

Reconstructing the Height of an Unknown Point Release in Low Wind Stable Conditions

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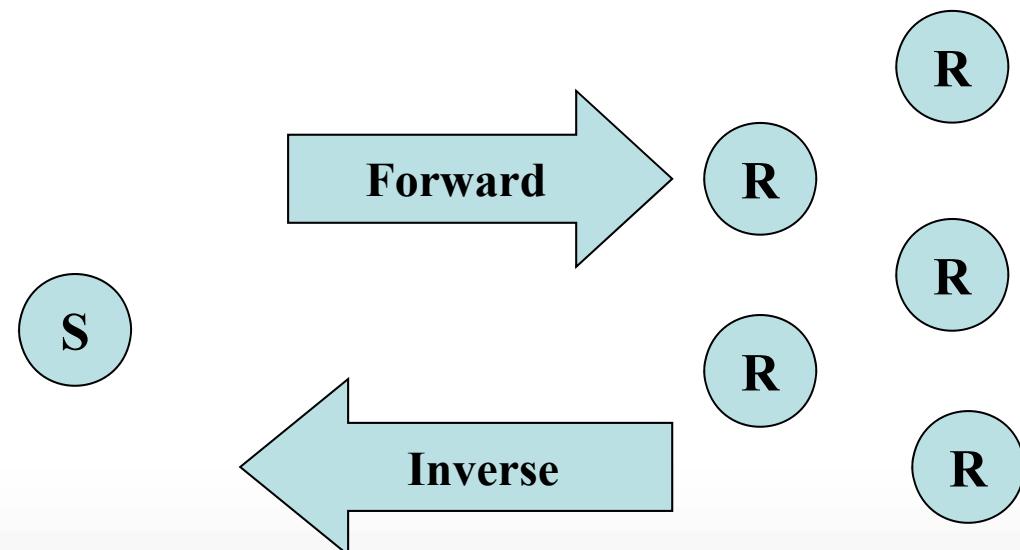
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Source Reconstruction

- Concentration measured/predicted is a function of source characteristics.

$$\mu(x,t) = F(\sigma).$$

S – Source and R- Receptor



Why Low-wind Stable conditions?

- ➡ Pollutant dispersion is subjected to the frequent meandering and large wind variability
- ➡ The diffusion of pollutant is irregular and indefinite.
- ➡ Observed concentration distribution is multi-peaked and non-Gaussian.
- ➡ Pollutants do not travel far from source.

Why elevated release?

In stable conditions, concentration measurements are sensitive to...

- Height of release.
- Height of receptors.

This affects the model representativity and retrieval accuracy.

Parametric Estimation Problem

- Four unknown parameters:
 - Location(x_0, y_0, z_0)
 - Emission Rate (q)

Renormalization Inversion Technique

- The correspondence between emission function $s(x,y,z)$ and measurement μ_i is,

$$\mu_i(x, y, z_r) = \int_{\Sigma} s(x, y, z) a_i(x, y, z) dx dy dz = (s, a_i)$$

$$s(x, y, z) = q \delta(x - x_0) \delta(y - y_0) \delta(z - z_0)$$

Derivation of Retro-plumes

- The forward transport equation for a continuous release of a non-reactive tracer is

$$\mathbf{u} \cdot \nabla \chi = \frac{1}{\rho} \nabla (\rho \mathbf{K} \cdot \nabla \chi) + \sigma$$

$$\sigma(x, y, z) = \frac{s(x, y, z)}{\rho}$$

- The backward transport equation

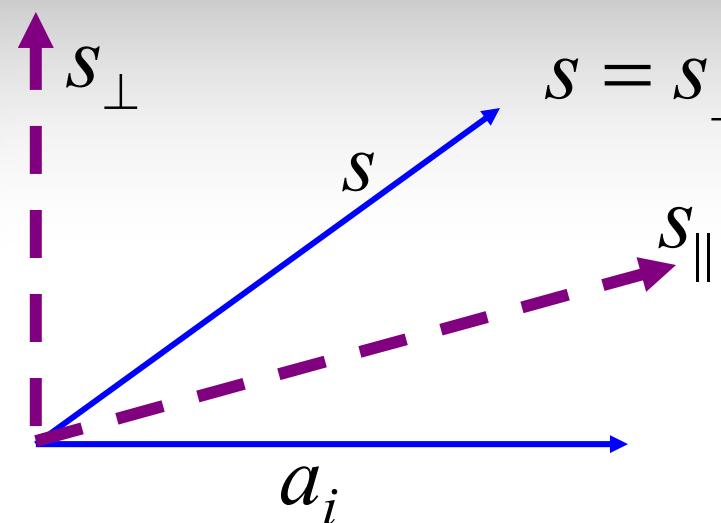
$$\text{is } -\mathbf{u} \cdot \nabla r_i = \frac{1}{\rho} \nabla (\rho \mathbf{K} \cdot \nabla r_i) + \pi_i$$

$$\mu_i = (\chi, \pi_i) = (L(\sigma), \pi_i) = (\sigma, L^*(\pi_i)) = (\sigma, r_i)$$

$$\mu_i = \int_{\Sigma} \rho \chi \pi_i dx dy dz = \int_{\Sigma} \rho \sigma r_i dx dy dz$$

$$a_i(x, y, z) = r_i(x, y, z)$$

Classical Identification Theory



$$S = S_{\perp} + S_{\parallel}$$

$$(s, a_i) = \mu_i$$

$$s_{\parallel}(\mathbf{x}) = \sum_{i=1}^n \lambda_i a_i(\mathbf{x})$$

$$\mathbf{H} = [(a_i, a_j)] \quad \text{and} \quad \boldsymbol{\lambda} = \mathbf{H}^{-1} \boldsymbol{\mu}$$

Distributed Emissions



$$S_{\parallel} = \boldsymbol{\mu}^T \mathbf{H}^{-1} \mathbf{a}$$

Associated with singularities in case of point measurements

Renormalization Theory

$$(s, a_i)_\varphi = \int_S \frac{a_i}{\varphi} \varphi d\mathbf{x} = \int_S a_{\varphi i} \circ \varphi d\mathbf{x}$$

in which $a_{\varphi i}(\mathbf{x}) = \frac{a_i(\mathbf{x})}{\varphi(\mathbf{x})}$

Renormalize
weight
function

= Renormalize adjoint
function

Optimality Criterion

$$\varphi(x, y, z) \geq 0$$

$$\int_S \varphi(x, y, z) dx dy dz = n$$

$$\mathbf{a}_\varphi(x, y, z)^T \mathbf{H}_\varphi^{-1} \mathbf{a}_\varphi(x, y, z) \equiv 1$$

$$s_{\parallel\varphi}(\mathbf{x}) = \boldsymbol{\mu}^T \mathbf{H}_\varphi^{-1} \mathbf{a}_\varphi(\mathbf{x})$$

$$\text{where } \mathbf{H}_\varphi = (a_{\varphi i}, a_{\varphi j})_\varphi$$

Point Source Retrieval

$$\mu_i = q a_i(\mathbf{x}_0) = q \varphi(\mathbf{x}_0) a_{\varphi i}(\mathbf{x}_0)$$

The source estimate is,

$$s_{\parallel\varphi}(\mathbf{x}) = q \varphi(\mathbf{x}_0) s_0(\mathbf{x}) \quad \text{where,} \quad s_0(\mathbf{x}) = \mathbf{a}_{\varphi}(\mathbf{x}_0)^T \mathbf{H}_{\varphi}^{-1} \mathbf{a}_{\varphi}(\mathbf{x})$$

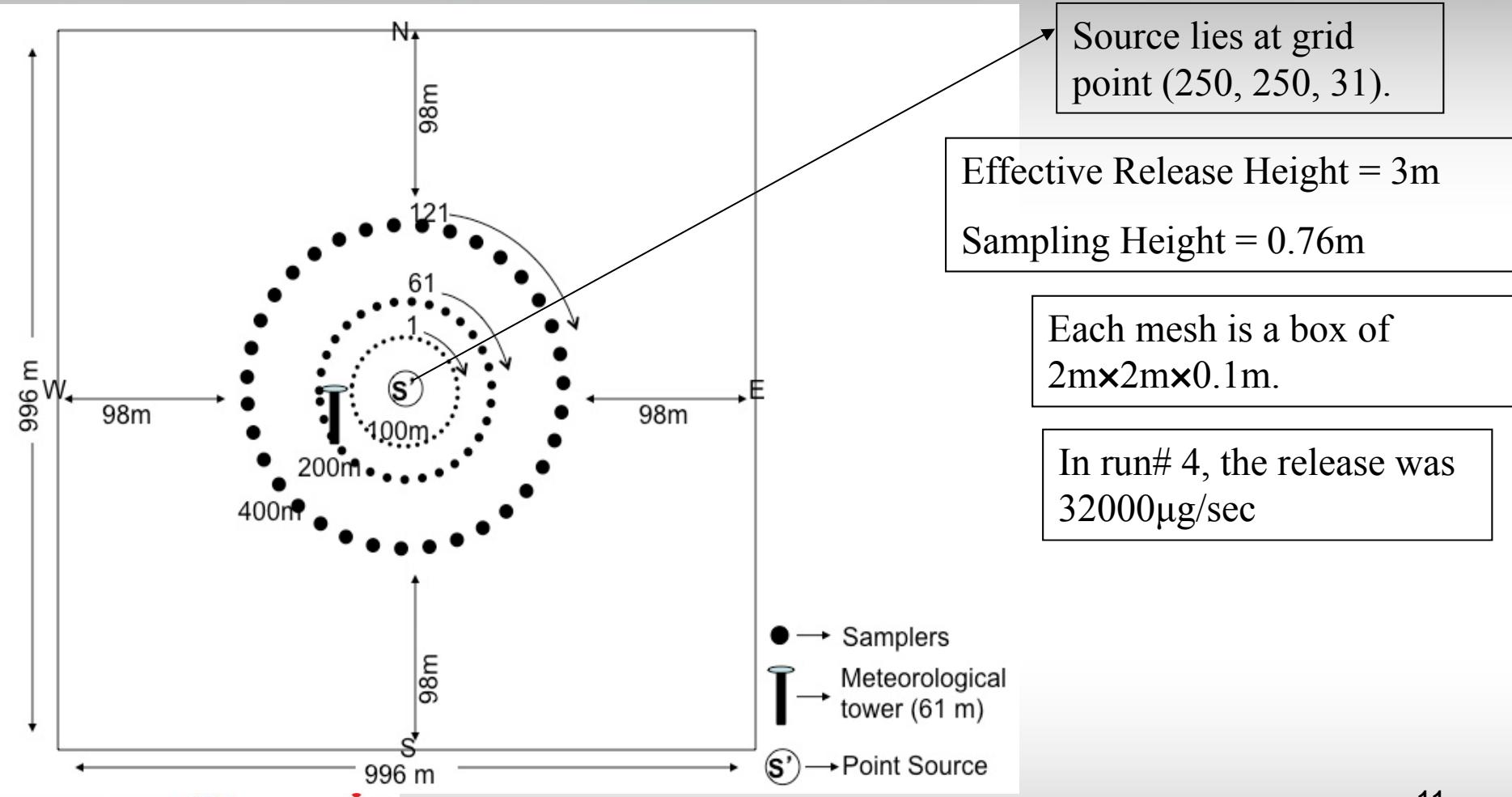
Using cauchy-schwarz inequality, $|s_0(\mathbf{x})| \leq 1$

Maximum of the $s_{\parallel\varphi}$ coincides with the point source **location**.

Now, **intensity** can be computed as,

$$\hat{q} = \frac{s_{\parallel\varphi}(\mathbf{x}_0)}{\varphi(\mathbf{x}_0)}$$

IDaho Diffusion Experiment



Computation

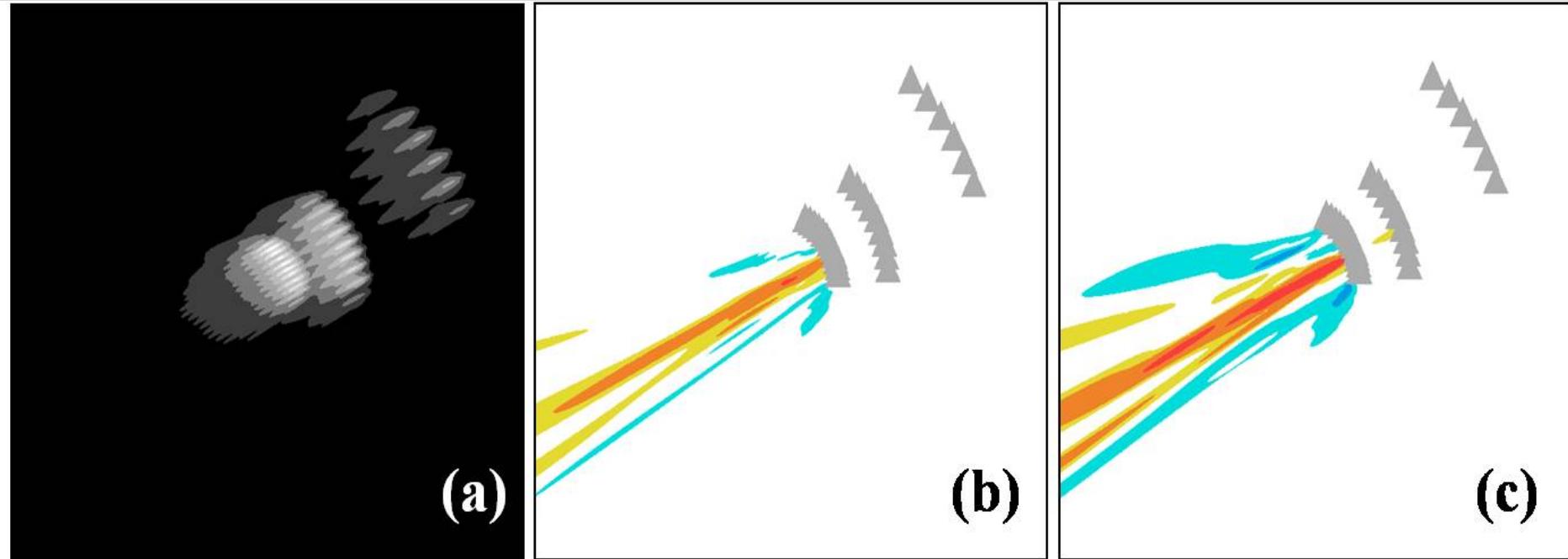
- ➔ Analytical Dispersion Model: Sharan et al.(1996)
- ➔ Dispersion parameterization:
 - ➔ In horizontal direction : Luhar (2011)
 - ➔ In vertical direction : Briggs (1973)
- ➔ Plume is segmented in to 30 sub-intervals

Evaluation

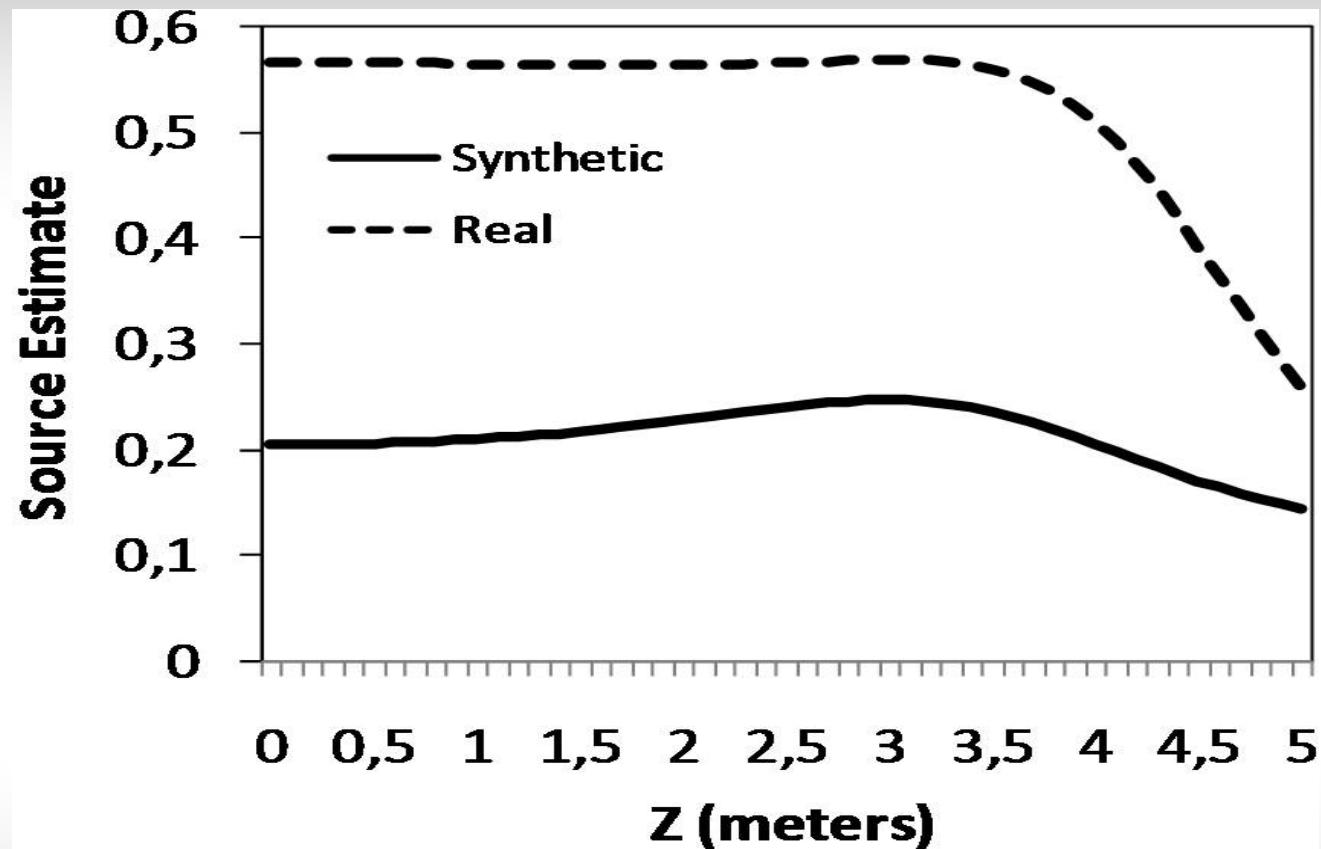
- ➔ Synthetic data
- ➔ Real data

| | Release Parameters | | | $s_{\parallel\varphi}$ | | φ at ($\times 10^{-6}$) | |
|---------------------------------------|--------------------|-----|-------|------------------------|------|-----------------------------------|------|
| | (x_0, y_0, z_0) | h | q | Real | Est. | Real | Est. |
| Experimental | (250, 250, 31) | 3 | 32000 | - | - | - | - |
| Reconstruction with Synthetic data | (250, 250, 31) | 3 | 32000 | 1.02 | 1.02 | 31.9 | 31.9 |
| Reconstruction with Real data | (253, 254, 31) | 3 | 39156 | 1.36 | 1.42 | 31.9 | 36.3 |

Figures



Continued...



Conclusions

- Propose a new method of source retrieval.
- Free from any prior information regarding release or its background state.
- Singularities due to point measurements can be dealt in a natural manner.
- Utilize the information from geometry of the monitoring network.
- With Idaho data, the Release is identified within a distance of 10m with 22% over-estimation of emission rate.

Thanks for your Kind Attention

Articles

- ▶ Issartel, J.-P., M. Sharan and M. Modani, 2007: An inversion technique to retrieve the source of a tracer with an application to synthetic satellite measurements. *Proc. Roy. Soc. A*, **463**, 2863-2886.
- ▶ Sagendorf, J. F. and C. R. Dickson, 1974: Diffusion under low wind speed inversion conditions. *NOAA Technical Memo-ERL-ARL-52, Air Resources Laboratories, Silver Spring*.
- ▶ Sharan, M., J.-P. Issartel, S. K. Singh and P. Kumar, 2009: An inversion technique for the retrieval of single-point emissions from atmospheric concentration measurements. *Proc. Roy. Soc. A*, **465**, 2069-2088.
- ▶ Sharan, M., J.-P. Issartel and S. K. Singh, 2012: A point-source reconstruction from concentration measurements in low-wind stable conditions. *Q.J.R. Meteorol. Soc.*, **138**, 1884–1894.
- ▶ Luhar AK. 2011: Analytical puff modelling of light-wind dispersion in stable and unstable conditions. *Atmos. Environ.* **45**, 357–368.
- ▶ Singh, S.K., Sharan, M. and Issartel, J.P.: (2013), ‘Inverse Modelling for Identification of Multiple-Point Releases from Atmospheric Concentration Measurements’. *Boundary-Layer Meteorol.*, **146**, 277-295.

Invitation to Workshop

Atmospheric Modeling

"Dispersion, Source Identification, Air Quality"

Organized at

LMEE, University d'Evry, Evry (near Paris), France

On

Monday, 10th June 2013 (9:30 -16:30)

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