AtmoSud

SPATIAL MODEL FOR DAILY AIR QUALITY HIGH RESOLUTION ESTIMATION

Inspirer un air meilleur

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AtmoSud is the Air Quality Observatory in South Region (France) agreed by the Ministry of Environment. AtmoSud missions: Monitoring network / Inventory of Emissions / Modelling / Forecasting

lodel fitting

Daily maps are computed from annual map by temporaly

2 AZUR is a modelling platform that creates daily HD concentration cartography for pollutants like PM10, PM2.5 and NO₂ on millions grid cells in short time computing compared to deterministic model. It produces cartography until day+2 at 25m of resolution, considering the punctual measurements and forecasts. The input data of this platform are:

annual concentration maps coming from ADMS-Urban model (Seaton et al. 2022) mix with geostatistical method

downscaling Annual map -> Daily map (Gressent et al. 2020). The statistical model describes the relationship between:

- daily ratio concentration (response variable)
- annual ratio concentration (predictor variable) from all pair of stations. This relationship depend on the value range of daily concentration represented by quantile rank.



Fig 1: Relationship between ratio for different quantile ranks

Model results

Leave one out cross validation on all stations in Sud Region (France), year 2019 (365 days).

punctual measurement and forecast simulated by the Eurlerian Chemistry Transport model CHIMERE (Menut et al., 2021).

Model use

The daily value $\hat{q}_{s_i}(s_0)$ of grid cell — are calculated with:

- Daily value of our station \uparrow as $q_p(s_i)$
- Annual ratio value between station and grid cell as **AR** •
- Quantile rank of daily value of our station as p





Fig 4 a: observation vs. model for PM10 daily mean on 23 stations, rmse=4.6, R2=0.78. b,c: exemples for traffic station and background station

High resolution Air Quality Mapping 6



Polynomial model with $\beta_{i,k}$ coefficients

$$\widehat{q}_{s_i}(s_0) = q_p(s_i) \sum_{j+k < n} \beta_{j,k} (AR)^j p^k$$

The model has interpolator property while being exact at the measurement points

Final estimation is given by inverse distance weighted mean with all stations s_i

$$\widehat{q}(s_0) = \sum_{i \in V_{s_0}} \lambda_i \widehat{q}_{s_i}(s_0) \text{ with } \sum_{i \in V_{s_0}} \lambda_i = 1$$



Fig 5 a,b: Air index map resulting from pollutant maps (25 x 25 meters, 10 000 x 10 000 grid cells), regional map (left), urban zoom (right)

References

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