i \frac{\partial c_n^*}{\partial x_i} - \frac{\partial}{\partial x_i} \left(Dc + \frac{v_t}{Sc_t} \right) \frac{\partial c_n^*}{\partial x_i} = p_n$$

• Number of simulations = Number of sensors

Implementation: OpenFOAM CFD tool

Source term estimation

Estimation of location and release rate --> Two step methodology (Efthimiou et al., 2017)

• Cost function for location estimation:

$$J = -\frac{\langle (c^c - \langle c^c \rangle)(c^o - \langle c^o \rangle) \rangle}{\sqrt{\langle (c^c - \langle c^c \rangle)^2 \rangle} \sqrt{\langle (c^o - \langle c^o \rangle)^2 \rangle}}$$

- Where c^c is concentration calculated by SRF: $c^c = q_s c^*$
- Release rate calculation equation:

$$q_{s} = \frac{\sum_{n=1}^{K} c_{n,k^{s}}^{*} c_{n}^{o}}{\sum_{n=1}^{K} (c_{n,k^{s}}^{*})^{2}}$$

Evaluation of the SRF

Solve forward dispersion problem with true source location and release rate

Calculate SRF based on adjoint concentrations at the true source location

The SRF calculated concentrations are compared with the forward concentrations at sensors

Scatter plot

Validation metrics

Evaluate the SRF

Validation Metrics (Schatzmann et al., 2010)

- Hit rate HR
- Factor of two observations FAC2
- Fractional bias FB
- Geometric mean bias MG
- Normalised mean square error NMSE
- Geometric variance VG
- Mean absolute error MAE

Case study - Mesh

• Geometry

- MUST wind tunnel experiment
- ≻120 shipping containers
- ▶45 degrees wind direction
 ▶(X, Y, Z): (340m, 300m, 21

≻248 sensors

m)



Figure 1: Computational domain in x - y level



• <u>Mesh</u>

Unstructured - Tetrahedral1.024.119 cells



Figure 3: Computational mesh in x – y level

Figure 2: Computational domain's buildings view

Results of wind field



Figure 4: Selected points for comparison of wind tunnel and calculated values of the three velocity components



Figure 5: Comparison of vertical values of the three velocity components of k-epsilon and k-omega SST forward simulations and wind tunnel measurements in four points

Evaluation of forward dispersion model



Figure 6: Scatter plot of the forward and the measured concentrations calculated by the k-epsilon model



Figure 7`: Scatter plot of the forward and the measured concentrations calculated by the k-omega SST model 30/09/2022

Validation metrics	k-epsilon	k-omega SST	Ideal model
HIT RATE	0.516	0.621	1
FAC2	0.641	0.750	1
FB	0.106	-0.037	0
MG	1.373	1.196	1
NMSE	1.557	1.443	0
VG	1.423	1.244	1
MAE	0.654	0.476	0

 Table 1: Validation metrics factors for the forward and the measured concentrations comparison
 Image: Concentration of the second s

Evaluation of the SRF



Figure 8: Scatter plot of the forward and the SRF concentrations calculated by the k-epsilon model



Figure 9: Scatter plot of the forward and the SRF concentrations calculated by the k-omega SST model 30/09/2022

Validation metrics	k-epsilon	k-omega SST	Ideal model
HIT RATE	0.948	1	1
FAC2	0.988	1	1
FB	-0.075	-0.007	0
MG	0.991	1.001	1
NMSE	0.370	0.026	0
VG	1.021	1	1
MAE	0.153	0.033	0

Table 2: Validation metrics factors for the forward and the SRF concentrations comparison

Results – evaluation of source parameters estimation

Case	Location – Domain coordinates			Release rate
	<i>X</i> (m)	<i>Y</i> (m)	<i>Z</i> (m)	<i>q</i> (kg/s)
True source	-102.48	-7.06	0.00	1.35·10 ⁻⁵
Estimated k- epsilon	-97.22	-12.03	3.20	0.94·10 ⁻⁵
Estimated k- omega SST	-102.28	-7.39	1.22	0.72·10 ⁻⁵
Divergence k- epsilon	5.26	4.97	3.20	0.41·10 ⁻⁵
Divergence k- omega SST	0.20	0.33	1.22	0.63·10 ⁻⁵

Evaluation criteria (Kovalets et al., 2011) $PR_H = \sqrt{(x_e - x_t)^2 + (y_e - y_t)^2} \le 15 m$ $PR_V = |z_e - z_t| \le 1.5 m$ $PAq = \max[(q_e/q_t), (q_t/q_e)] \le 4$

Case	<i>R_H</i> (m)	<i>R_V</i> (m)	Δq
k-epsilon	7.24	3.20	1.44
k-omega SST	0.39	1.22	1.88

Table 4: Horizontal and vertical distances and release rate ratio results

Table 3: Source parameters estimation results

Conclusions - Future work (1/3)

- Both models provided accurate solutions in the location estimation at the horizontal level and release rate
- k-epsilon failed to achieve the criteria in the vertical distance
- k-omega SST estimated the source location very accurately
- k-epsilon calculated more accurately the release rate
- k-omega SST had higher achievement in the calculation of the forward dispersion model
- The SRF were solved more correctly by k-omega SST

Conclusions - Future work (2/3)

- A sensitivity analysis for the number of sensors is under investigation
- The methodology will be tested in transient conditions (unsteady RANS, Large Eddy Simulation)
- Investigate a complex geometry case

Conclusions - Future work (3/3)

 The utilization of methodology in cases of shipping sources in harbour areas in order to detect and quantify the shipping emissions





Figure 7: Numerical simulation (CFD model) to estimate pollutant dispersion in Marseille harbour– SCIPPER project

Acknowledgements

- P. Gkirmpas acknowledges the Helmholtz Association of German Research Centers for funding the doctoral dissertation through the European program Helmholtz European Partnership for Technological Advancement (HEPTA).
- Also, he acknowledges the Graduate School of the Centre for Climate and Environment (GRACE) at the Karlsruhe Institute of Technology (KIT) for financial support.
- The authors would like to acknowledge the SCIPPER Project (project that has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 814893) for financial support.

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Thank you for your attention!